



CS 380 - GPU and GPGPU Programming

Lecture 4: GPU Architecture, Pt. 2

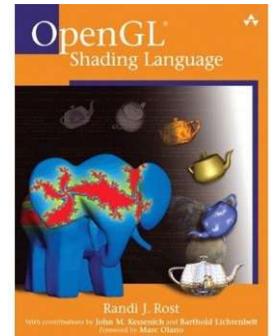
Markus Hadwiger, KAUST

Reading Assignment #2 (until Sep 9)



Read (required):

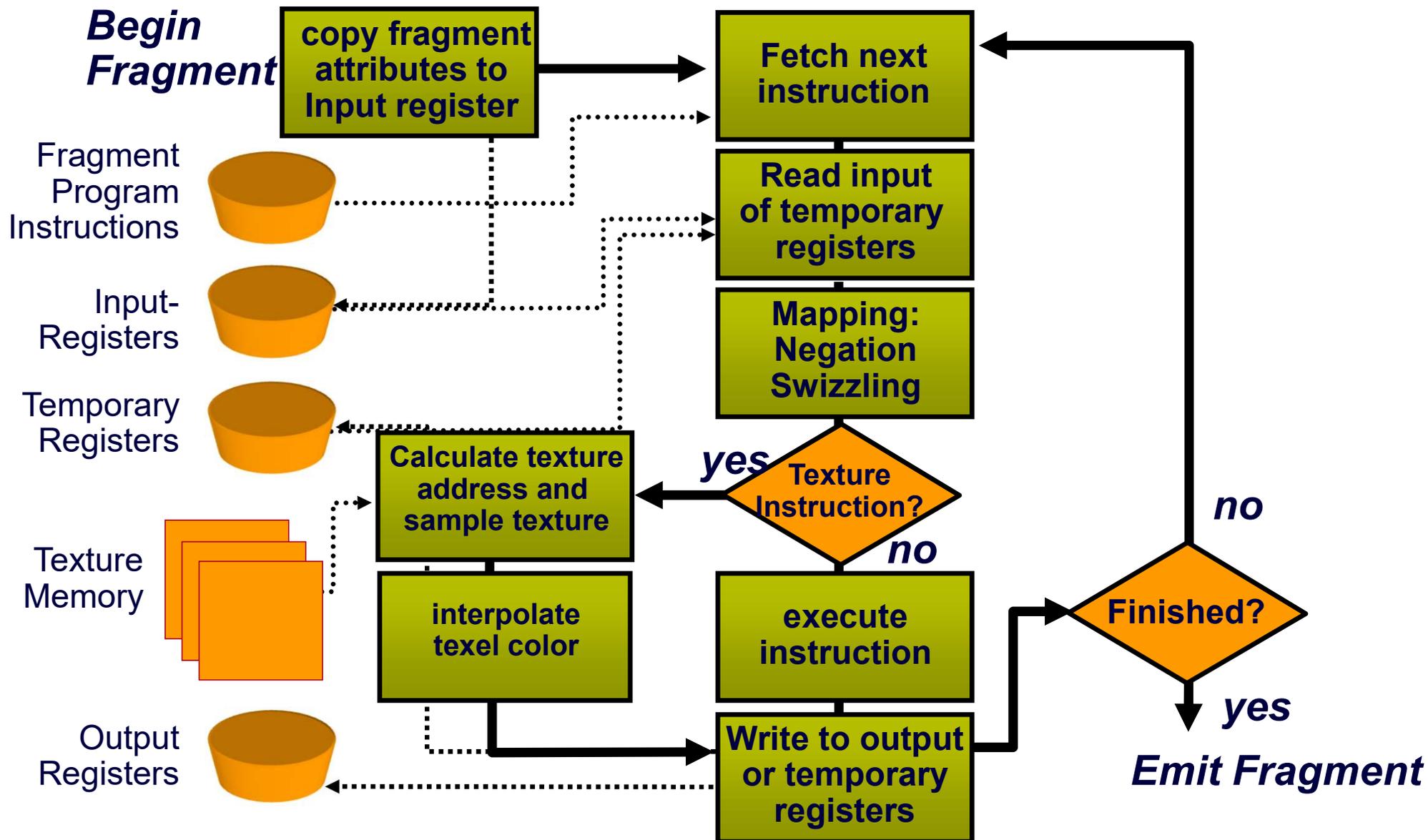
- Orange book (GLSL), Chapter 4
(*The OpenGL Programmable Pipeline*)
- Nice brief overviews of GLSL and legacy assembly shading language
https://en.wikipedia.org/wiki/OpenGL_Shading_Language
https://en.wikipedia.org/wiki/ARB_assembly_language
- Read:
https://en.wikipedia.org/wiki/Instruction_pipelining
https://en.wikipedia.org/wiki/Classic_RISC_pipeline
- Get an overview of NVIDIA Hopper (H100) Tensor Core GPU white paper:
<https://resources.nvidia.com/en-us-tensor-core>



Read (optional):

- GPU Gems 2 book, Chapter 30
(*The GeForce 6 Series GPU Architecture*)
http://download.nvidia.com/developer/GPU_Gems_2/GPU_Gems2_ch30.pdf

Fragment Processor



A diffuse reflectance shader

```
sampler mySamp;
Texture2D<float3> myTex;
float3 lightDir;

float4 diffuseShader(float3 norm, float2 uv)
{
    float3 kd;
    kd = myTex.Sample(mySamp, uv);
    kd *= clamp( dot(lightDir, norm), 0.0, 1.0);
    return float4(kd, 1.0);
}
```

Independent, but no explicit parallelism

Compile shader

1 unshaded fragment input record



```
sampler mySamp;  
Texture2D<float3> myTex;  
float3 lightDir;  
  
float4 diffuseShader(float3 norm, float2 uv)  
{  
    float3 kd;  
    kd = myTex.Sample(mySamp, uv);  
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}
```



```
<diffuseShader>:  
sample r0, v4, t0, s0  
mul r3, v0, cb0[0]  
madd r3, v1, cb0[1], r3  
madd r3, v2, cb0[2], r3  
clmp r3, r3, 1(0.0), 1(1.0)  
mul o0, r0, r3  
mul o1, r1, r3  
mul o2, r2, r3  
mov o3, 1(1.0)
```



1 shaded fragment output record



Execute shader



<diffuseShader>:

sample r0, v4, t0, s0

mul r3, v0, cb0[0]

madd r3, v1, cb0[1], r3

madd r3, v2, cb0[2], r3

clamp r3, r3, 1(0.0), 1(1.0)

mul o0, r0, r3

mul o1, r1, r3

mul o2, r2, r3

mov o3, 1(1.0)



Execute shader



```
<diffuseShader>:  
sample r0, v4, t0, s0  
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Execute shader



```
<diffuseShader>:  
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```



Execute shader



```
<diffuseShader>:  
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madd r3, v2, cb0[2], r3  
clamp r3, r3, 1(0.0), 1(1.0)  
mul o0, r0, r3  
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mul o2, r2, r3  
mov o3, 1(1.0)
```



Execute shader



```
<diffuseShader>:  
sample r0, v4, t0, s0  
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clamp r3, r3, 1(0.0), 1(1.0)  
mul o0, r0, r3  
mul o1, r1, r3  
mul o2, r2, r3  
mov o3, 1(1.0)
```



Per-Pixel(Fragment) Lighting

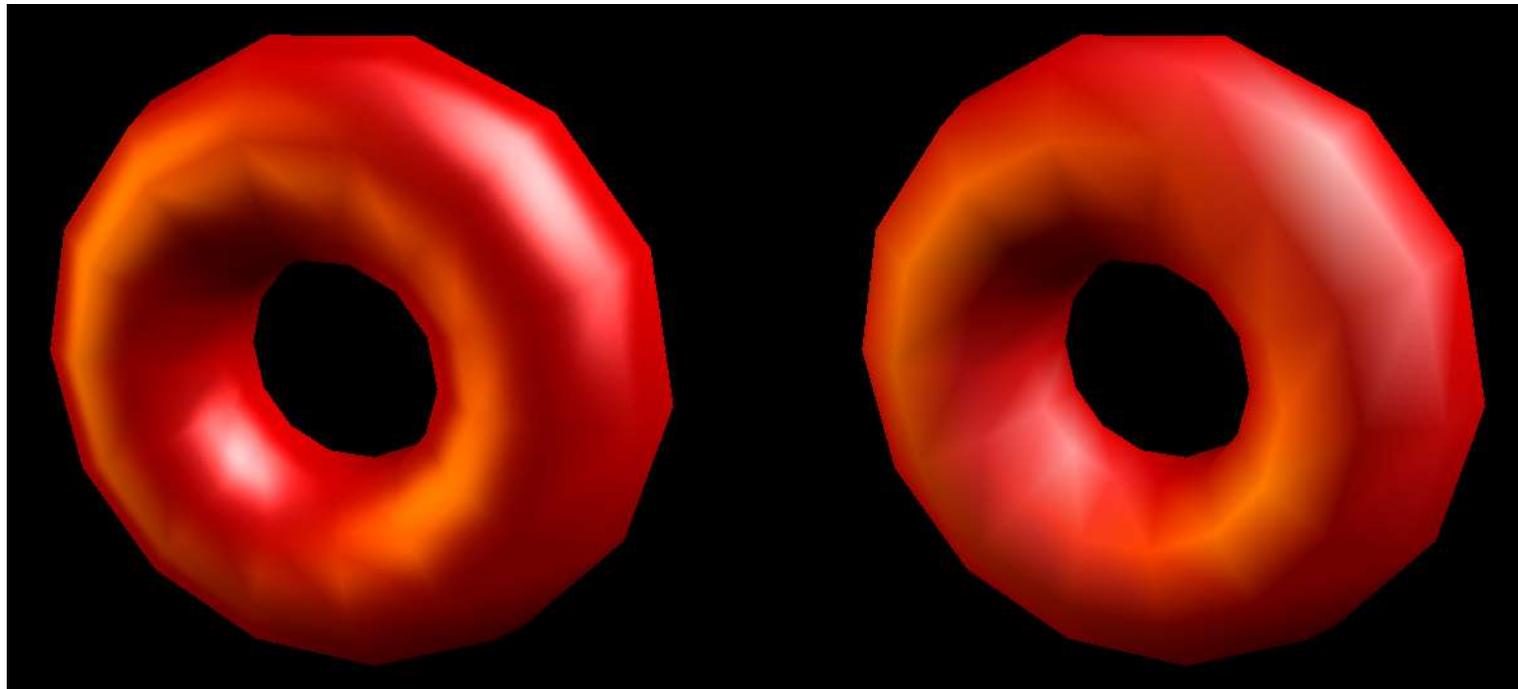


Simulating smooth surfaces by calculating illumination for each fragment

Example: specular highlights (Phong illumination/shading)

Phong shading:
per-fragment evaluation

Gouraud shading:
linear interpolation from vertices



Per-Pixel Phong Lighting (Cg)



```
void main(float4 position : TEXCOORD0,
          float3 normal   : TEXCOORD1,

          out float4 oColor : COLOR,

          uniform float3 ambientCol,
          uniform float3 lightCol,
          uniform float3 lightPos,
          uniform float3 eyePos,
          uniform float3 Ka,
          uniform float3 Kd,
          uniform float3 Ks,
          uniform float shiny)
{
```

Per-Pixel Phong Lighting (Cg)



```
float3 P = position.xyz;
float3 N = normal;
float3 V = normalize(eyePosition - P);
float3 H = normalize(L + V);

float3 ambient = Ka * ambientCol;

float3 L          = normalize(lightPos - P);
float  diffLight = max(dot(L, N), 0);
float3 diffuse    = Kd * lightCol * diffLight;

float  specLight = pow(max(dot(H, N), 0), shiny);
float3 specular  = Ks * lightCol * specLight;

oColor.xyz = ambient + diffuse + specular;
oColor.w = 1;
}
```

GPU Architecture: General Architecture

Concepts: Latency vs. Throughput



Latency

- What is the time between start and finish of an operation/computation?
- How long does it take between starting to execute an instruction until the execution is actually finished?
- Examples: 1 FP32 MUL instruction; 1 vertex computation, ...

Throughput

- How many computations (operations/instructions) finish per time unit?
- How many instructions of a certain type (e.g., FP32 MUL) finish per time unit (per clock cycle, per second)?

GPUs: ***High-throughput execution*** (at the expense of latency)
(but: *hide* latencies to avoid throughput going down)

Concepts: Types of Parallelism



Instruction level parallelism (ILP)

- In single instruction stream: Can consecutive instructions/operations be executed in parallel? (Because they don't have a dependency)
- To exploit ILP: Execute independent instructions in parallel (e.g., superscalar processors)
- On GPUs: also important, but much less than TLP (compare, e.g., Kepler with current GPUs)

Thread level parallelism (TLP)

- Exploit that by definition operations in different threads are independent (if no explicit communication/synchronization is used)
- To exploit TLP: Execute operations/instructions from multiple threads in parallel
- **On GPUs: main type of parallelism**

(more types:

- Bit-level parallelism (processor word size: 64 bits instead of 32, etc.)
- Data parallelism (SIMD, but also SIMT), task parallelism, ...)

Concepts: Latency Hiding



It's not about latency of single operation or group of operations,
it's about avoiding that the *throughput* goes below peak

Hide latency that *does* occur for one instruction (group) by
executing a different instruction (group) as soon as current one stalls:

→ *Total throughput does not go down*

In GPUs, hide latencies via:

- **TLP: pull independent, not-stalling instruction from other thread group**
- ILP: pull independent instruction from down the inst. stream in same thread group
- Depending on GPU: TLP often sufficient, but sometimes also need ILP
- However: If in one cycle TLP doesn't work, ILP can jump in or vice versa



From Shader Code to a **Teraflop**: How Shader Cores Work

Kayvon Fatahalian
Stanford University

Where this is going...



Summary: three key ideas for high-throughput execution

- 1. Use many “slimmed down cores,” run them in parallel**
- 2. Pack cores full of ALUs (by sharing instruction stream overhead across groups of fragments)**
 - Option 1: Explicit SIMD vector instructions**
 - Option 2: Implicit sharing managed by hardware**
- 3. Avoid latency stalls by interleaving execution of many groups of fragments**
 - When one group stalls, work on another group**

Where this is going...

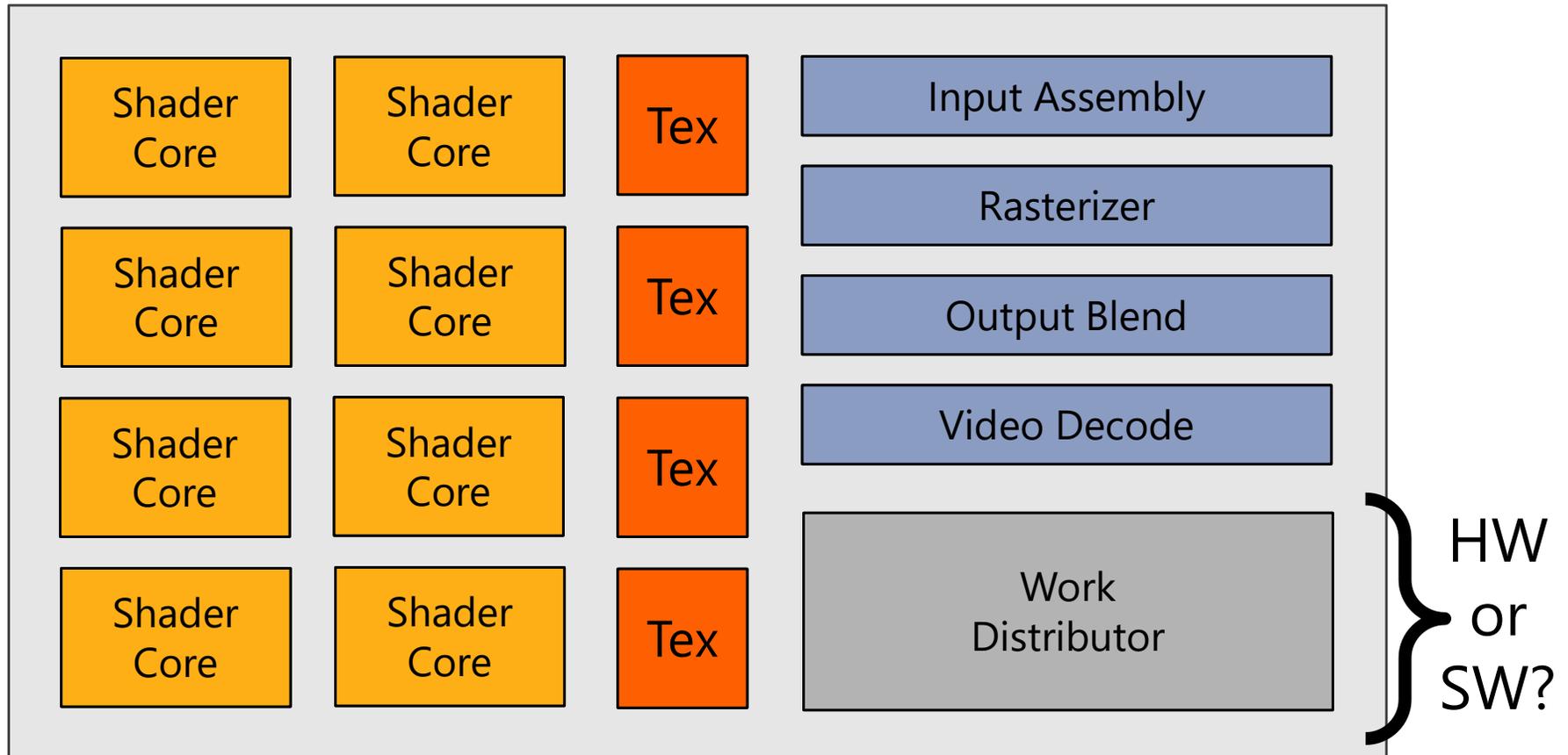


Summary: three key ideas for high-throughput execution

1. Use many “slimmed down cores,” run them in parallel
2. Pack cores full of ALUs (by sharing instruction stream overhead across groups of fragments)
 - Option 1: Explicit SIMD vector instructions
 - Option 2: Implicit sharing managed by hardware
3. Avoid latency stalls by interleaving execution of many groups of fragments
 - When one group stalls, work on another group

**GPUs are here!
(usually)**

What's in a GPU?



Heterogeneous chip multi-processor (highly tuned for graphics)

A diffuse reflectance shader

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Texture2D<float3> myTex;
float3 lightDir;

float4 diffuseShader(float3 norm, float2 uv)
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    float3 kd;
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```

Independent, but no explicit parallelism

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float4 diffuseShader(float3 norm, float2 uv)
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    kd = myTex.Sample(mySamp, uv);
    kd *= clamp ( dot(lightDir, norm), 0.0, 1.0);
    return float4(kd, 1.0);
}
```



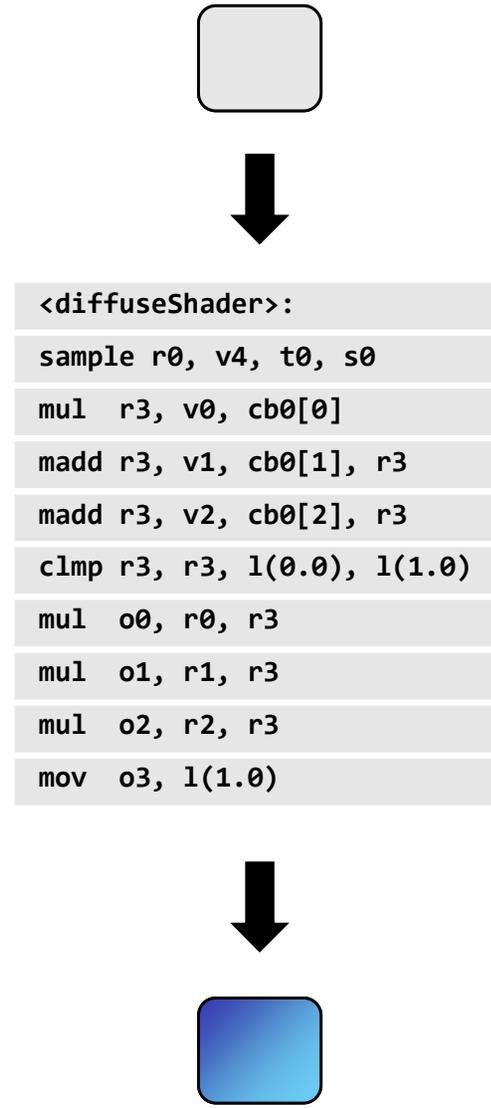
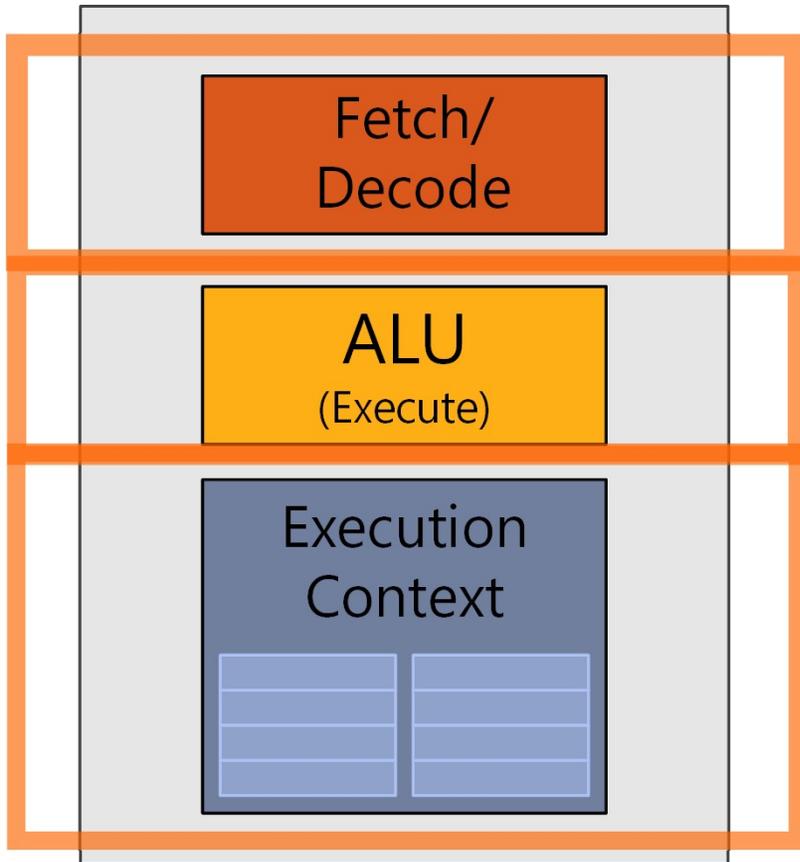
```
<diffuseShader>:
sample r0, v4, t0, s0
mul  r3, v0, cb0[0]
madd r3, v1, cb0[1], r3
madd r3, v2, cb0[2], r3
clmp r3, r3, 1(0.0), 1(1.0)
mul  o0, r0, r3
mul  o1, r1, r3
mul  o2, r2, r3
mov  o3, 1(1.0)
```



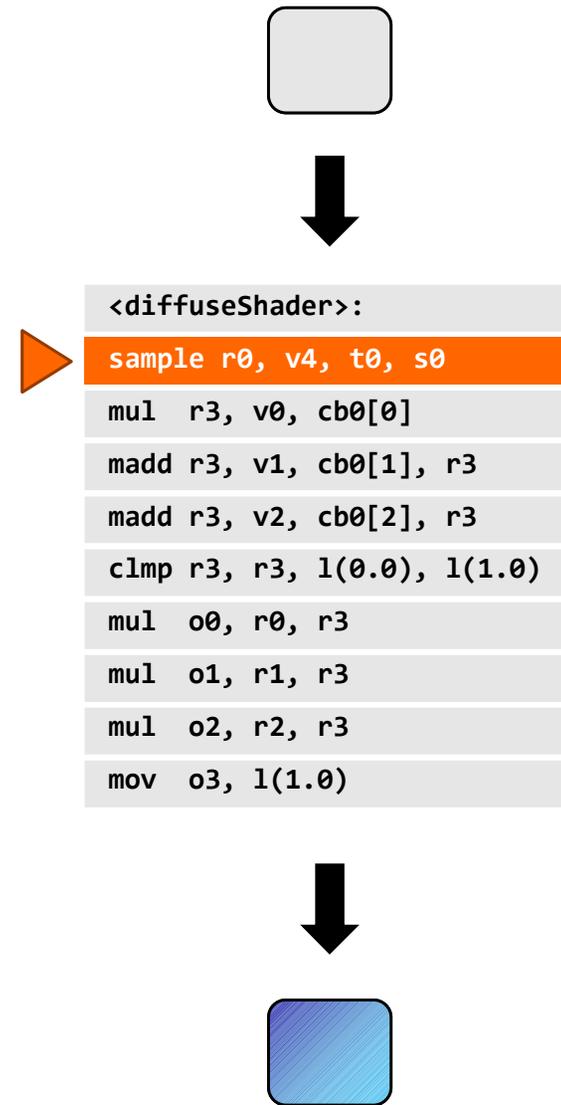
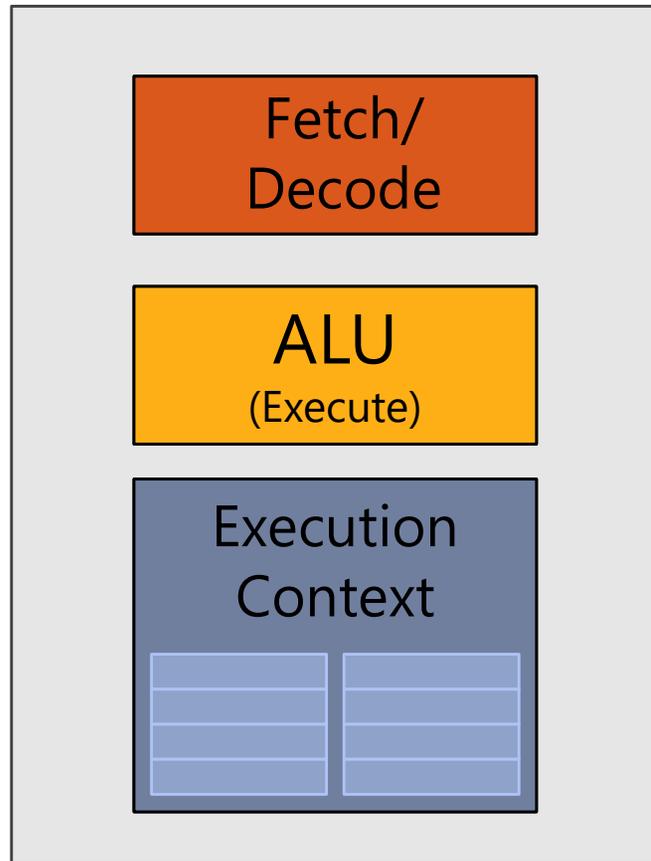
1 shaded fragment output record



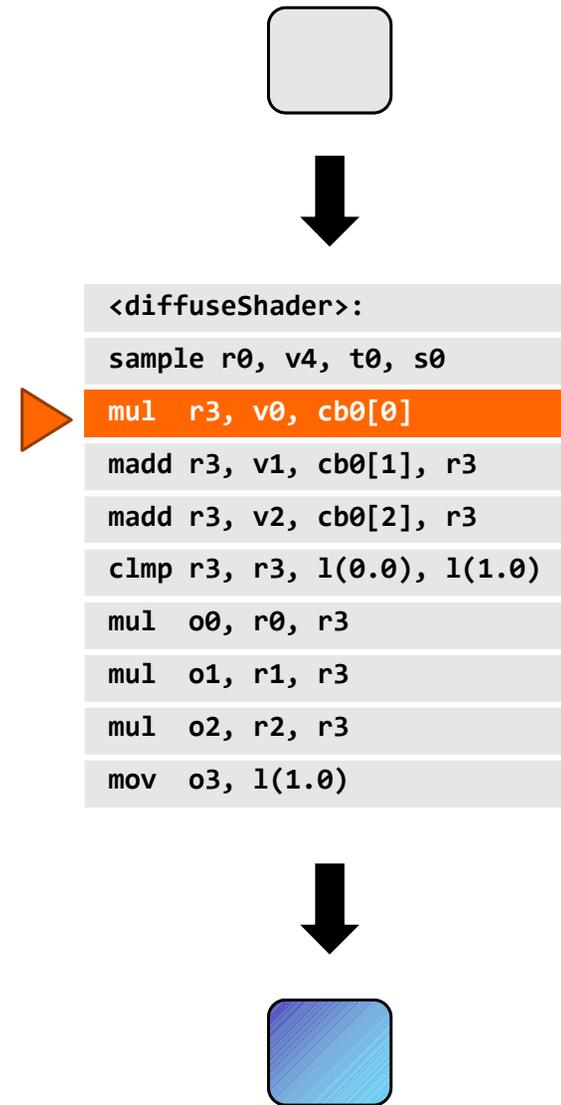
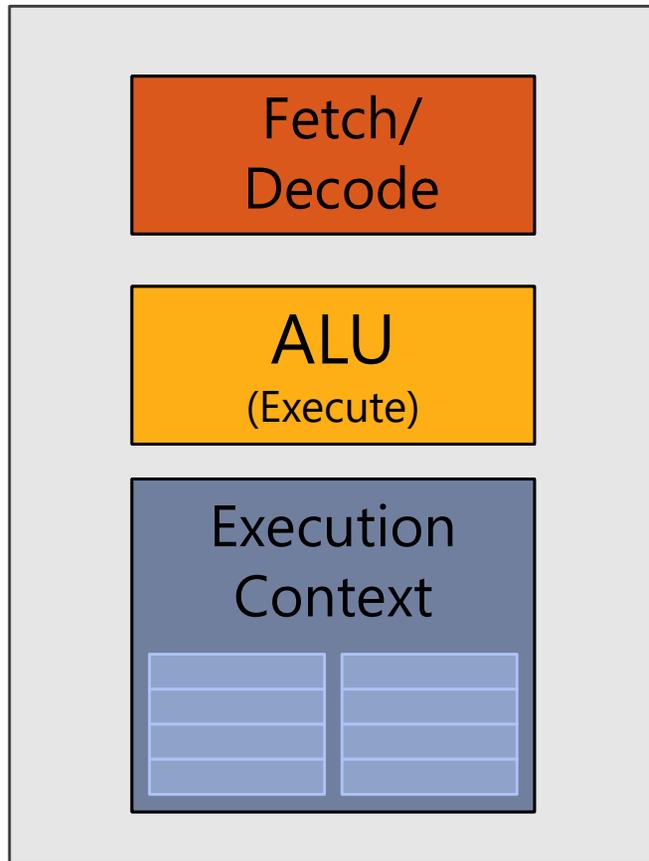
Execute shader



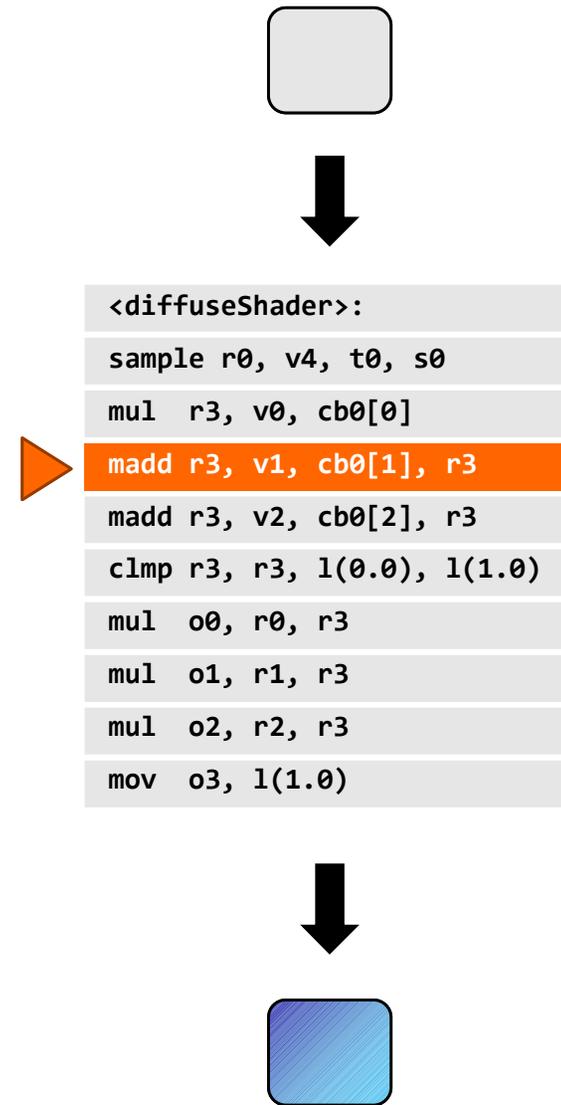
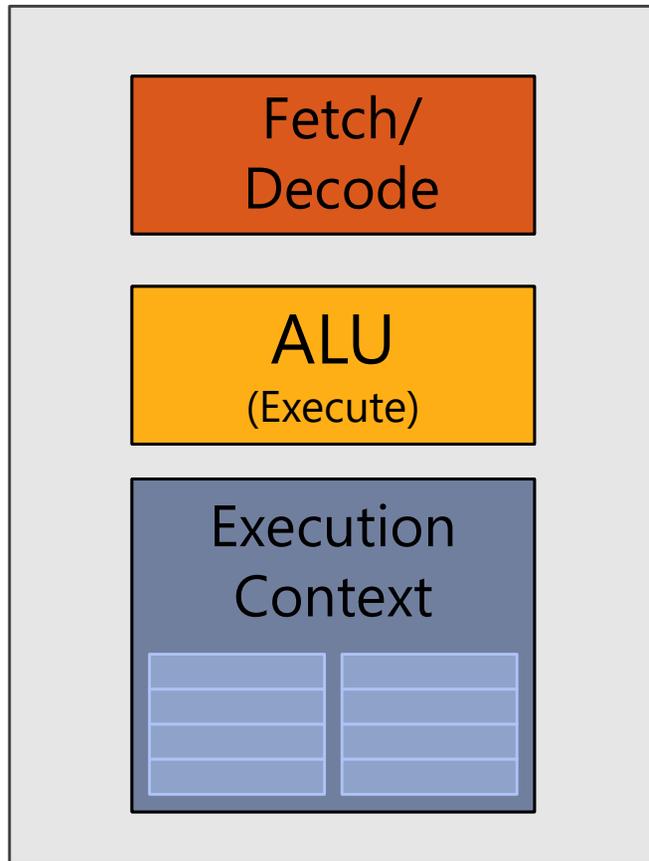
Execute shader



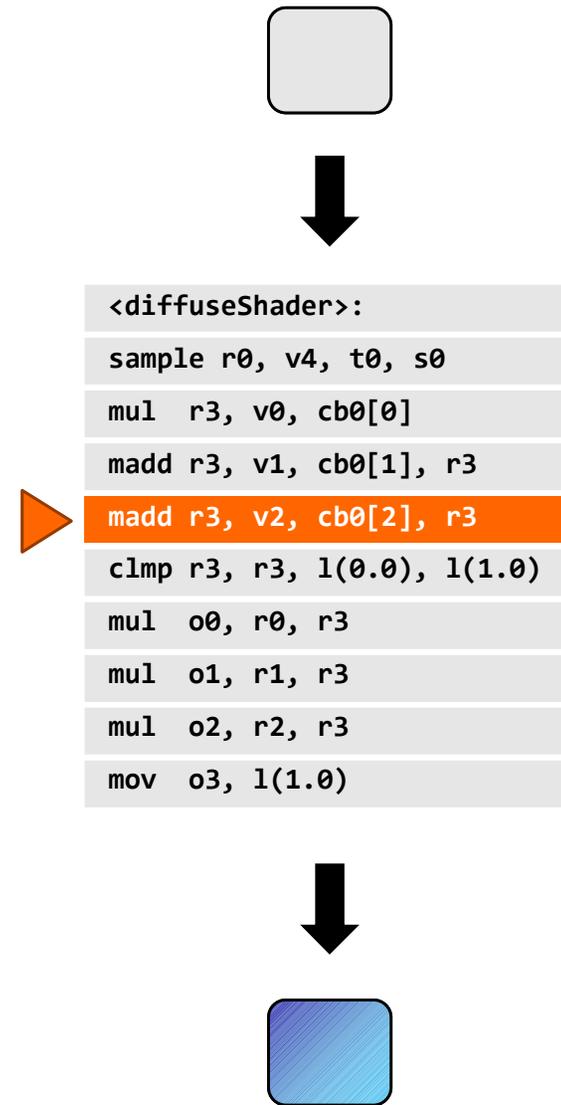
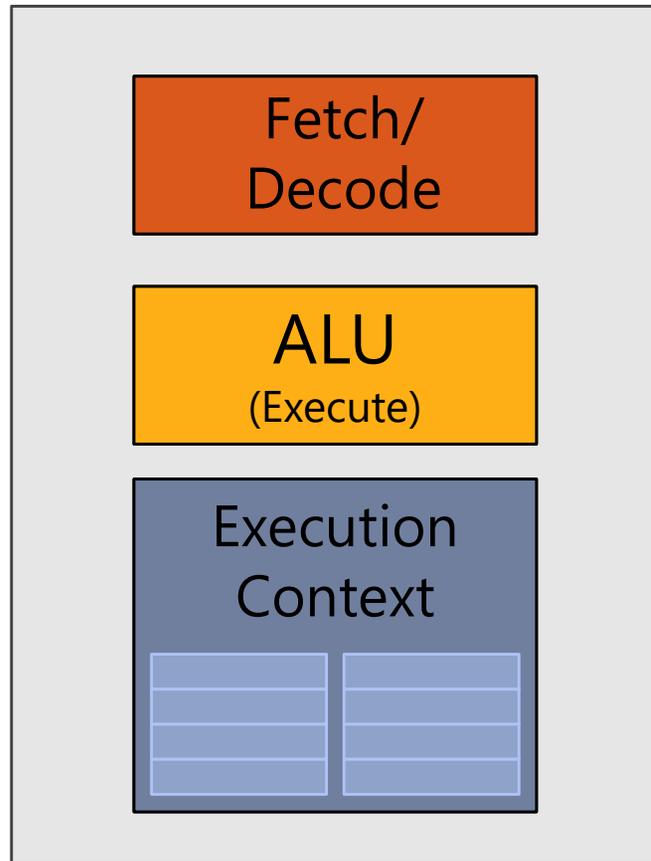
Execute shader



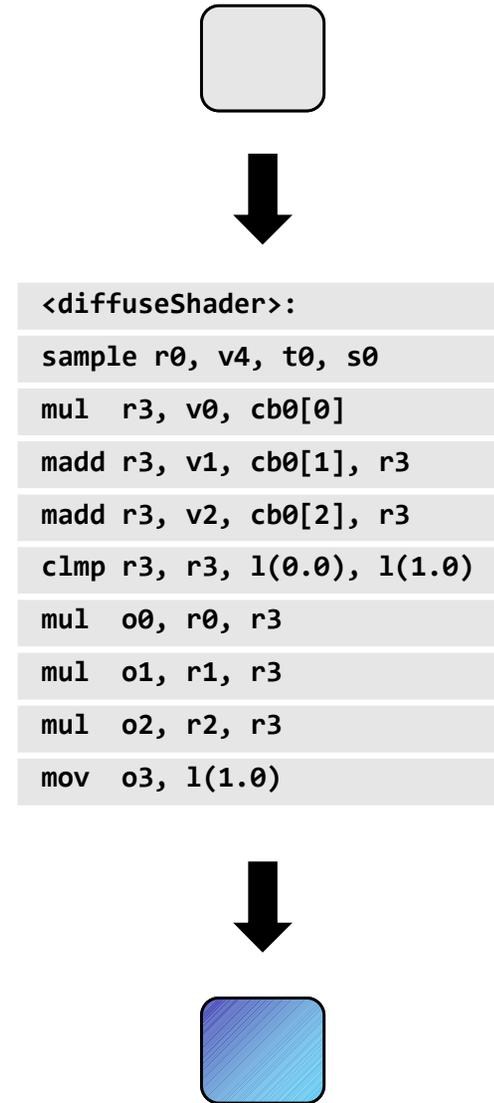
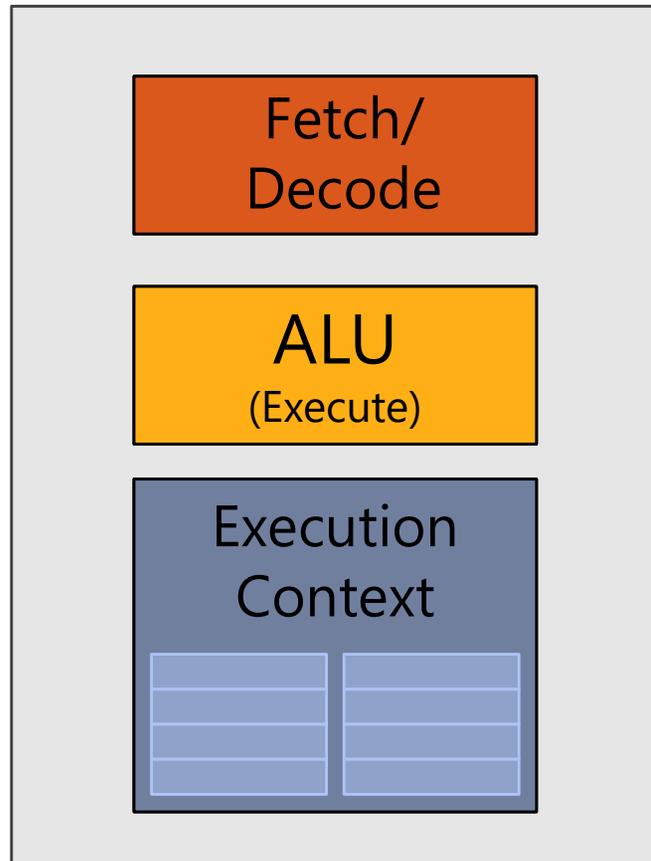
Execute shader



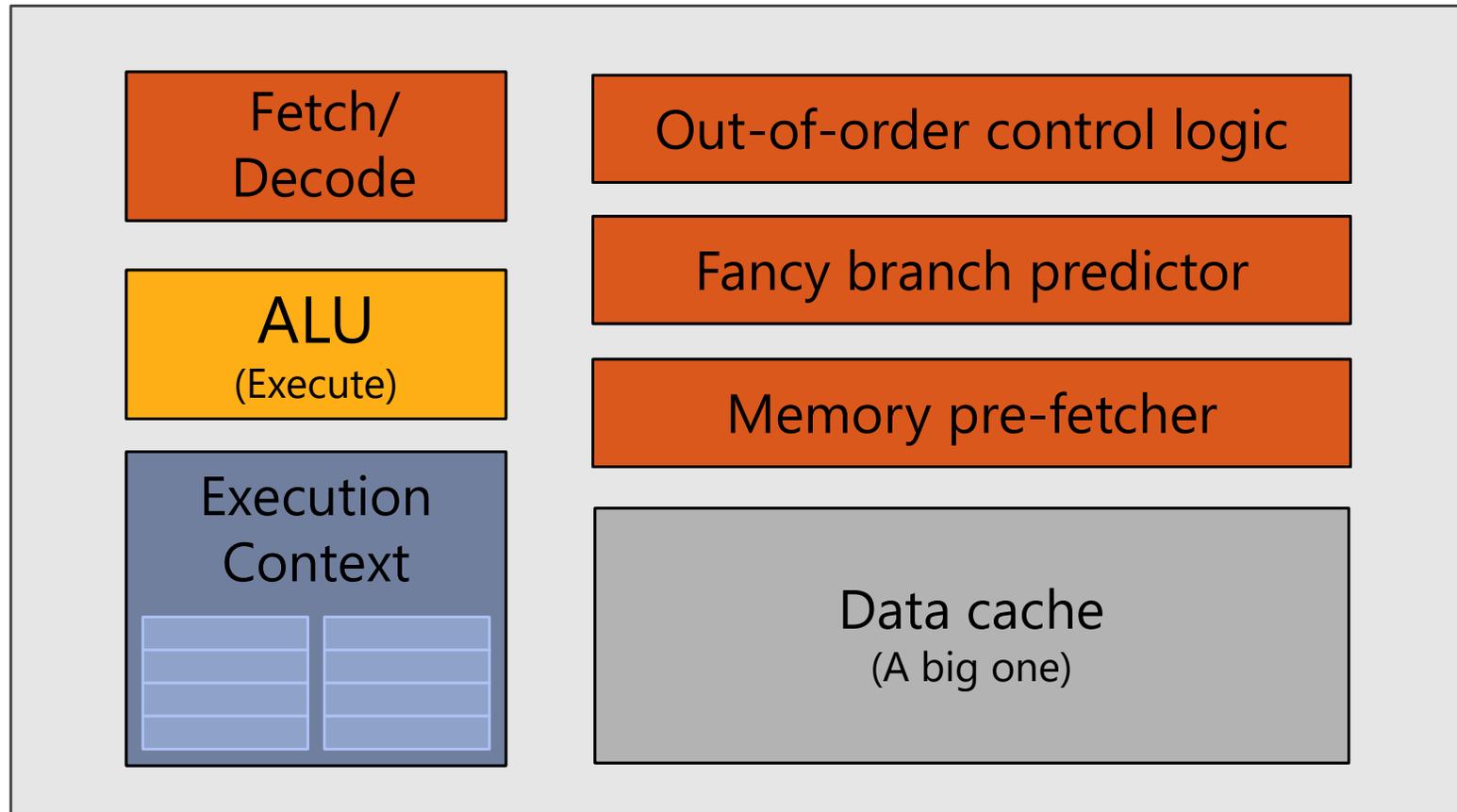
Execute shader



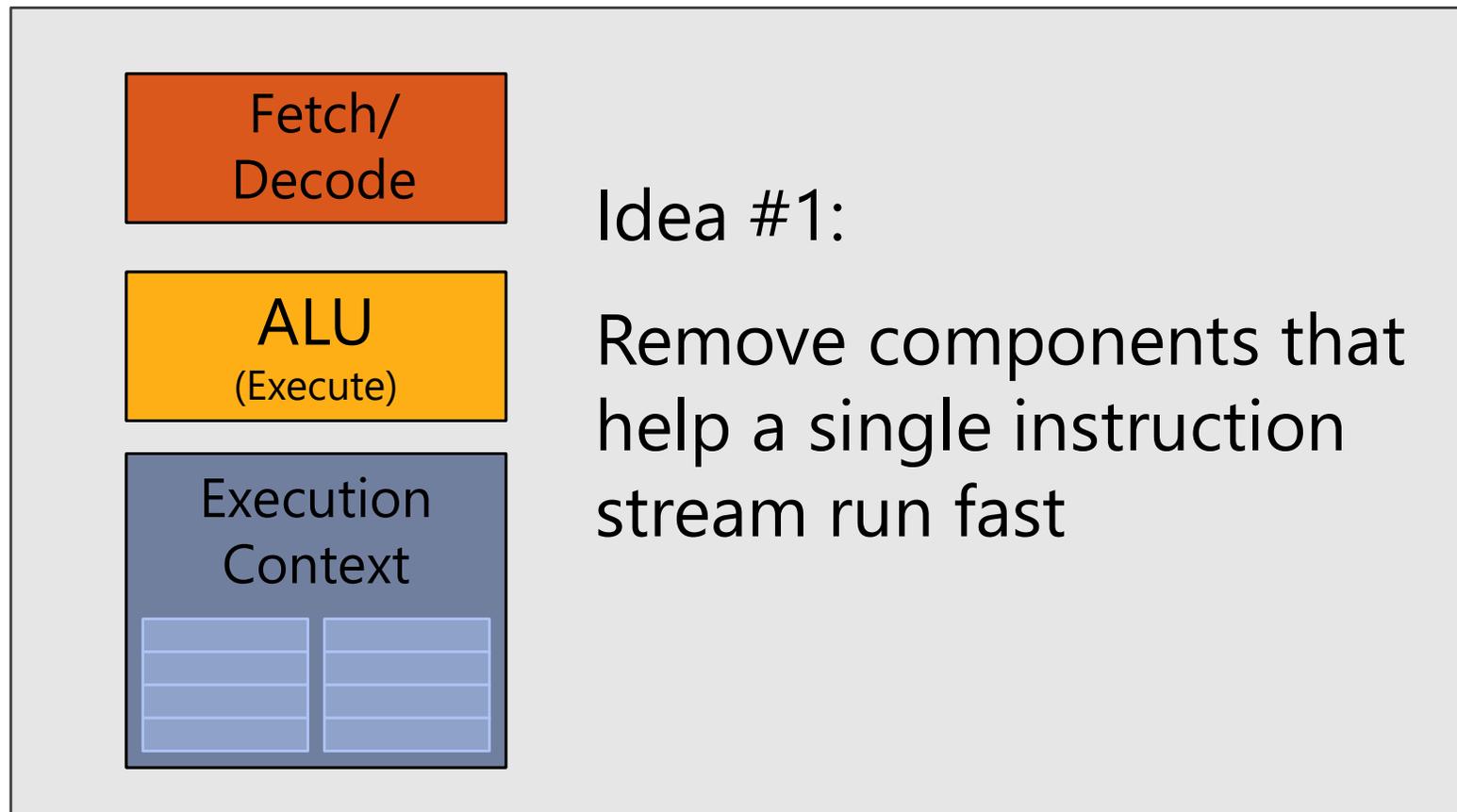
Execute shader



CPU-“style” cores

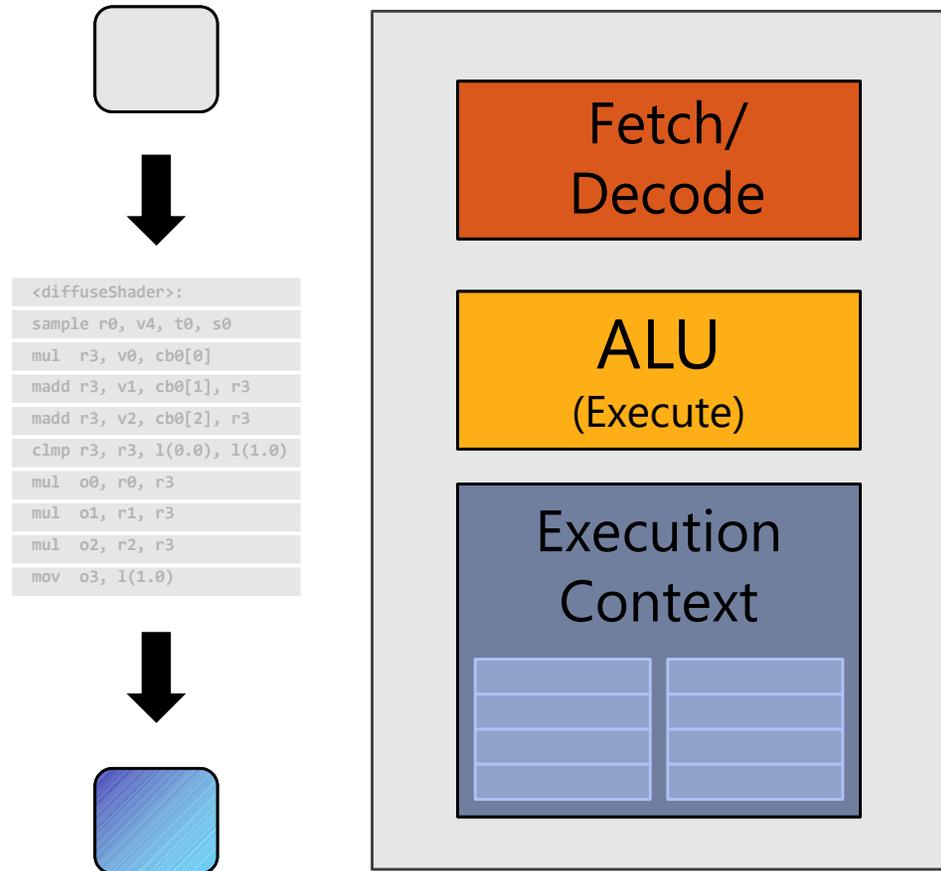


Idea #1: Slim down

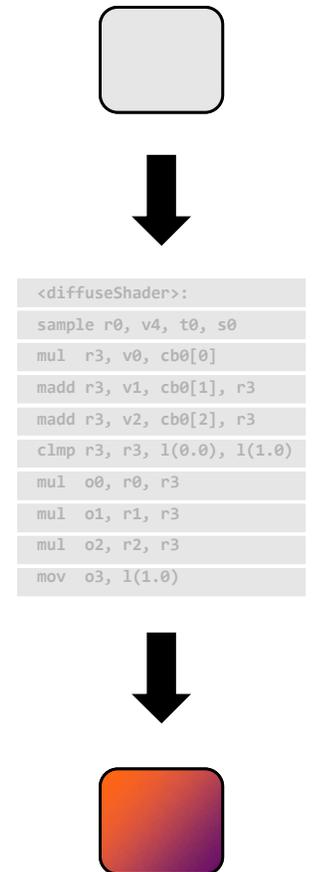


Two cores (two fragments in parallel)

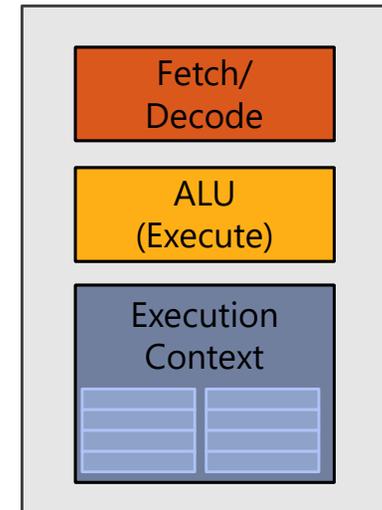
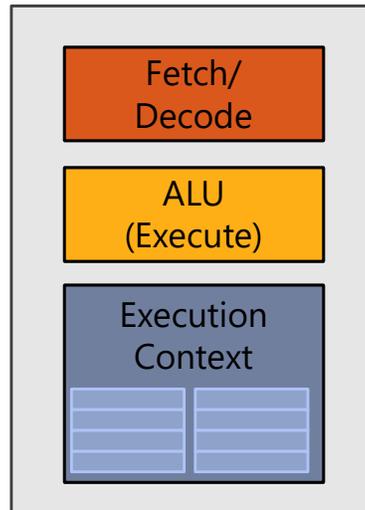
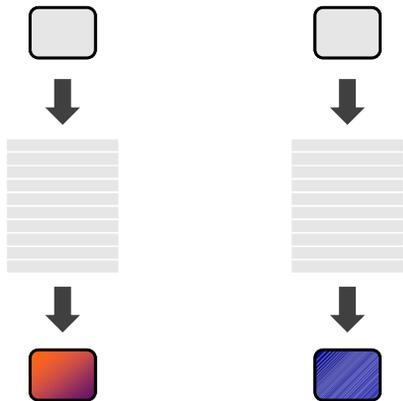
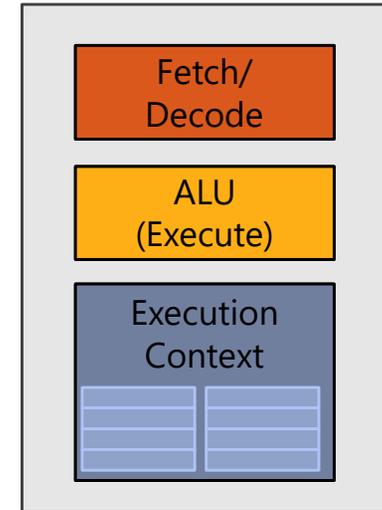
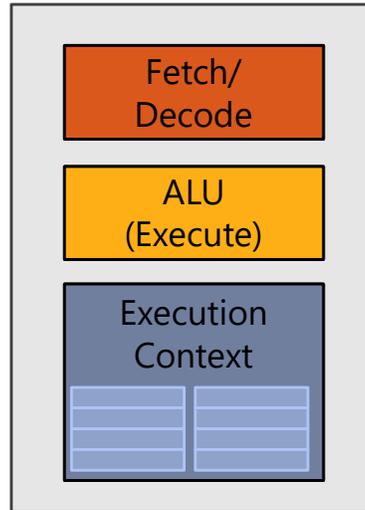
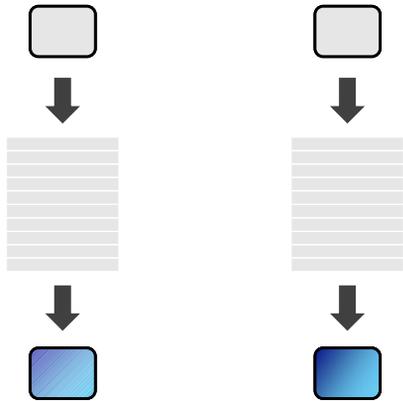
fragment 1



fragment 2



Four cores (four fragments in parallel)

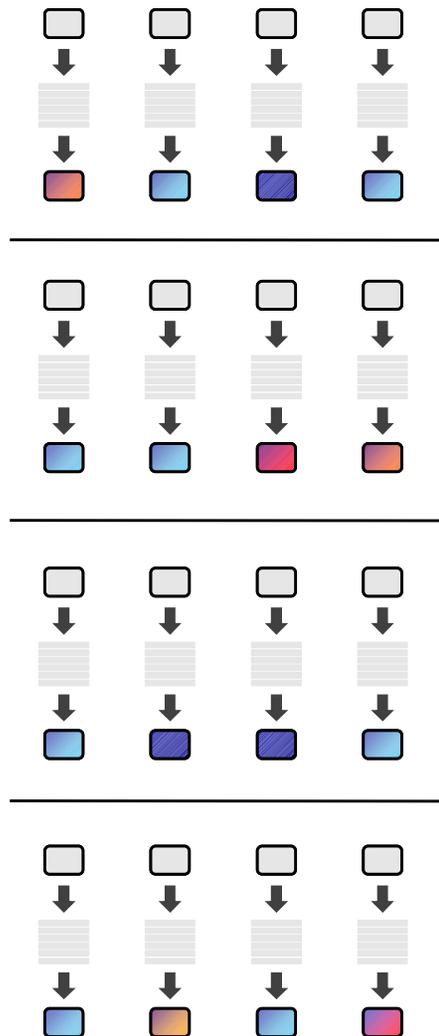


Sixteen cores (sixteen fragments in parallel)



16 cores = 16 simultaneous instruction streams

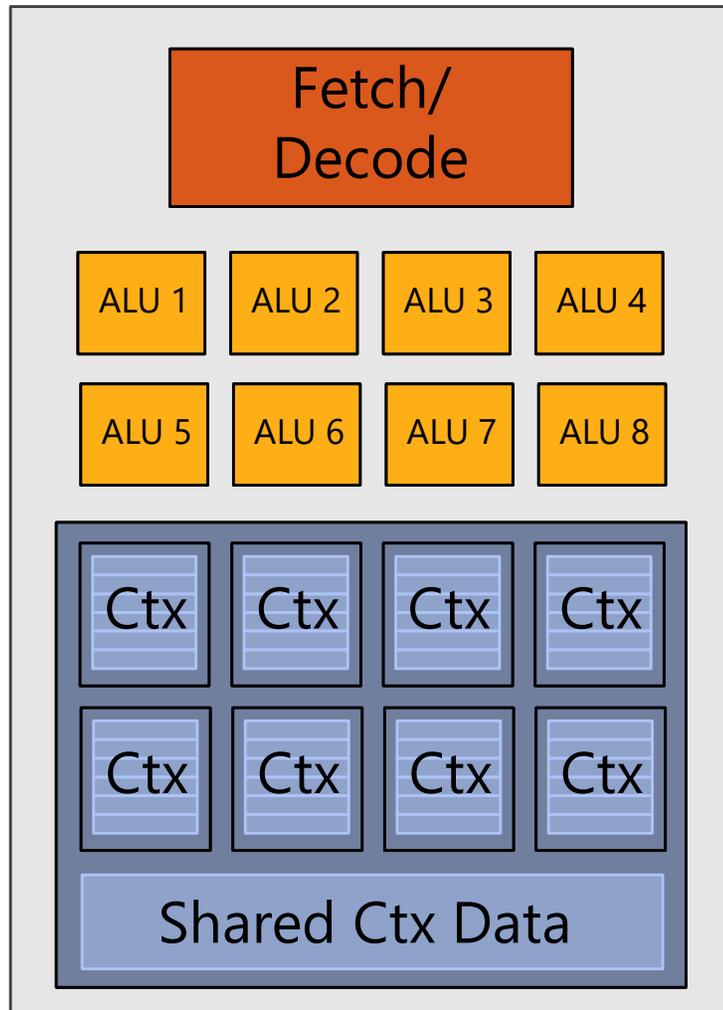
Instruction stream sharing



But... many fragments should be able to share an instruction stream! → **big idea #2 !**

```
<diffuseShader>:  
sample r0, v4, t0, s0  
mul r3, v0, cb0[0]  
madd r3, v1, cb0[1], r3  
madd r3, v2, cb0[2], r3  
clamp r3, r3, 1(0.0), 1(1.0)  
mul o0, r0, r3  
mul o1, r1, r3  
mul o2, r2, r3  
mov o3, 1(1.0)
```

Idea #2: Add ALUs



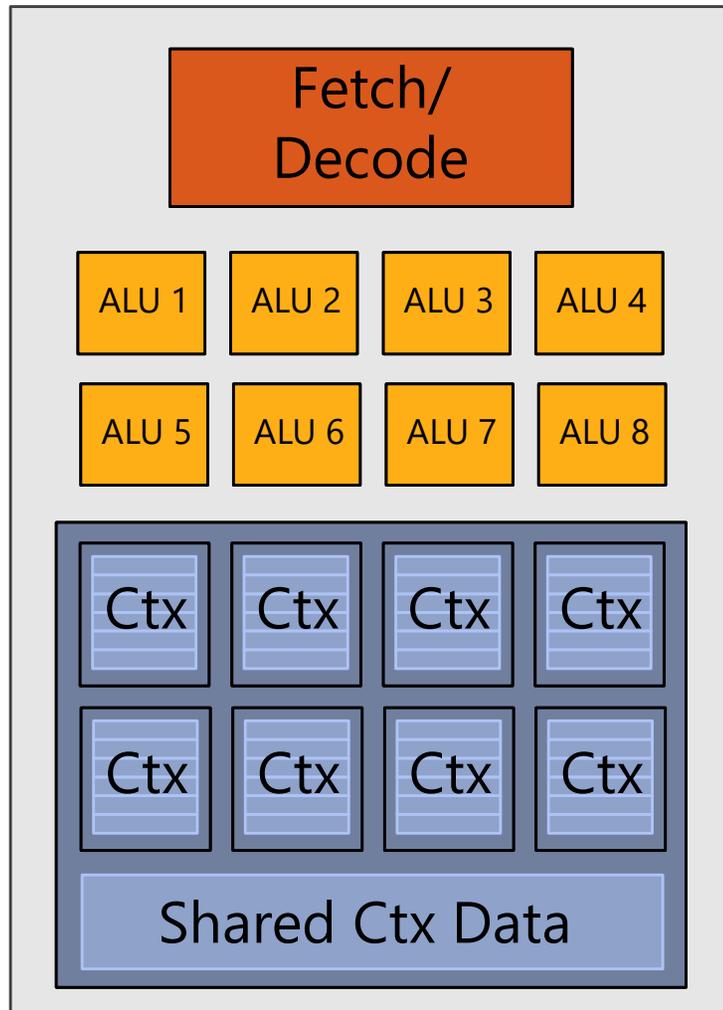
Idea #2:

Amortize cost/complexity of managing an instruction stream across many ALUs

SIMD processing

(or **SIMT**, SPMD)

How does shader execution behave?

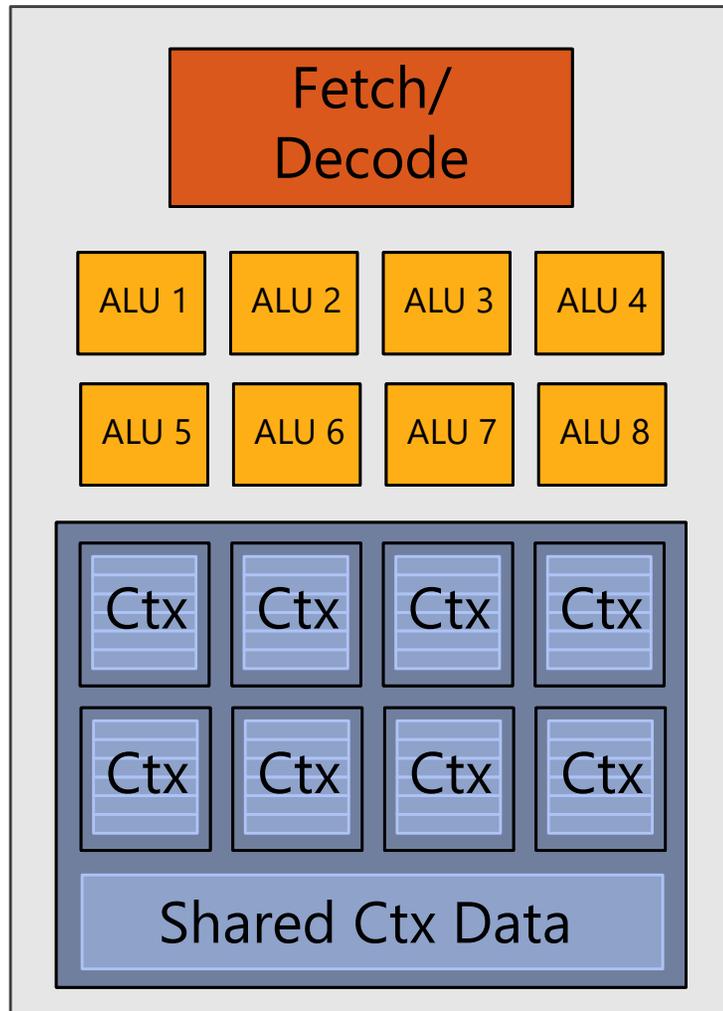


```
<diffuseShader>:  
sample r0, v4, t0, s0  
mul r3, v0, cb0[0]  
madd r3, v1, cb0[1], r3  
madd r3, v2, cb0[2], r3  
clamp r3, r3, 1(0.0), 1(1.0)  
mul o0, r0, r3  
mul o1, r1, r3  
mul o2, r2, r3  
mov o3, 1(1.0)
```

Original compiled shader:

Processes one fragment
using scalar ops on scalar registers

How does shader execution behave?



```
<VEC8_diffuseShader>:  
VEC8_sample vec_r0, vec_v4, t0, vec_s0  
VEC8_mul vec_r3, vec_v0, cb0[0]  
VEC8_madd vec_r3, vec_v1, cb0[1], vec_r3  
VEC8_madd vec_r3, vec_v2, cb0[2], vec_r3  
VEC8_clmp vec_r3, vec_r3, 1(0.0), 1(1.0)  
VEC8_mul vec_o0, vec_r0, vec_r3  
VEC8_mul vec_o1, vec_r1, vec_r3  
VEC8_mul vec_o2, vec_r2, vec_r3  
VEC8_mov vec_o3, 1(1.0)
```

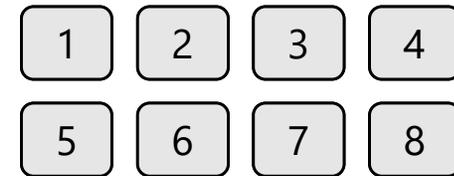
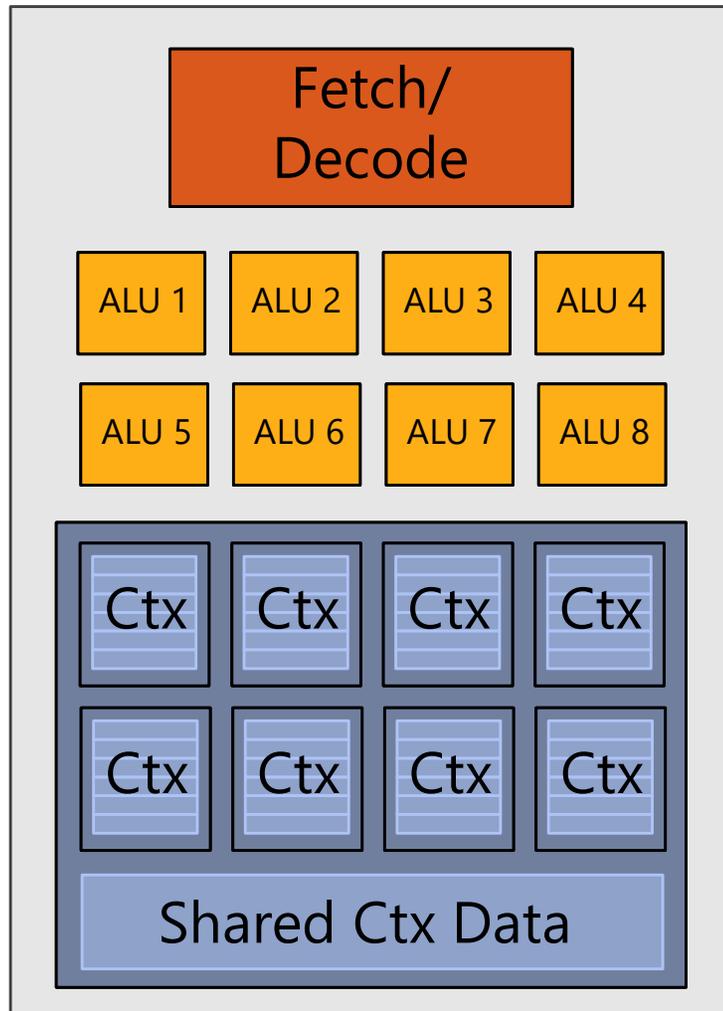
Actually executed shader:

Processes 8 fragments

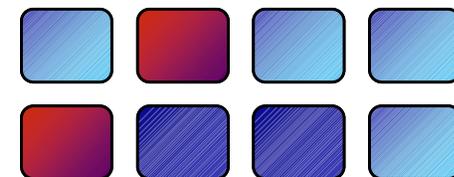
using "vector ops" on "vector registers"

(Caveat: This does NOT mean there are actual vector instructions/cores/regs! See later slide.)

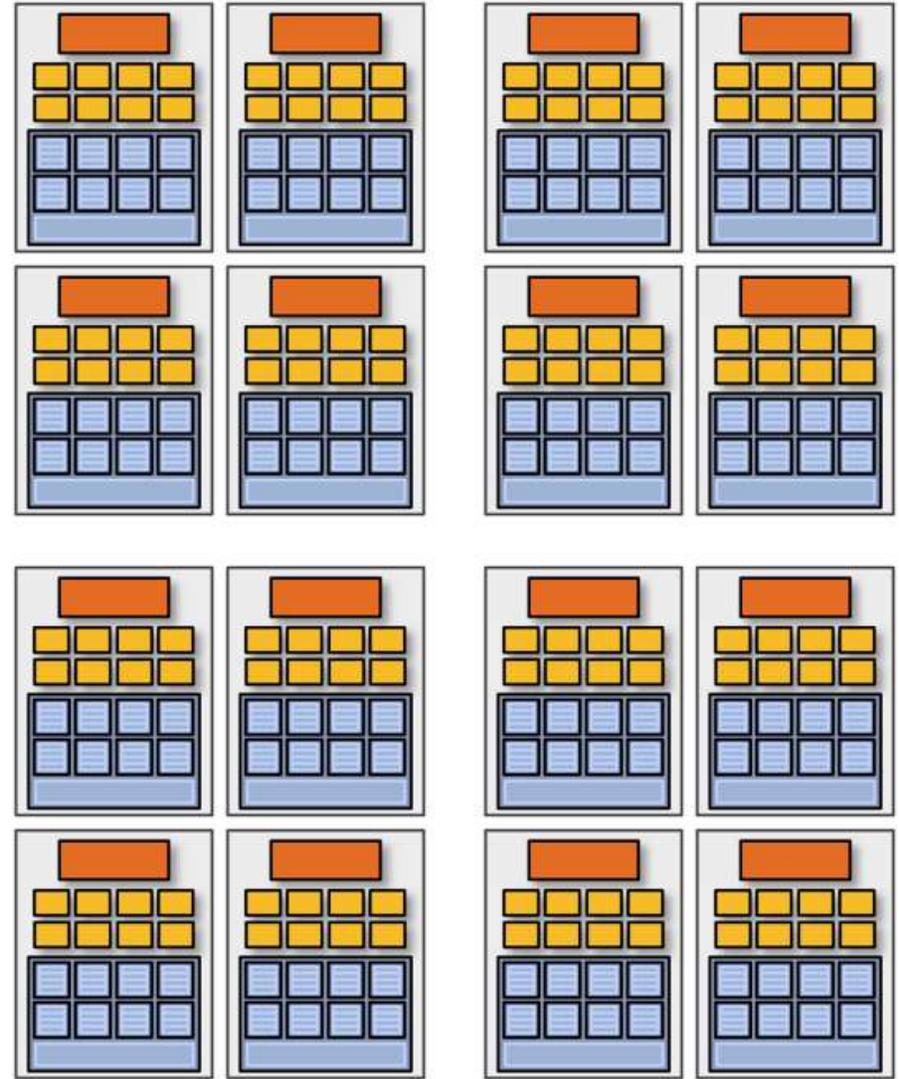
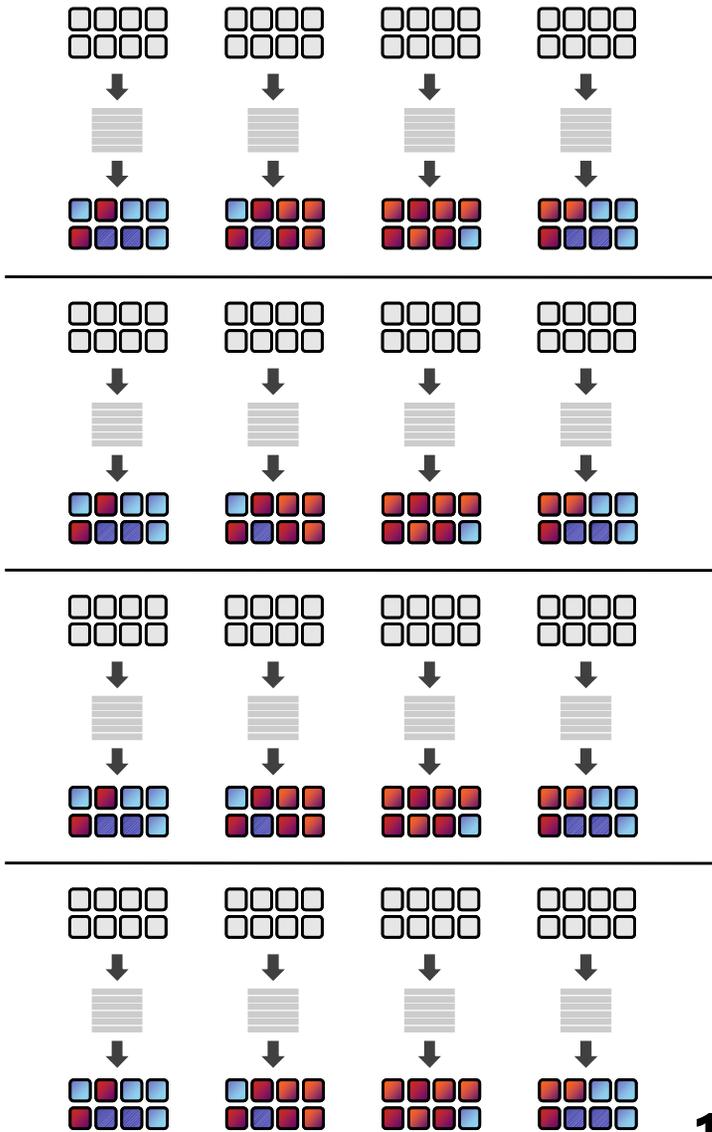
How does shader execution behave?



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<VEC8_diffuseShader>:  
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VEC8_madd vec_r3, vec_v2, cb0[2], vec_r3  
VEC8_clmp vec_r3, vec_r3, 1(0.0), 1(1.0)  
VEC8_mul vec_o0, vec_r0, vec_r3  
VEC8_mul vec_o1, vec_r1, vec_r3  
VEC8_mul vec_o2, vec_r2, vec_r3  
VEC8_mov vec_o3, 1(1.0)
```

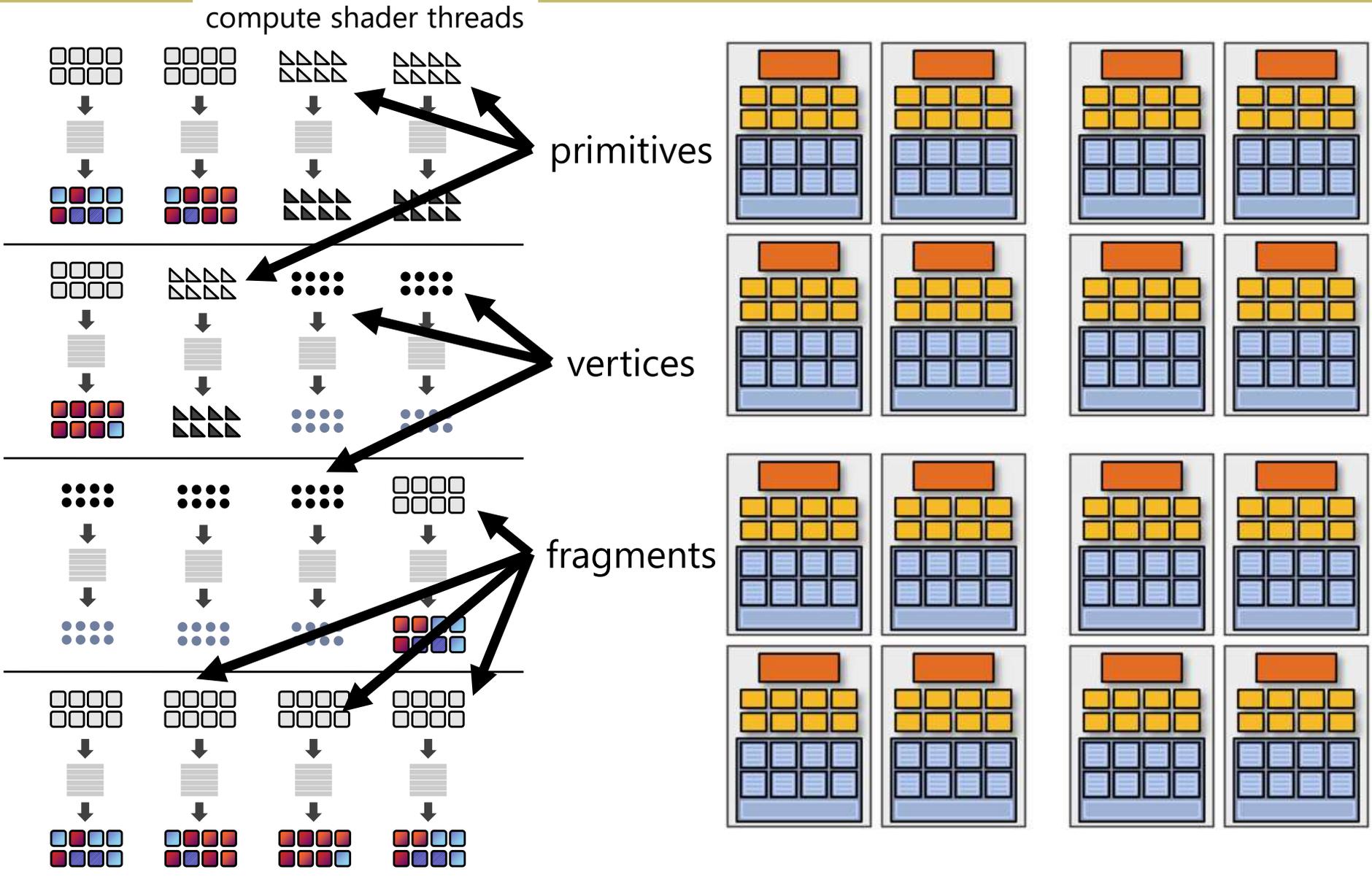


128 fragments in parallel



16 cores = **128** ALUs
= **16** simultaneous instruction streams

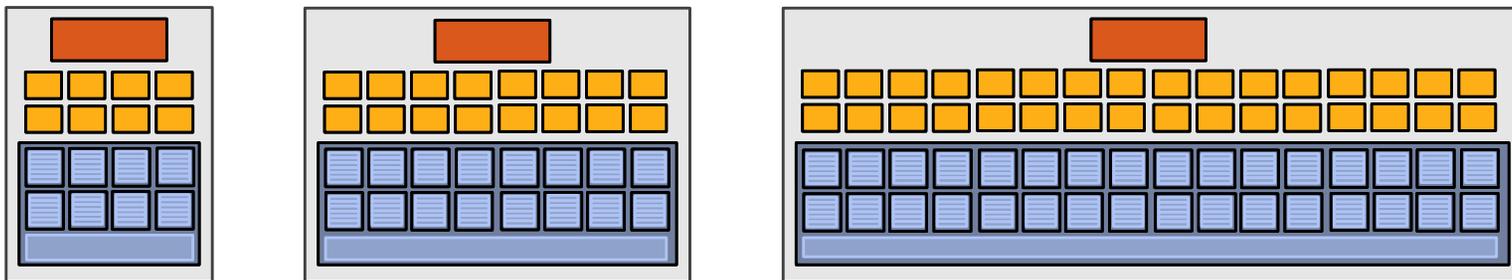
128 [vertices / fragments primitives CUDA threads OpenCL work items compute shader threads] in parallel



Clarification

SIMD processing does not imply SIMD instructions

- Option 1: Explicit vector instructions
 - Intel/AMD x86 MMX/SSE/AVX(2), Intel Larrabee/Xeon Phi/ ...
- Option 2: Scalar instructions, implicit HW vectorization
 - HW determines instruction stream sharing across ALUs (amount of sharing hidden from software, i.e., not in ISA)
 - NVIDIA GeForce (“SIMT” warps), AMD Radeon/GNC/RDNA(2)



In practice: 16 to 64 fragments share an instruction stream

Thank you.