

CS 380 - GPU and GPGPU Programming

Lecture 15: GPU Texturing 2

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Reading Assignment #9 (until Nov 2)



Read (required):

- MIP-Map Level Selection for Texture Mapping

<https://ieeexplore.ieee.org/stamp/stamp.jsp?arnumber=765326>

- Homogeneous Coordinates

https://en.wikipedia.org/wiki/Homogeneous_coordinates

- *Don't forget:*

Interpolation for Polygon Texture Mapping and Shading,
Paul Heckbert and Henry Moreton

<http://citeseerx.ist.psu.edu/viewdoc/summary?doi=10.1.1.48.7886>

Read (optional):

- Vulkan Tutorial

<https://vulkan-tutorial.com>



This week is IEEE VIS: registration is free



`ieeevis.org`

`virtual.ieeevis.org`

Quiz #2: Oct 28



Organization

- First 30 min of lecture
- No material (book, notes, ...) allowed

Content of questions

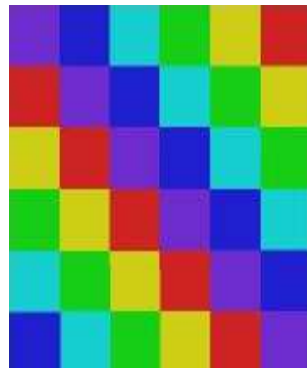
- Lectures (both actual lectures and slides)
- Reading assignments
- Programming assignments (algorithms, methods)
- Solve short practical examples

GPU Texturing

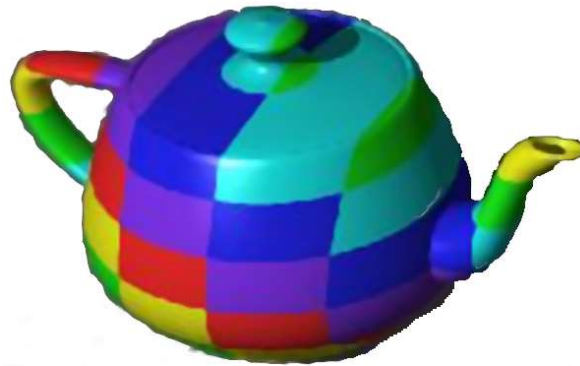


Rage / id Tech 5 (id Software)

Texturing: General Approach



Texels



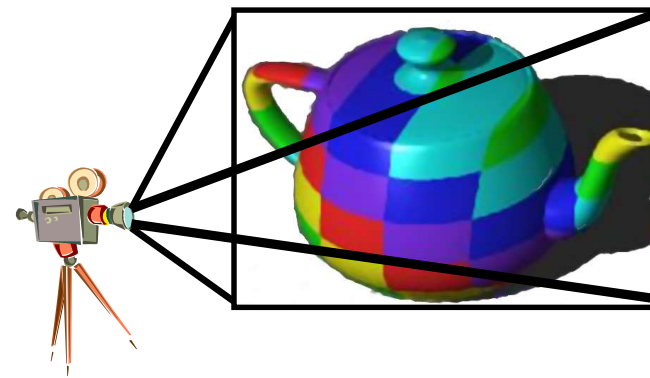
Texture space (u, v)

Object space (x_O, y_O, z_O)

Image Space (x_I, y_I)

Parametrization

Rendering
(Projection etc.)



Texture Mapping

2D (3D) Texture Space

| Texture Transformation

2D Object Parameters

| Parameterization

3D Object Space

| Model Transformation

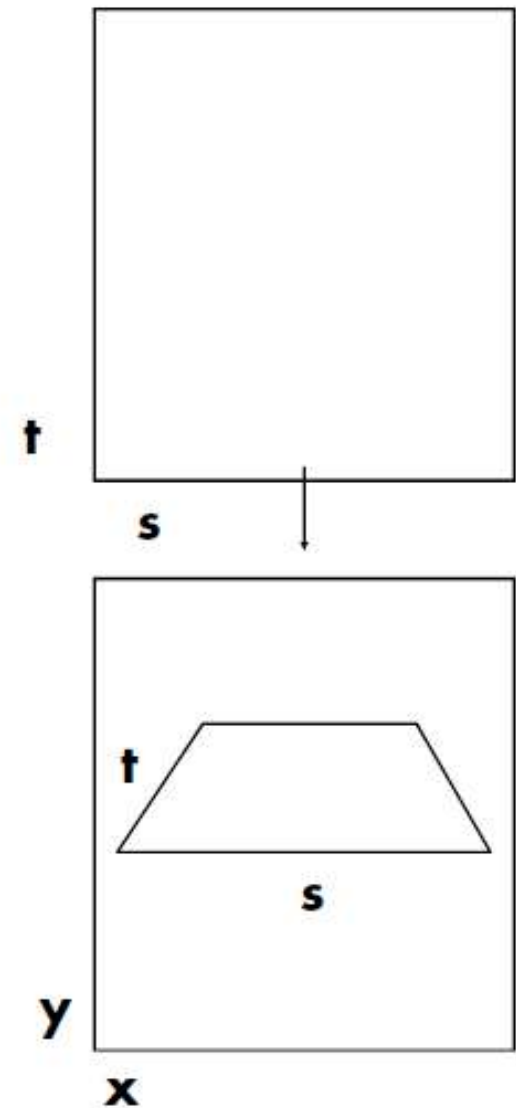
3D World Space

| Viewing Transformation

3D Camera Space

| Projection

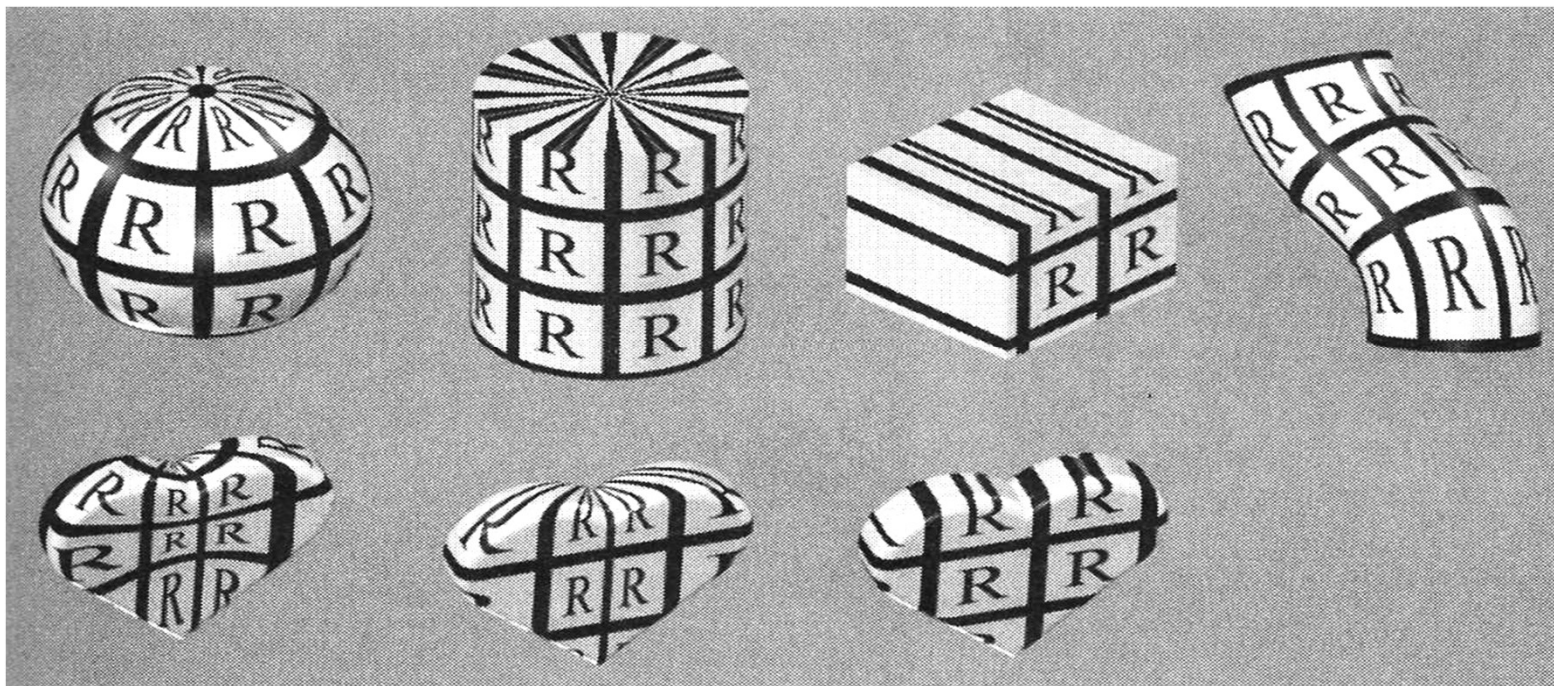
2D Image Space



Where do texture coordinates come from?

- **Online:** texture matrix/texcoord generation
- **Offline:** manually (or by modeling program)

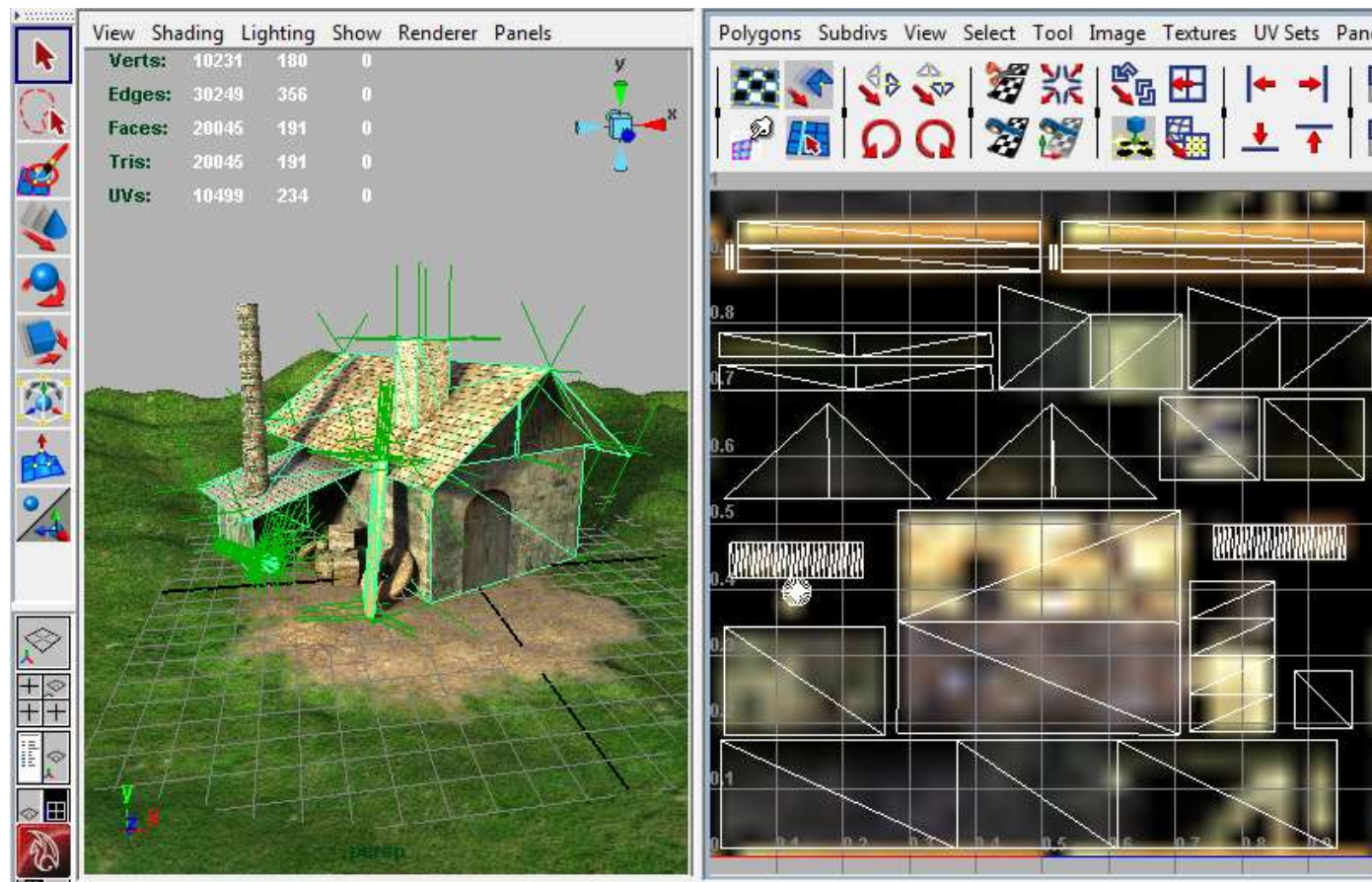
spherical *cylindrical* *planar* *natural*



Texture Projectors

Where do texture coordinates come from?

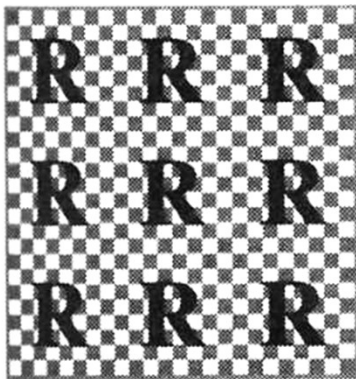
- **Offline:** manual UV coordinates by DCC program
- Note: **a modeling problem!**



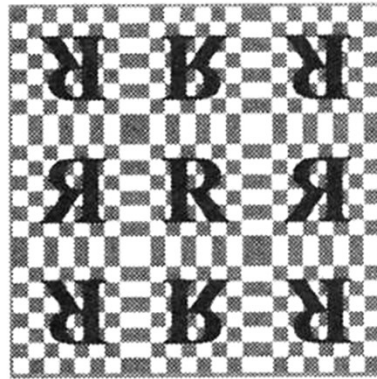
Texture Wrap Mode

- How to extend texture beyond the border?
- Border and repeat/clamp modes
- Arbitrary $(s,t,\dots) \rightarrow [0,1] \times [0,1] \rightarrow [0,255] \times [0,255]$

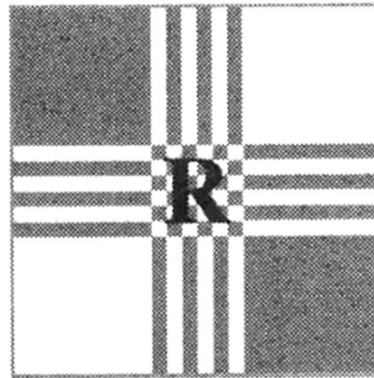
repeat



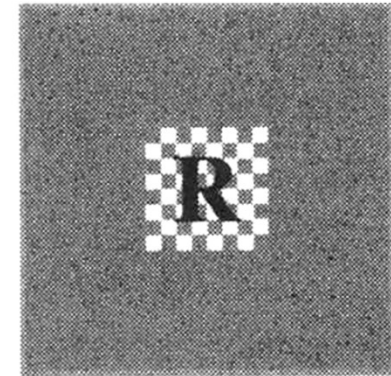
mirror/repeat



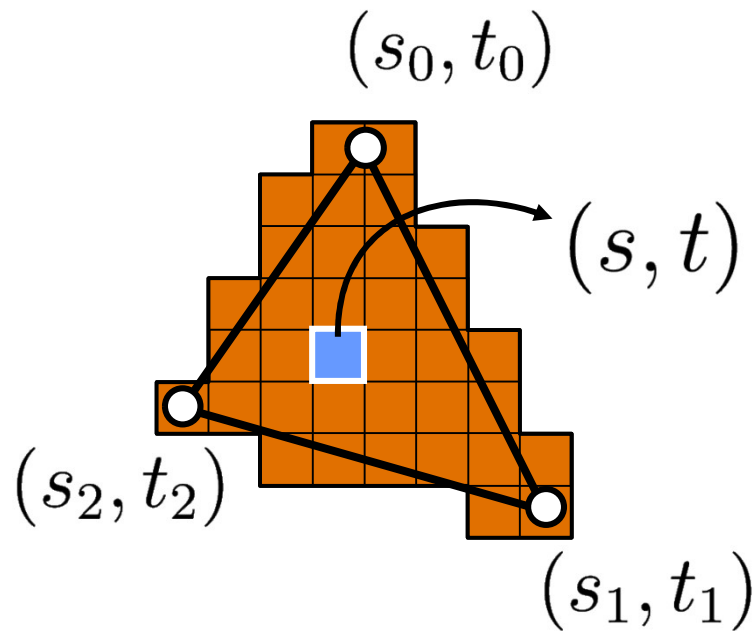
clamp



border



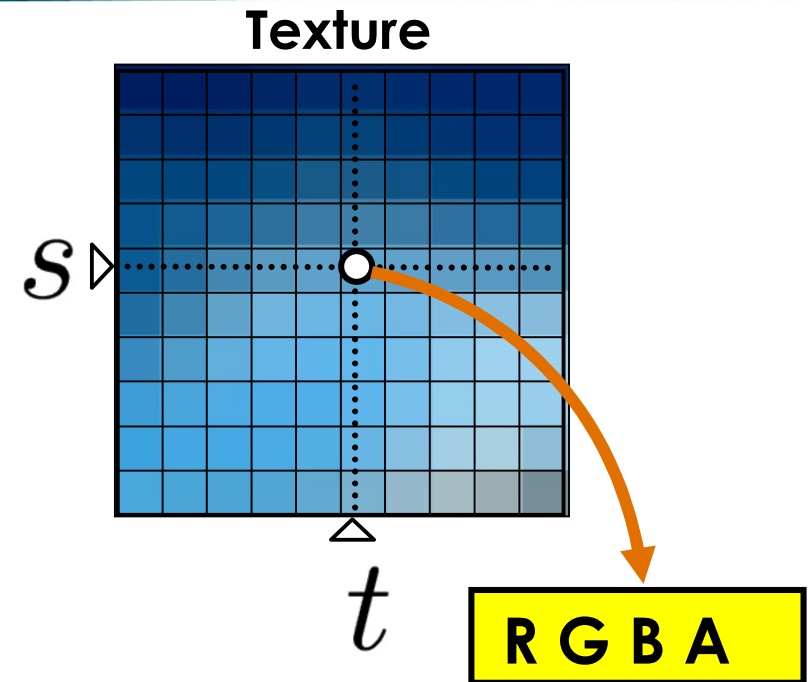
2D Texture Mapping



For each fragment:
interpolate the
texture coordinates
(barycentric)

Or:

Use arbitrary, computed coordinates

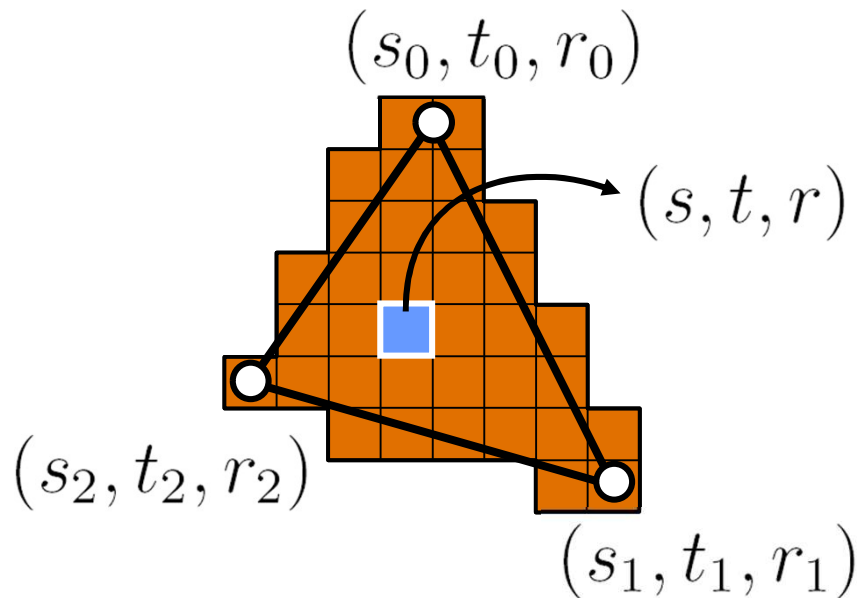


Texture-Lookup:
interpolate the
texture data
(bi-linear)

Or:

Nearest-neighbor for "array lookup"

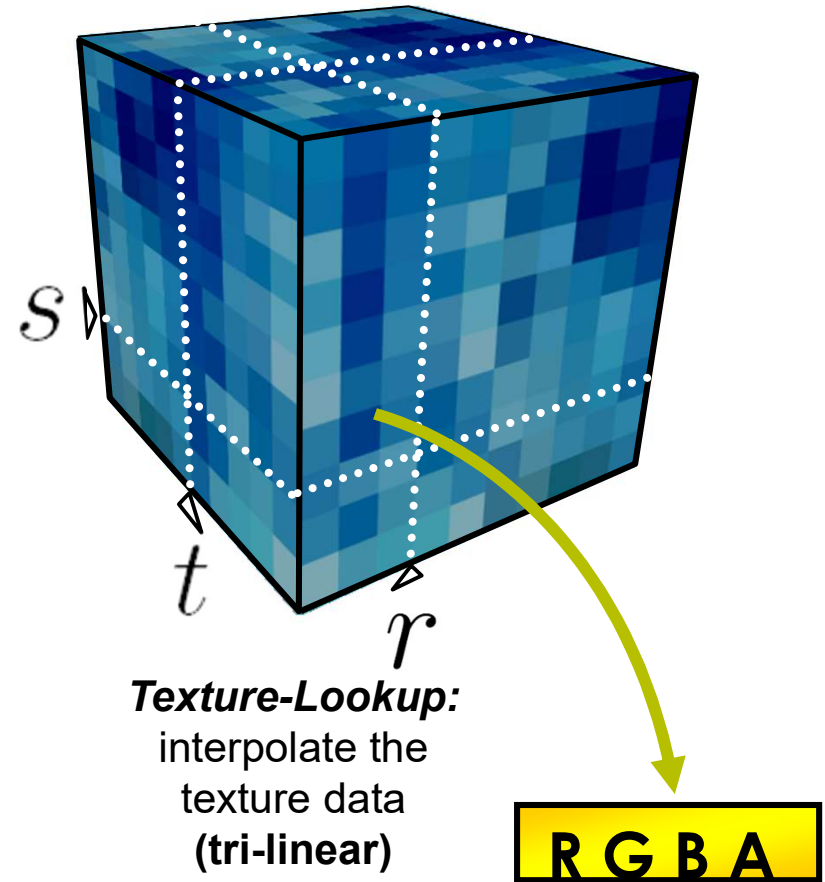
3D Texture Mapping



For each fragment:
interpolate the
texture coordinates
(barycentric)

Or:

Use arbitrary, computed coordinates



Texture-Lookup:
interpolate the
texture data
(tri-linear)

Or:

Nearest-neighbor for “array lookup”



Interpolation Type + Purpose #1:

Interpolation of Texture Coordinates

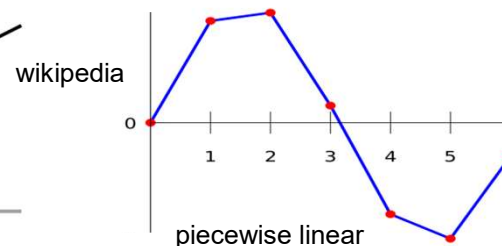
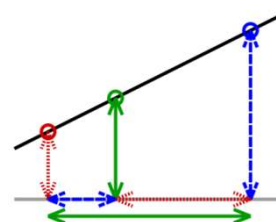
(Linear / Rational-Linear Interpolation)

Linear Interpolation / Convex Combinations



Linear interpolation in 1D:

$$f(\alpha) = (1 - \alpha)v_1 + \alpha v_2$$



Line embedded in 2D (linear interpolation of vertex coordinates/attributes):

$$f(\alpha_1, \alpha_2) = \alpha_1 v_1 + \alpha_2 v_2$$

$$\alpha_1 + \alpha_2 = 1$$

$$f(\alpha) = v_1 + \alpha(v_2 - v_1)$$

$$\alpha = \alpha_2$$

Line segment: $\alpha_1, \alpha_2 \geq 0$ (\rightarrow convex combination)

Compare to line parameterization
with parameter t :

$$v(t) = v_1 + t(v_2 - v_1)$$

Linear Interpolation / Convex Combinations



Linear combination (n -dim. space):

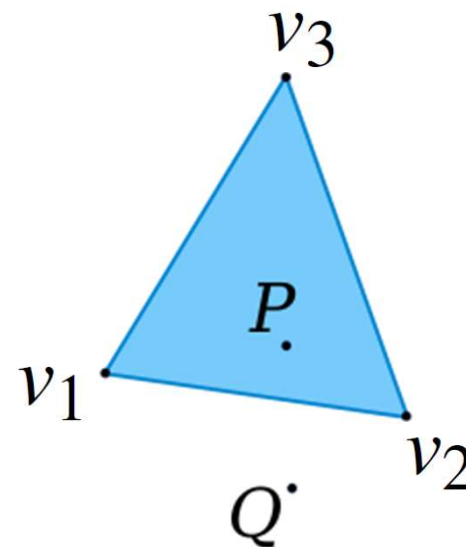
$$\alpha_1 v_1 + \alpha_2 v_2 + \dots + \alpha_n v_n = \sum_{i=1}^n \alpha_i v_i$$

Affine combination: Restrict to $(n - 1)$ -dim. subspace:

$$\alpha_1 + \alpha_2 + \dots + \alpha_n = \sum_{i=1}^n \alpha_i = 1$$

Convex combination: $\alpha_i \geq 0$

(restrict to simplex in subspace)



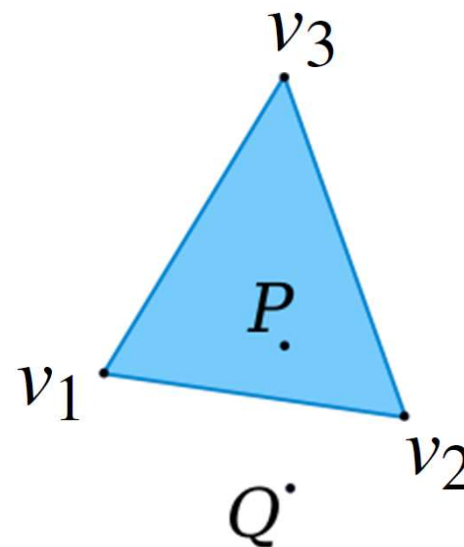
Linear Interpolation / Convex Combinations



$$\alpha_1 v_1 + \alpha_2 v_2 + \dots + \alpha_n v_n = \sum_{i=1}^n \alpha_i v_i$$
$$\alpha_1 + \alpha_2 + \dots + \alpha_n = \sum_{i=1}^n \alpha_i = 1$$

Re-parameterize to get affine coordinates:

$$\begin{aligned}\alpha_1 v_1 + \alpha_2 v_2 + \alpha_3 v_3 &= \\ \tilde{\alpha}_1 (v_2 - v_1) + \tilde{\alpha}_2 (v_3 - v_1) + v_1 & \\ \tilde{\alpha}_1 &= \alpha_2 \\ \tilde{\alpha}_2 &= \alpha_3\end{aligned}$$



Linear Interpolation / Convex Combinations



The weights α_i are the (normalized) barycentric coordinates

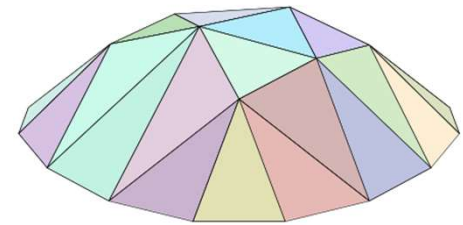
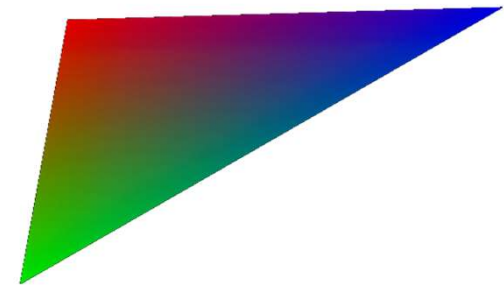
→ linear attribute interpolation in simplex

$$\alpha_1 v_1 + \alpha_2 v_2 + \dots + \alpha_n v_n = \sum_{i=1}^n \alpha_i v_i$$

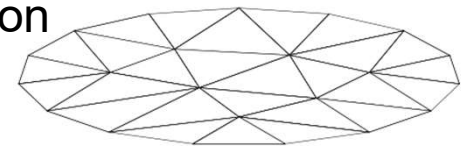
$$\alpha_1 + \alpha_2 + \dots + \alpha_n = \sum_{i=1}^n \alpha_i = 1$$

$$\alpha_i \geq 0$$

attribute interpolation



spatial position
interpolation



wikipedia

Homogeneous Coordinates (1)



Projective geometry

- (Real) projective spaces \mathbb{RP}^n :
Real projective line \mathbb{RP}^1 , real projective plane \mathbb{RP}^2 , ...
- A point in \mathbb{RP}^n is a line through the origin (i.e., all the scalar multiples of the same vector) in an $(n+1)$ -dimensional (real) vector space



Homogeneous coordinates of 2D projective point in \mathbb{RP}^2

- Coordinates differing only by a non-zero factor λ map to the same point
 $(\lambda x, \lambda y, \lambda)$ dividing out the λ gives $(x, y, 1)$, corresponding to (x, y) in \mathbb{R}^2
- Coordinates with last component = 0 map to “points at infinity”
 $(\lambda x, \lambda y, 0)$ division by last component not allowed; but again this is the same point if it only differs by a scalar factor, e.g., this is the same point as $(x, y, 0)$

Homogeneous Coordinates (2)



Examples of usage

- Translation (with translation vector \vec{b})
- Affine transformations (linear transformation + translation)

$$\vec{y} = A\vec{x} + \vec{b}.$$

- With homogeneous coordinates:

$$\begin{bmatrix} \vec{y} \\ 1 \end{bmatrix} = \left[\begin{array}{ccc|c} & A & & \vec{b} \\ 0 & \dots & 0 & 1 \end{array} \right] \begin{bmatrix} \vec{x} \\ 1 \end{bmatrix}$$

- Setting the last coordinate = 1 and the last row of the matrix to $[0, \dots, 0, 1]$ results in translation of the point \vec{x} (via addition of translation vector \vec{b})
- The matrix above is a linear map, but because it is one dimension higher, it does not have to move the origin in the $(n+1)$ -dimensional space for translation

Homogeneous Coordinates (3)

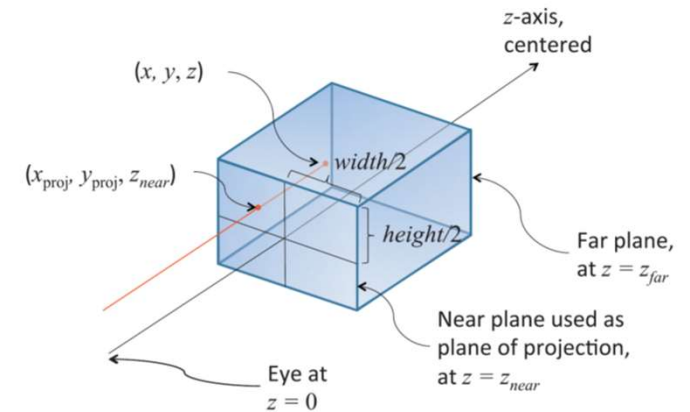


Examples of usage

- Projection (e.g., OpenGL projection matrices)

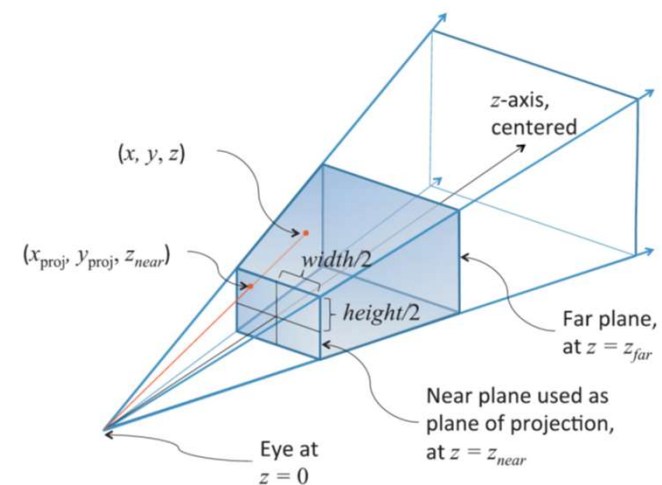
$$\begin{bmatrix} \frac{2}{\text{right} - \text{left}} & 0 & 0 & \frac{\text{right} + \text{left}}{\text{right} - \text{left}} \\ 0 & \frac{2}{\text{top} - \text{bottom}} & 0 & \frac{\text{top} + \text{bottom}}{\text{top} - \text{bottom}} \\ 0 & 0 & \frac{-2}{\text{far} - \text{near}} & \frac{\text{far} + \text{near}}{\text{far} - \text{near}} \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

orthographic



$$\begin{bmatrix} \frac{z_{\text{near}}}{\text{width}/2} & 0.0 & \frac{\text{left} + \text{right}}{\text{width}/2} & 0.0 \\ 0.0 & \frac{z_{\text{near}}}{\text{height}/2} & \frac{\text{top} + \text{bottom}}{\text{height}/2} & 0.0 \\ 0.0 & 0.0 & \frac{z_{\text{far}} + z_{\text{near}}}{z_{\text{far}} - z_{\text{near}}} & \frac{2z_{\text{far}}z_{\text{near}}}{z_{\text{far}} - z_{\text{near}}} \\ 0.0 & 0.0 & -1.0 & 0.0 \end{bmatrix}$$

perspective



Thank you.