



CS 247 – Scientific Visualization

Lecture 10: Scalar Field Visualization, Pt. 4

Markus Hadwiger, KAUST

Reading Assignment #6 (until Mar 8)



Read (required):

- Real-Time Volume Graphics, Chapter 2
(*GPU Programming*)
- Reminder: Real-Time Volume Graphics, Chapter 5.4

Read (optional):

- Paper:
Gregory M. Nielson and Bernd Hamann,
The Asymptotic Decider: Resolving the Ambiguity in Marching Cubes,
Visualization 1991
<https://dl.acm.org/doi/abs/10.5555/949607.949621>

Quiz #1: Mar 8



Organization

- First 30 min of lecture
- No material (book, notes, ...) allowed

Content of questions

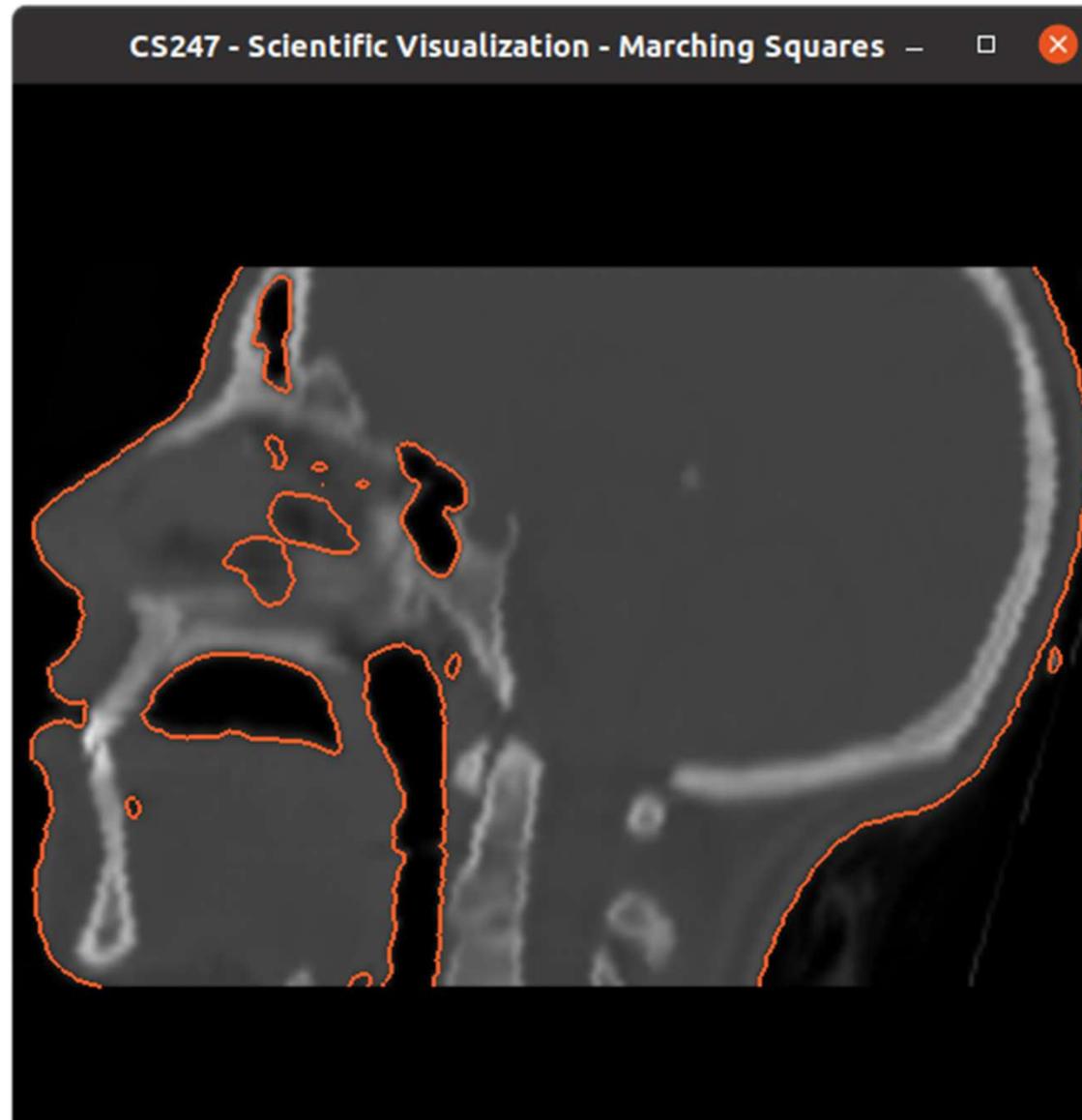
- Lectures (both actual lectures and slides)
- Reading assignments (except optional ones)
- Programming assignments (algorithms, methods)
- Solve short practical examples

Programming Assignments Schedule (tentative)



Assignment 0:	Lab sign-up: join discord, setup github account + get repo Basic OpenGL example	until	Feb 1
Assignment 1:	Volume slice viewer	until	Feb 15
Assignment 2:	Iso-contours (marching squares)	until	Mar 1
Assignment 3:	Iso-surface rendering (marching cubes)	until	Mar 15
Assignment 4:	Volume ray-casting, part 1	until	Apr 12
	Volume ray-casting, part 2	until	Apr 19
Assignment 5:	Flow vis, part 1 (hedgehog plots, streamlines, pathlines)	until	May 3
Assignment 6:	Flow vis, part 2 (LIC with color coding)	until	May 13

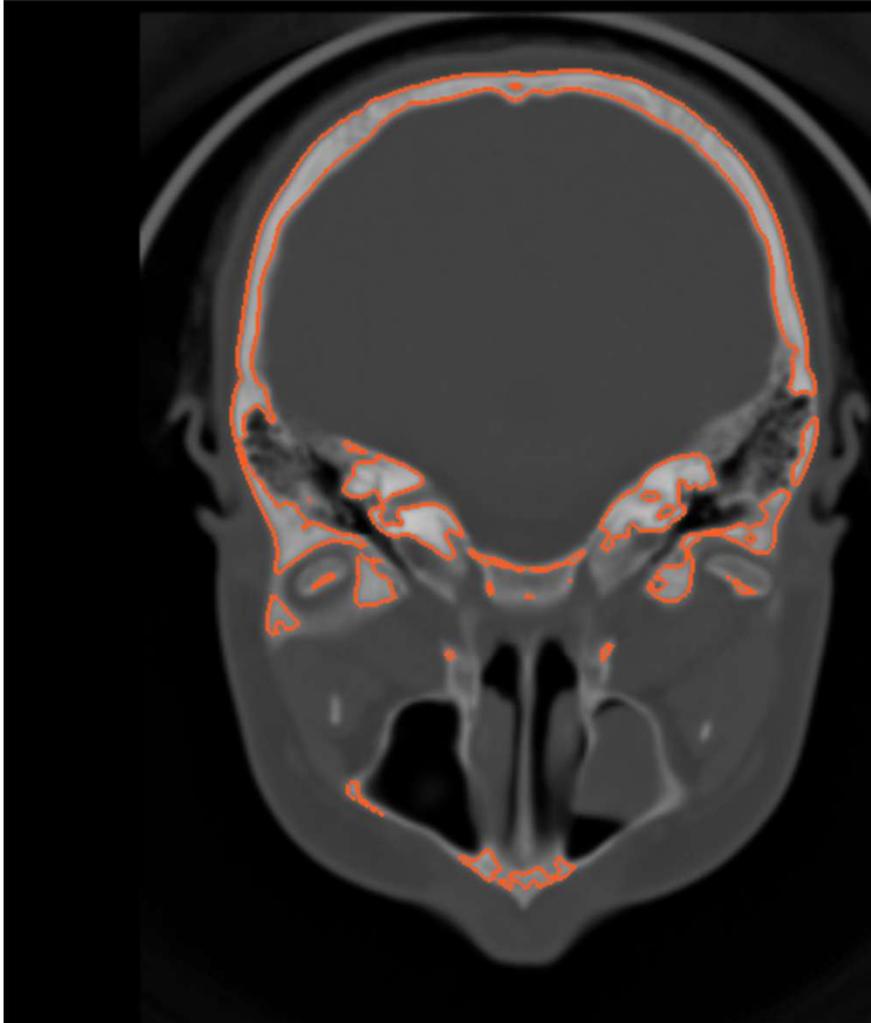
Programming Assignment 2



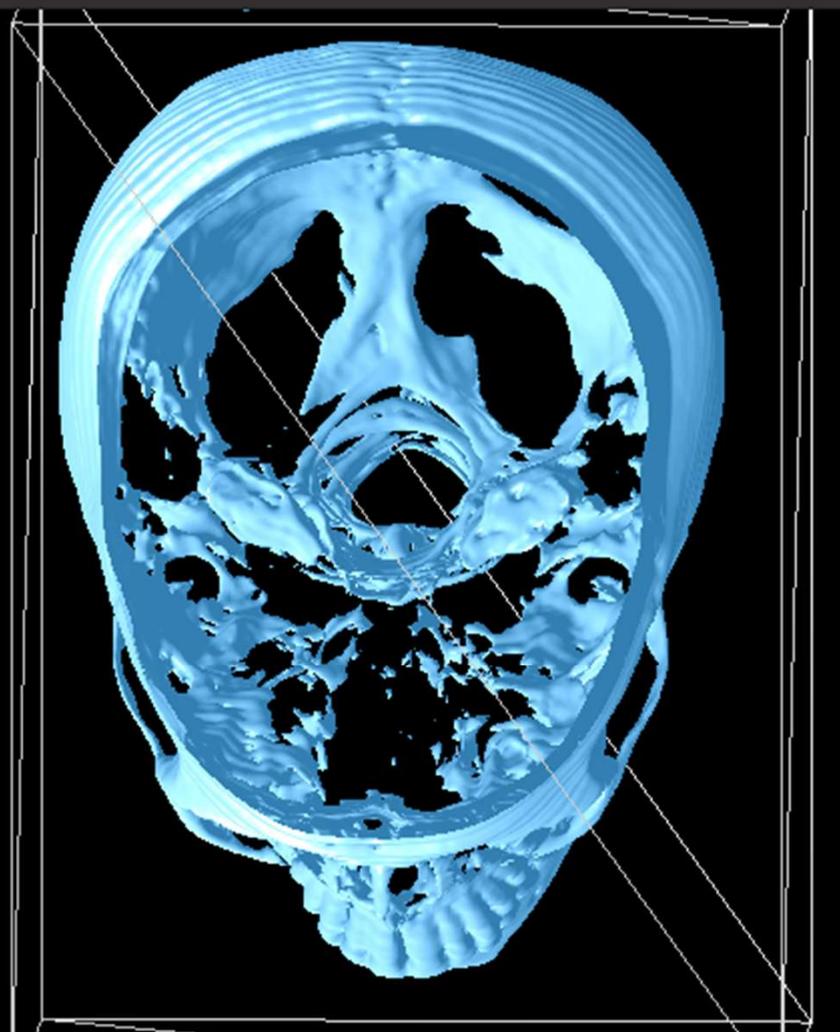
Programming Assignment 2 + 3



CS247 - Scientific Visualization - Marching Squares



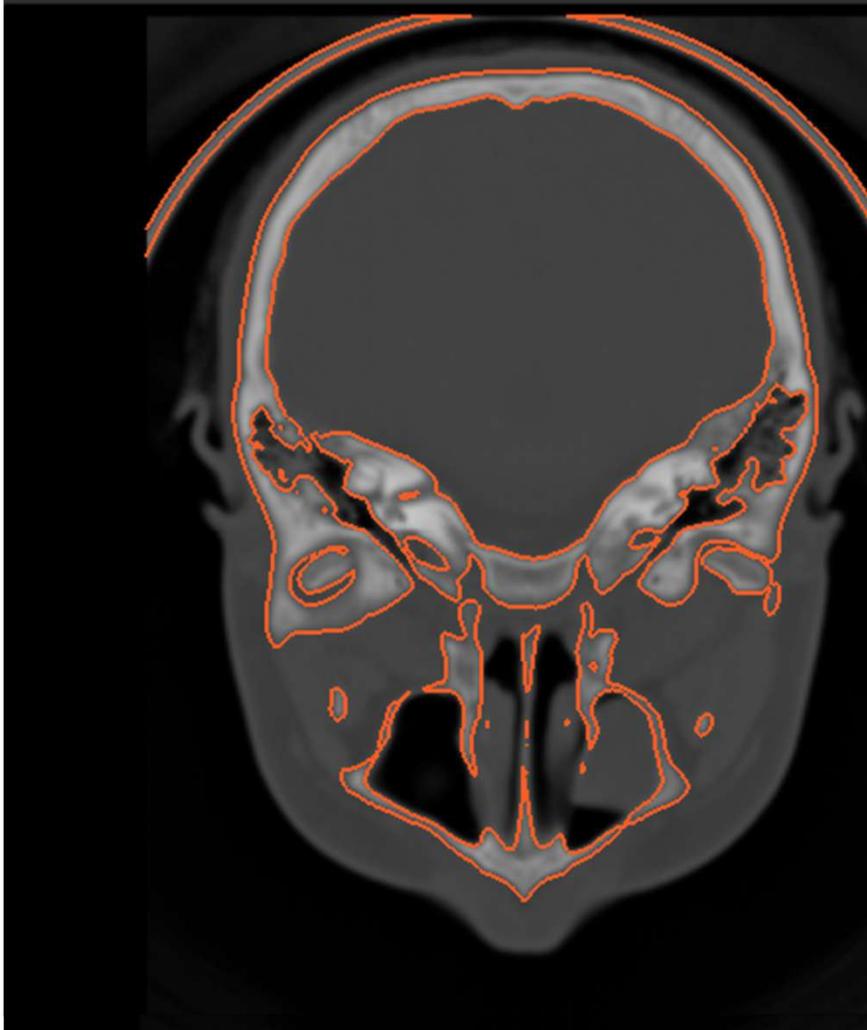
CS247 - Scientific Visualization - Marching Cubes



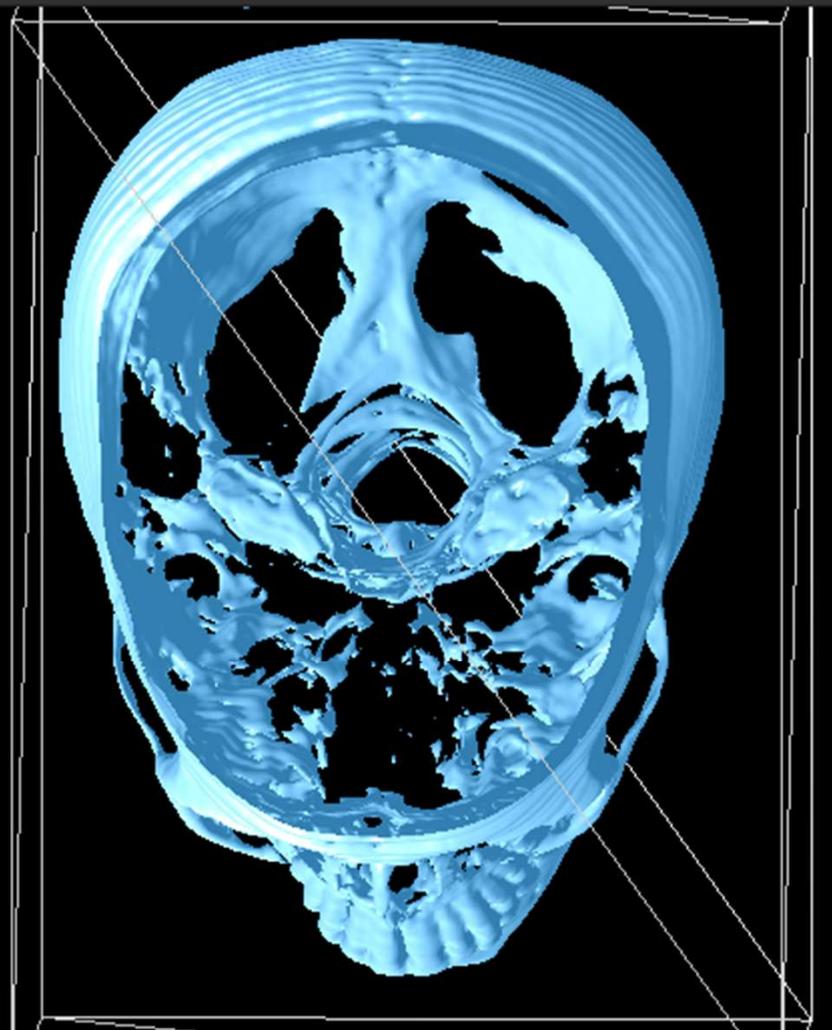
Programming Assignment 2 + 3



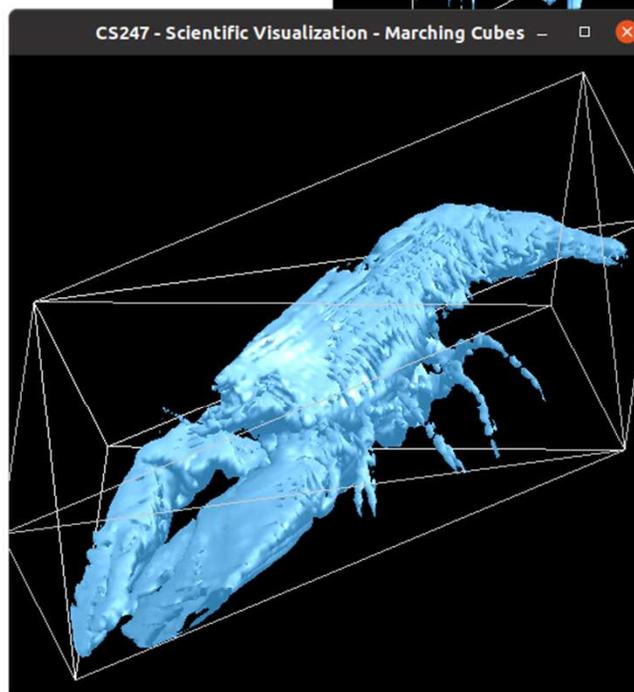
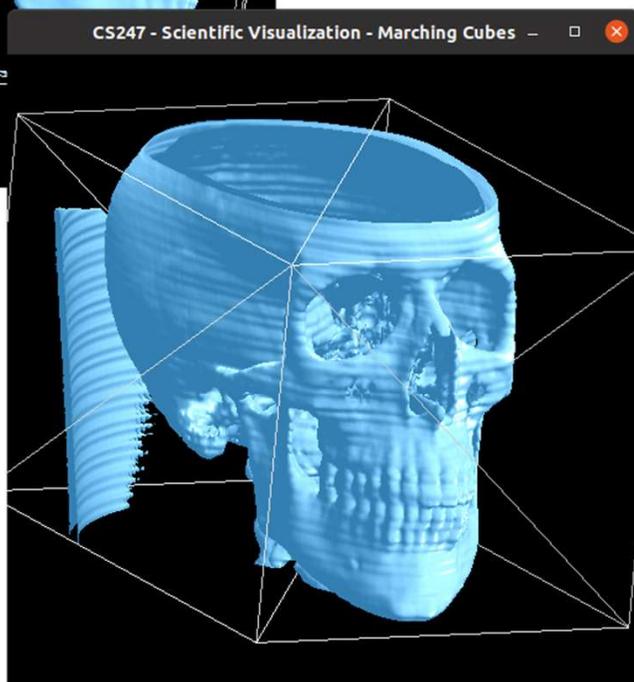
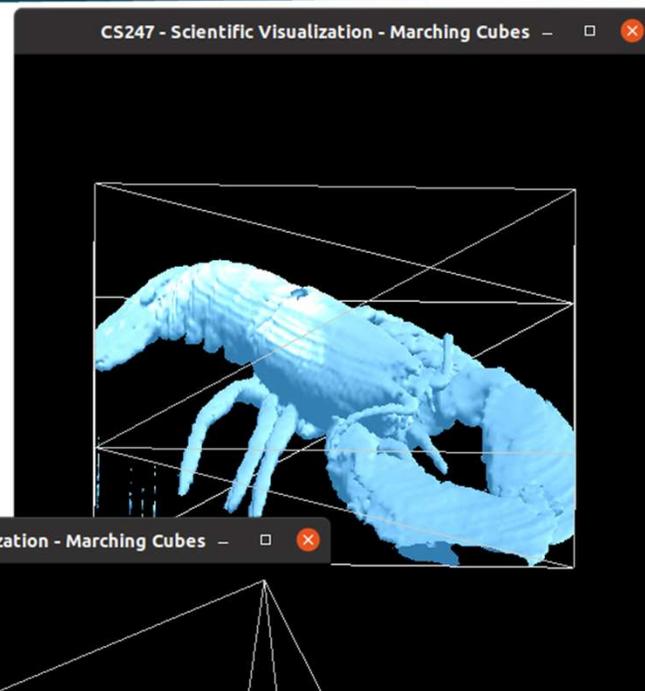
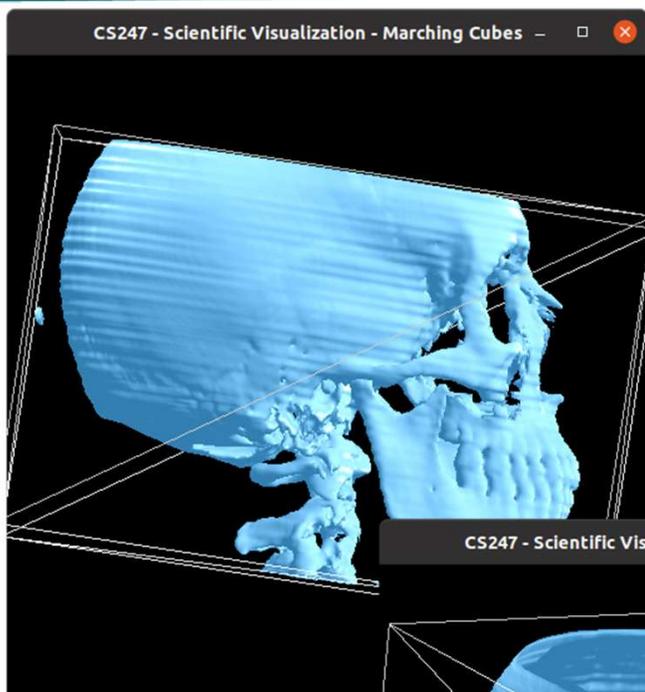
CS247 - Scientific Visualization - Marching Squares



CS247 - Scientific Visualization - Marching Cubes



Programming Assignment 3



Contours in a quadrangle cell

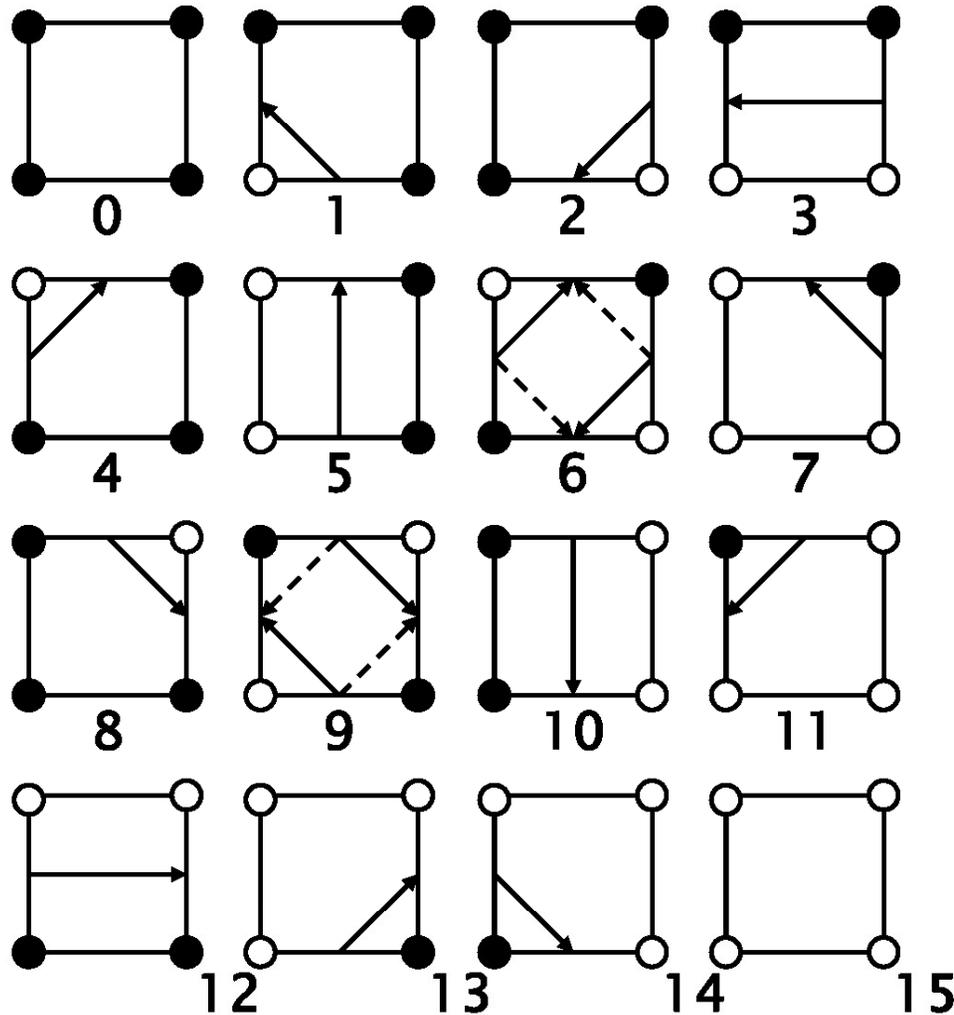
Basic contouring algorithms:

- **cell-by-cell** algorithms: simple structure, but generate disconnected segments, require post-processing
- **contour propagation** methods: more complicated, but generate connected contours

"Marching squares" algorithm (systematic cell-by-cell):

- process nodes in ccw order, denoted here as x_0, x_1, x_2, x_3
- compute at each node x_i the reduced field $\tilde{f}(x_i) = f(x_i) - (c - \varepsilon)$ (which is forced to be nonzero)
- take its sign as the i^{th} bit of a 4-bit integer
- use this as an index for lookup table containing the connectivity information:

Contours in a quadrangle cell



- $\tilde{f}(x_i) < 0$
- $\tilde{f}(x_i) > 0$

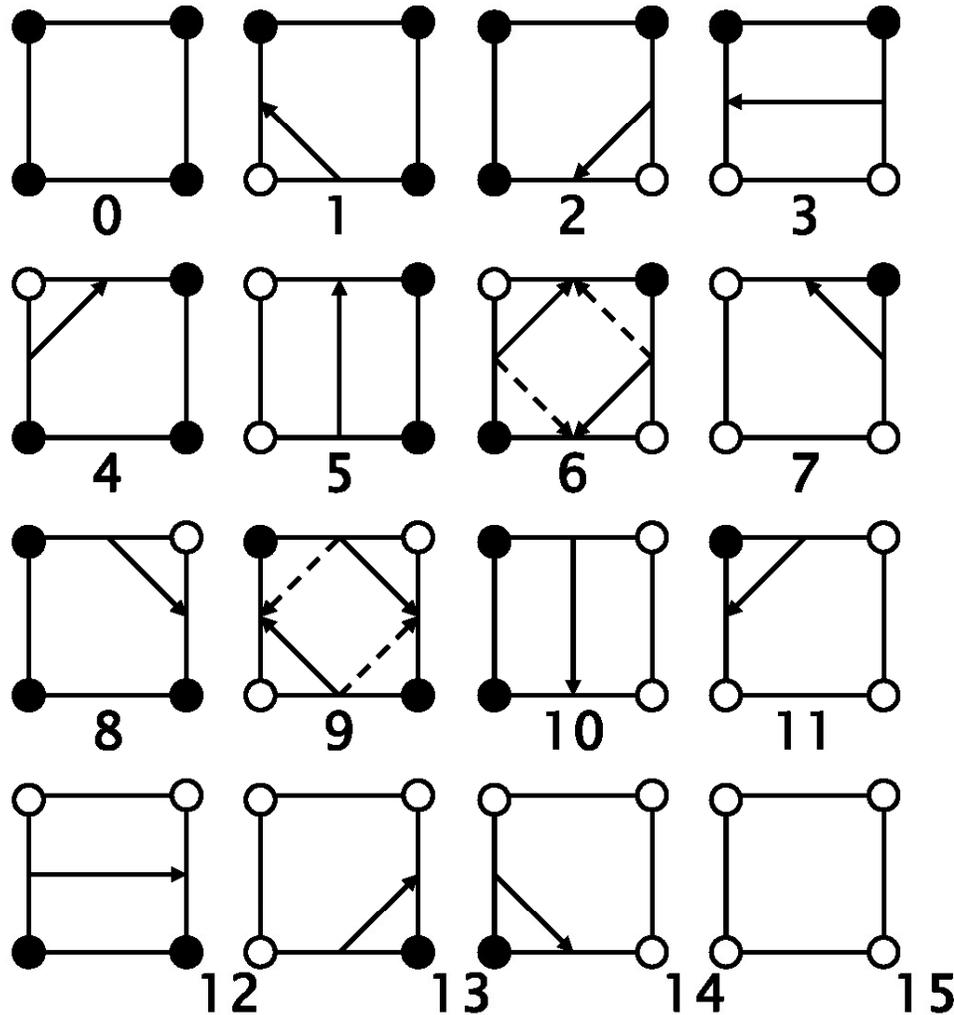
Alternating signs exist in cases 6 and 9.

Choose the solid or dashed line?

Both are possible for topological consistency.

This allows to have a fixed table of 16 cases.

Contours in a quadrangle cell



- $f(x_i) < c$
- $f(x_i) \geq c$

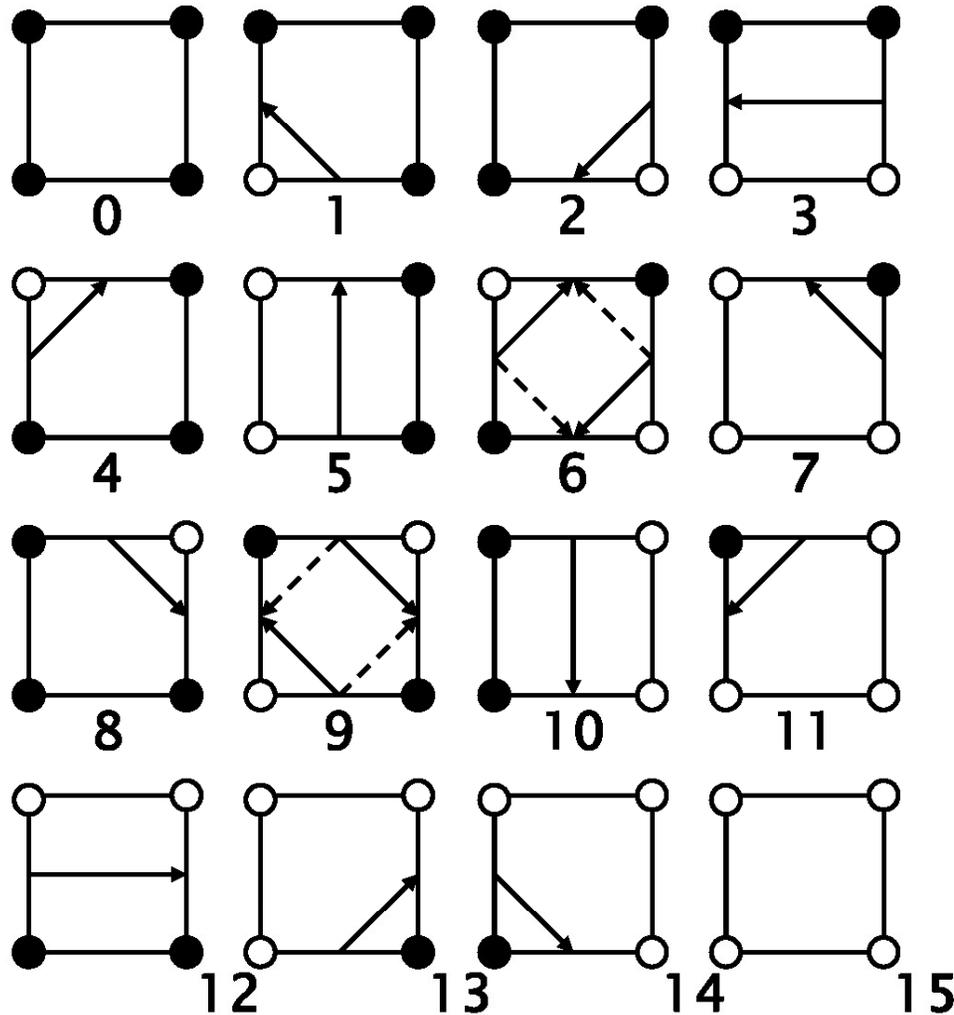
Alternating signs exist in cases 6 and 9.

Choose the solid or dashed line?

Both are possible for topological consistency.

This allows to have a fixed table of 16 cases.

Contours in a quadrangle cell



- $f(x_i) \leq c$
- $f(x_i) > c$

Alternating signs exist in cases 6 and 9.

Choose the solid or dashed line?

Both are possible for topological consistency.

This allows to have a fixed table of 16 cases.

Orientability (1-manifold embedded in 2D)

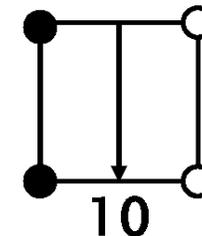
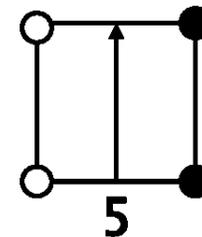


Orientability of 1-manifold:

Possible to assign consistent left/right orientation

Iso-contours

- Consistent side for scalar values...
 - greater than iso-value (e.g, *left* side)
 - less than iso-value (e.g., *right* side)
- Use consistent ordering of vertices (e.g., larger vertex index is “tip” of arrow; if (0,1) points “up”, “left” is left, ...)



not orientable



Möbius strip
(only one side!)

● $\tilde{f}(x_i) < 0$

○ $\tilde{f}(x_i) > 0$

Orientability (2-manifold embedded in 3D)

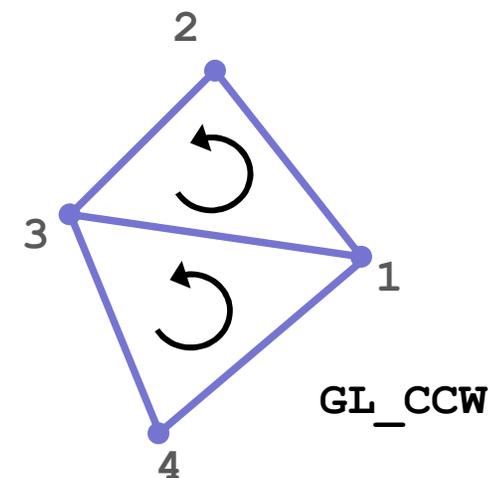


Orientability of 2-manifold:

Possible to assign consistent normal vector orientation

Triangle meshes

- Edges
 - Consistent ordering of vertices: CCW (counter-clockwise) or CW (clockwise) (e.g., (3,1,2) on one side of edge, (1,3,4) on the other side)
- Triangles
 - Consistent front side vs. back side
 - Normal vector; or ordering of vertices (CCW/CW)
 - See also: “right-hand rule”



not orientable



Möbius strip
(only one side!)

Topological consistency

To avoid degeneracies, use **symbolic perturbations**:

If level c is found as a node value, set the level to $c-\varepsilon$ where ε is a symbolic infinitesimal.

Then:

- contours intersect edges at some (possibly infinitesimal) distance from end points
- flat regions can be visualized by pair of contours at $c-\varepsilon$ and $c+\varepsilon$
- contours are **topologically consistent**, meaning:

Contours are **closed, orientable, nonintersecting lines**.

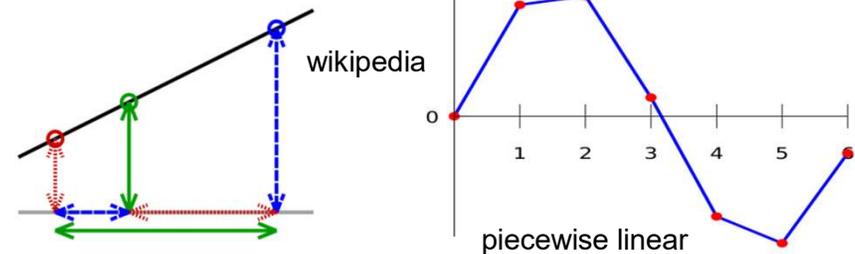
(except where the
boundary is hit)

Linear Interpolation / Convex Combinations



Linear interpolation in 1D:

$$f(\alpha) = (1 - \alpha)v_1 + \alpha v_2$$



Line embedded in 2D (linear interpolation of vertex coordinates/attributes):

$$f(\alpha_1, \alpha_2) = \alpha_1 v_1 + \alpha_2 v_2$$

$$\alpha_1 + \alpha_2 = 1$$

$$f(\alpha) = v_1 + \alpha(v_2 - v_1)$$

$$\alpha = \alpha_2$$

Line segment: $\alpha_1, \alpha_2 \geq 0$ (\rightarrow convex combination)

Compare to line parameterization
with parameter t :

$$v(t) = v_1 + t(v_2 - v_1)$$

Linear Interpolation / Convex Combinations



Linear combination (n -dim. space):

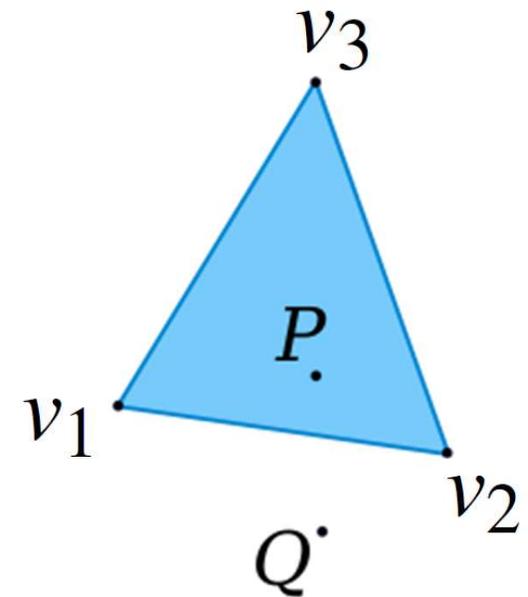
$$\alpha_1 v_1 + \alpha_2 v_2 + \dots + \alpha_n v_n = \sum_{i=1}^n \alpha_i v_i$$

Affine combination: Restrict to $(n - 1)$ -dim. subspace:

$$\alpha_1 + \alpha_2 + \dots + \alpha_n = \sum_{i=1}^n \alpha_i = 1$$

Convex combination: $\alpha_i \geq 0$

(restrict to simplex in subspace)



Linear Interpolation / Convex Combinations



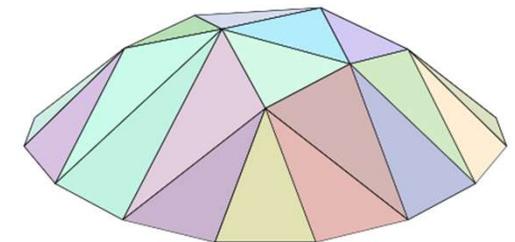
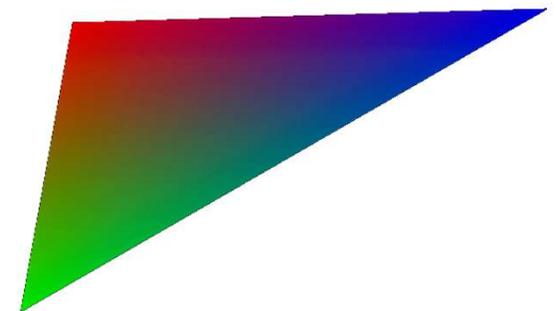
The weights α_i are the n normalized **barycentric** coordinates

→ linear attribute interpolation in simplex

$$\alpha_1 v_1 + \alpha_2 v_2 + \dots + \alpha_n v_n = \sum_{i=1}^n \alpha_i v_i$$

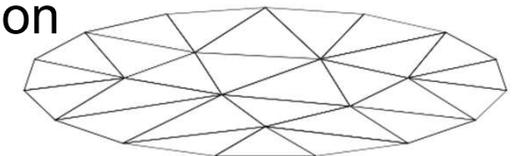
$$\alpha_1 + \alpha_2 + \dots + \alpha_n = \sum_{i=1}^n \alpha_i = 1$$
$$\alpha_i \geq 0$$

attribute interpolation



spatial position
interpolation

wikipedia



Linear Interpolation / Convex Combinations

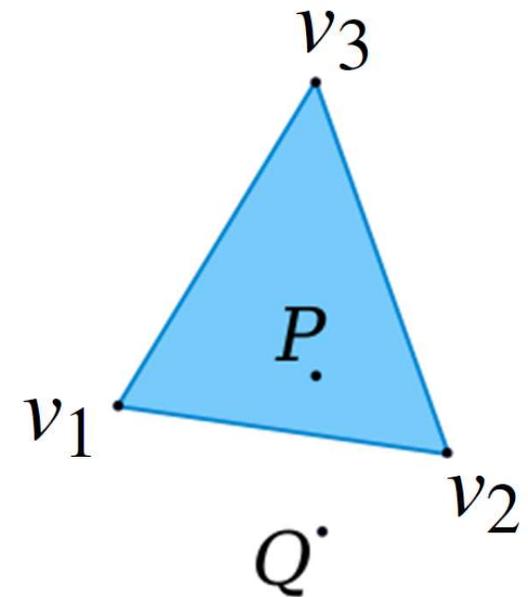


$$\alpha_1 v_1 + \alpha_2 v_2 + \dots + \alpha_n v_n = \sum_{i=1}^n \alpha_i v_i$$

$$\alpha_1 + \alpha_2 + \dots + \alpha_n = \sum_{i=1}^n \alpha_i = 1$$

Can re-parameterize to get $(n - 1)$ **affine** coordinates:

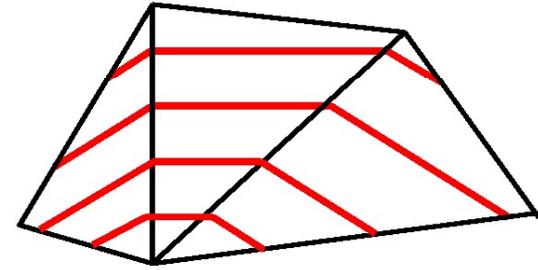
$$\begin{aligned} \alpha_1 v_1 + \alpha_2 v_2 + \alpha_3 v_3 &= \\ \tilde{\alpha}_1 (v_2 - v_1) + \tilde{\alpha}_2 (v_3 - v_1) + v_1 & \\ \tilde{\alpha}_1 &= \alpha_2 \\ \tilde{\alpha}_2 &= \alpha_3 \end{aligned}$$



Contours in triangle/tetrahedral cells

Linear interpolation of cells implies piece-wise linear contours.

Contours are unambiguous, making "marching triangles" even simpler than "marching squares".

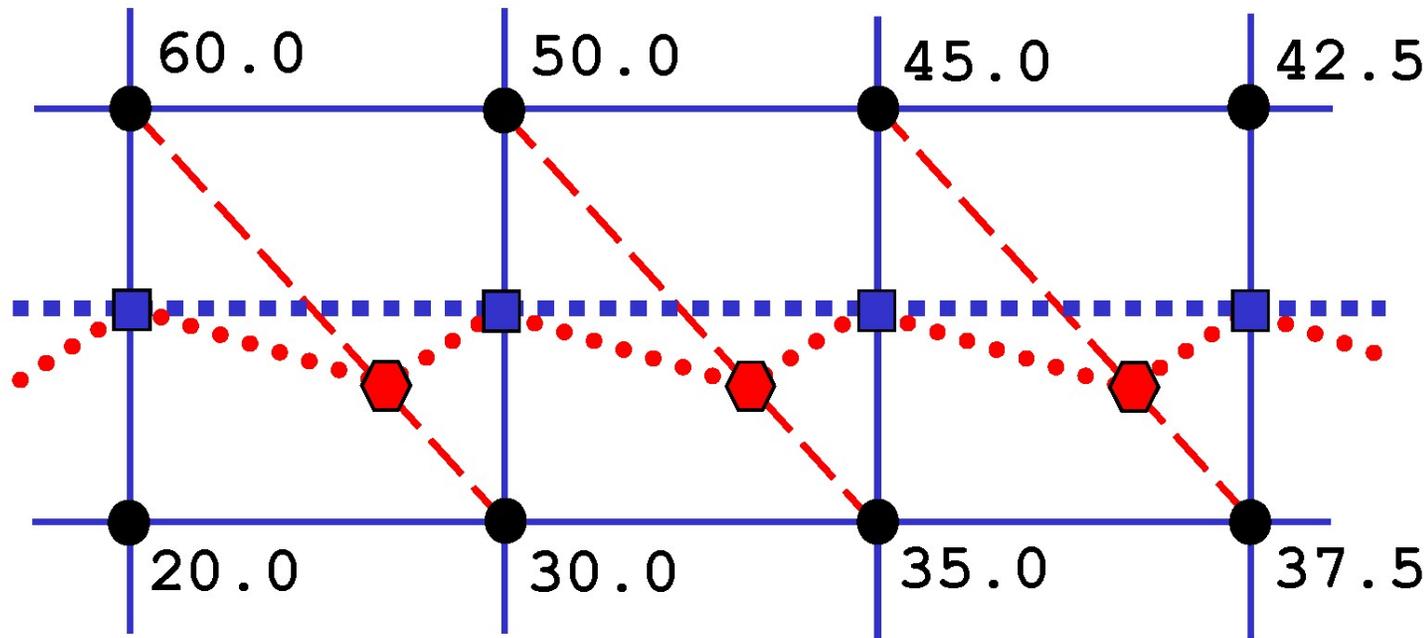


Question: Why not split quadrangles into two triangles (and hexahedra into five or six tetrahedra) and use marching triangles (tetrahedra)?

Answer: This can introduce periodic artifacts!

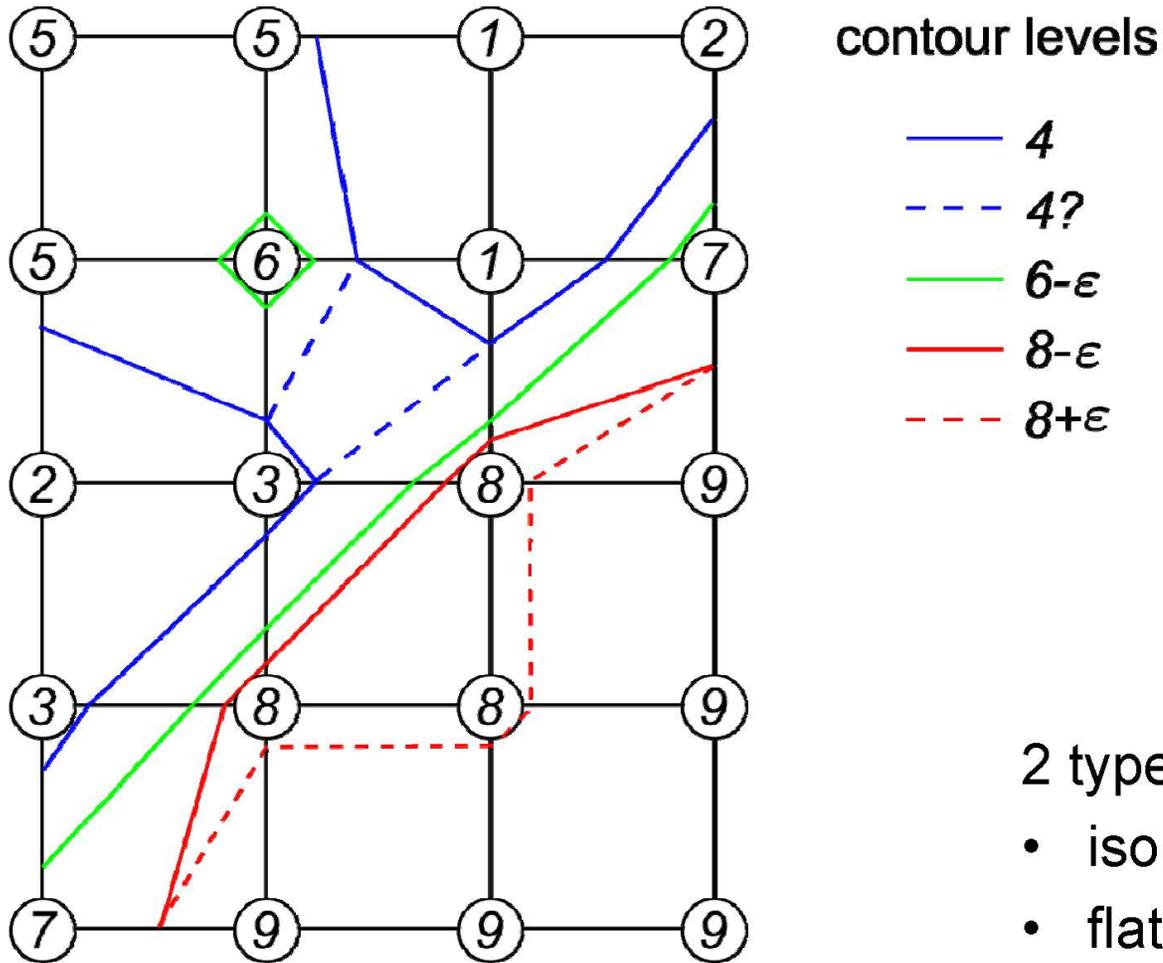
Contours in triangle/tetrahedral cells

Illustrative example: Find contour at level $c=40.0$!



- original quad grid, yielding vertices ■ and contour - - - - -
- - - triangulated grid, yielding vertices ⬡ and contour

Example

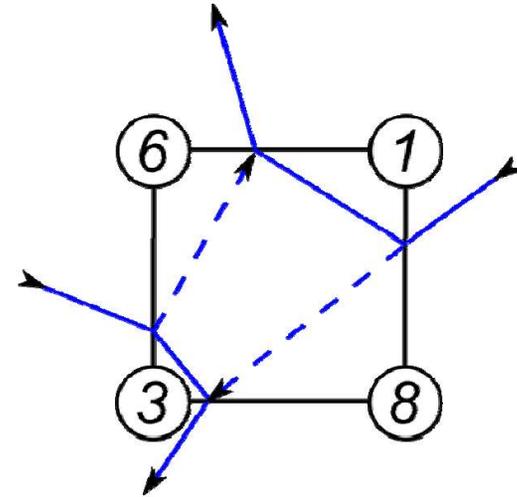


Ambiguities of contours

What is the **correct** contour of $c=4$?

Two possibilities, both are orientable:

- connect high values ————
- connect low values - - - - -



Answer: correctness depends on interior values of $f(x)$.

But: different interpolation schemes are possible.

Better question: What is the correct contour with respect to bilinear interpolation?

Bi-Linear Interpolation



Consider area between 2x2 adjacent samples (e.g., pixel centers):

Given any (fractional) position

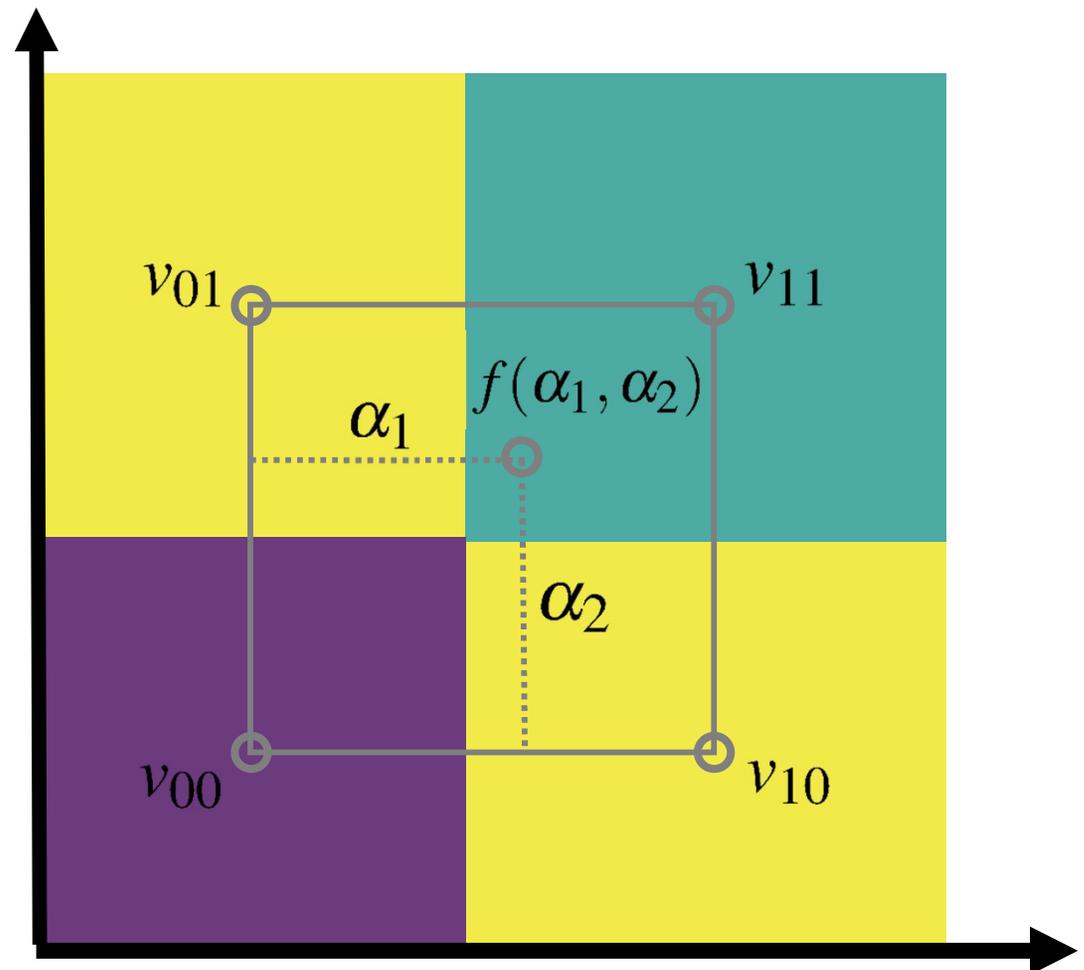
$$\alpha_1 := x_1 - \lfloor x_1 \rfloor \quad \alpha_1 \in [0.0, 1.0)$$

$$\alpha_2 := x_2 - \lfloor x_2 \rfloor \quad \alpha_2 \in [0.0, 1.0)$$

and 2x2 sample values

$$\begin{bmatrix} v_{01} & v_{11} \\ v_{00} & v_{10} \end{bmatrix}$$

Compute: $f(\alpha_1, \alpha_2)$



Bi-Linear Interpolation



Consider area between 2x2 adjacent samples (e.g., pixel centers):

Given any (fractional) position

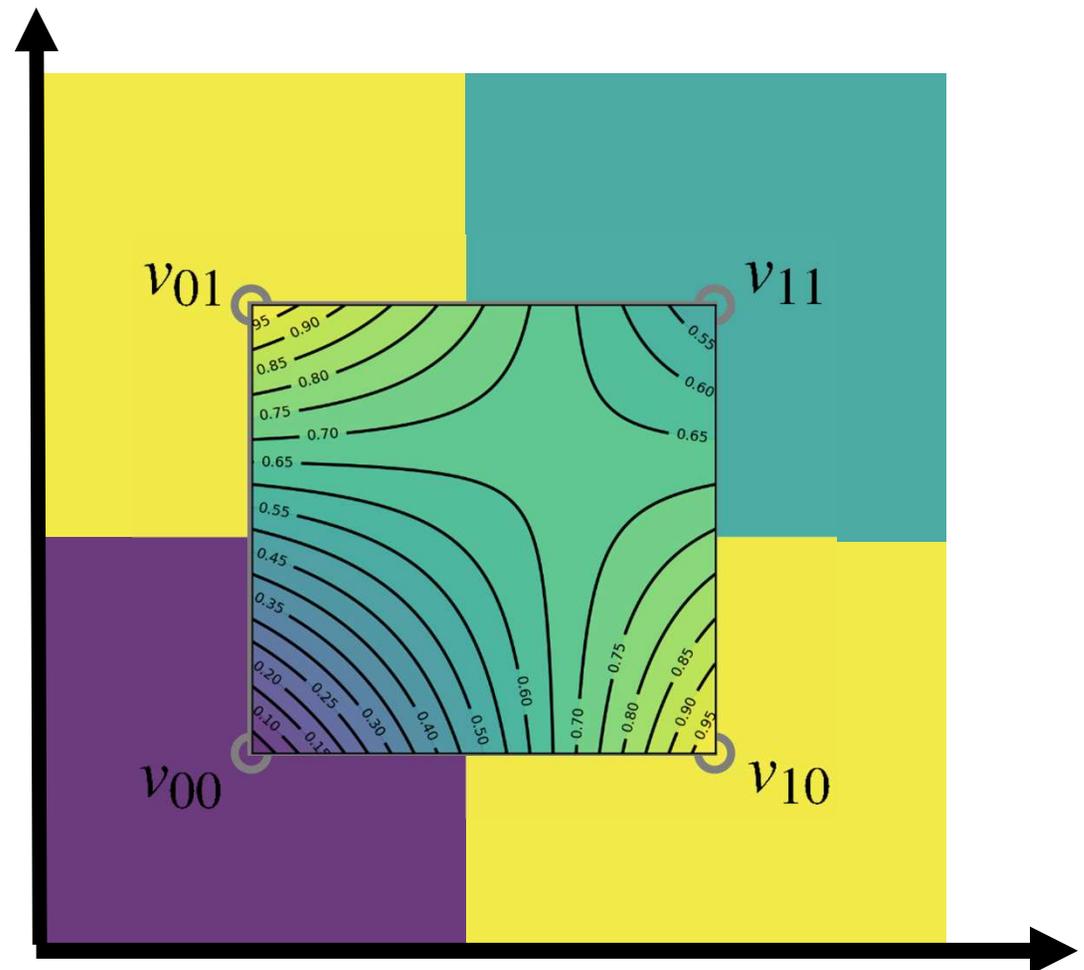
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and 2x2 sample values

$$\begin{bmatrix} v_{01} & v_{11} \\ v_{00} & v_{10} \end{bmatrix}$$

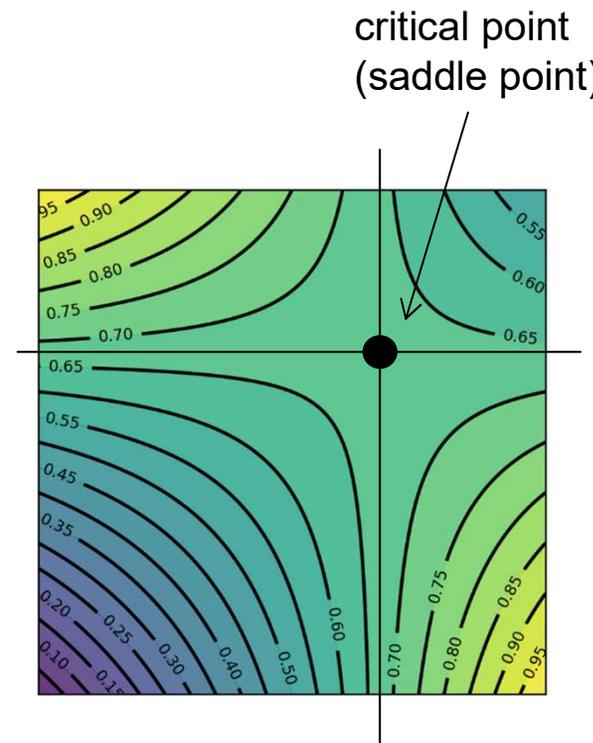
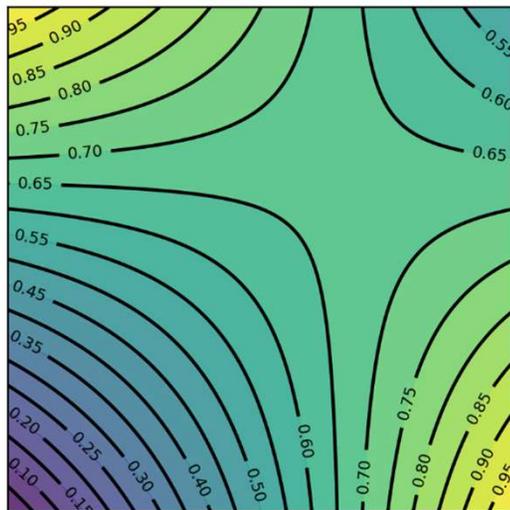
Compute: $f(\alpha_1, \alpha_2)$



Bi-Linear Interpolation: Critical Points



Critical points are where the gradient vanishes (i.e., is the zero vector)



here, the critical value is $2/3=0.666\dots$

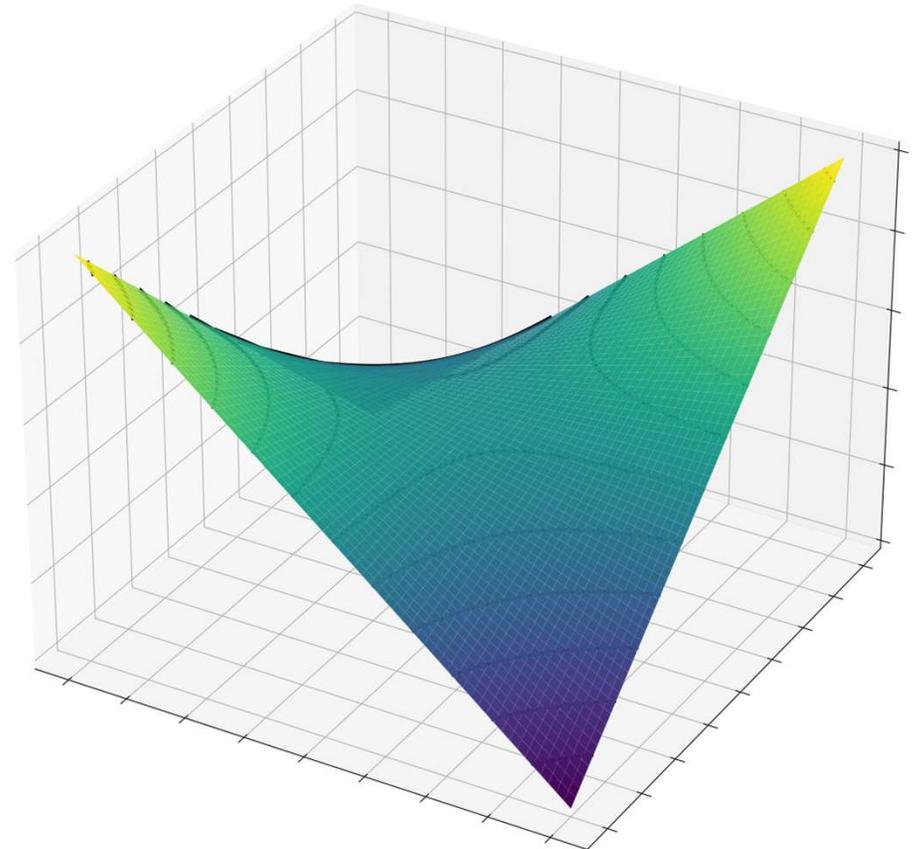
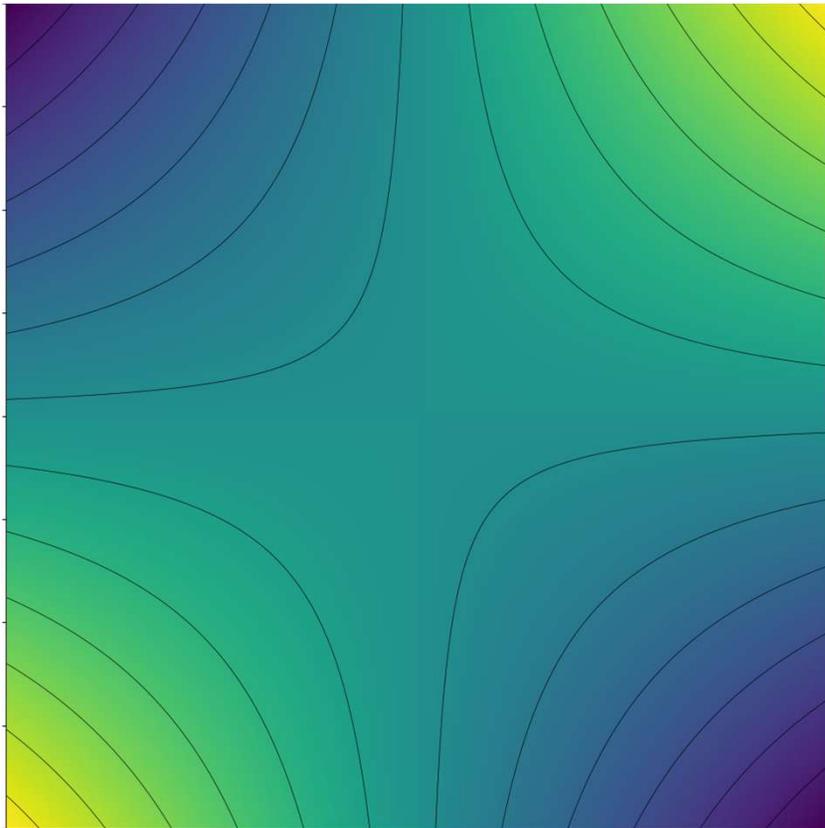
“Asymptotic decider”: resolve ambiguous configurations (6 and 9) by comparing specific iso-value with critical value (scalar value at critical point)

Bi-Linear Interpolation



Consider area between 2x2 adjacent samples (e.g., pixel centers)

Example #1: 1 at bottom-left and top-right, 0 at top-left and bottom-right

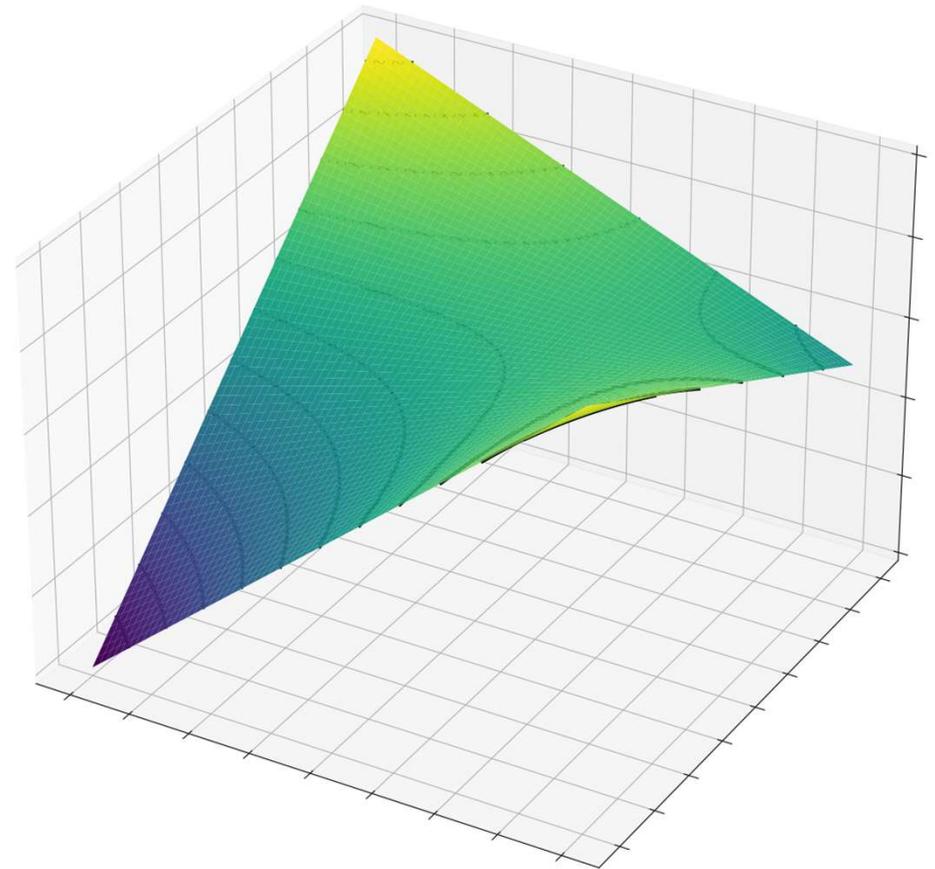
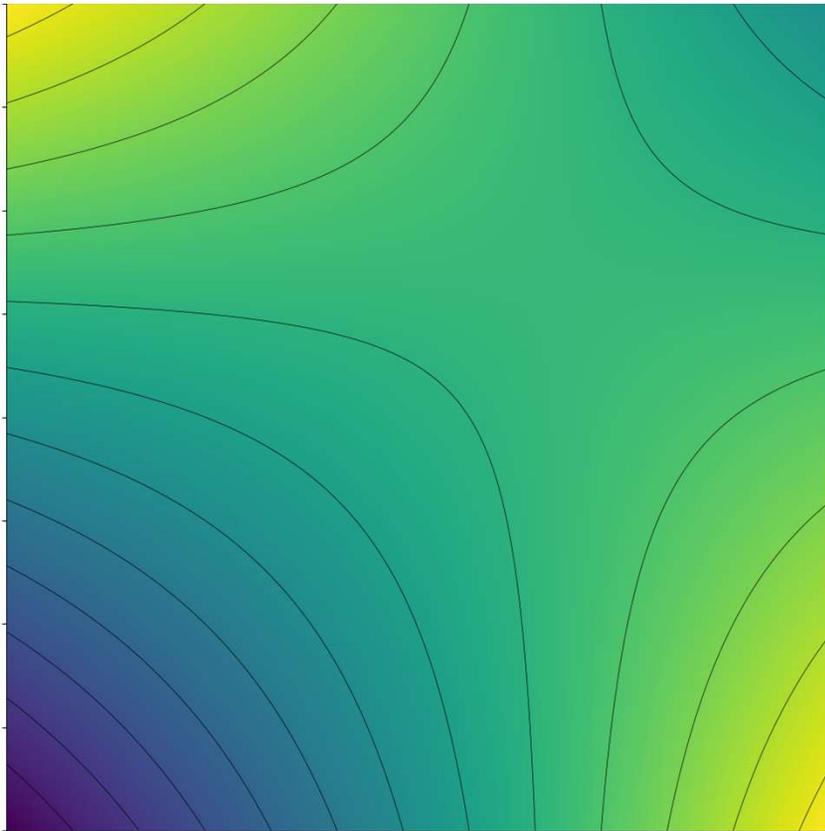


Bi-Linear Interpolation



Consider area between 2x2 adjacent samples (e.g., pixel centers)

Example #2: 1 at top-left and bottom-right, 0 at bottom-left, 0.5 at top-right



Bi-Linear Interpolation



Interpolate function at (fractional) position (α_1, α_2) :

$$\begin{aligned} f(\alpha_1, \alpha_2) &= \begin{bmatrix} \alpha_2 & (1 - \alpha_2) \end{bmatrix} \begin{bmatrix} v_{01} & v_{11} \\ v_{00} & v_{10} \end{bmatrix} \begin{bmatrix} (1 - \alpha_1) \\ \alpha_1 \end{bmatrix} \\ &= (1 - \alpha_1)(1 - \alpha_2)v_{00} + \alpha_1(1 - \alpha_2)v_{10} + (1 - \alpha_1)\alpha_2v_{01} + \alpha_1\alpha_2v_{11} \\ &= v_{00} + \alpha_1(v_{10} - v_{00}) + \alpha_2(v_{01} - v_{00}) + \alpha_1\alpha_2(v_{00} + v_{11} - v_{10} - v_{01}) \end{aligned}$$

Bi-Linear Interpolation: Contours

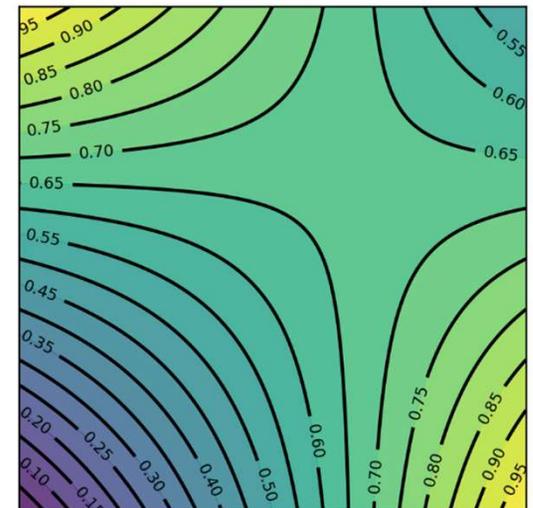


Find one specific iso-contour (can of course do this for any/all isovalues):

$$f(\alpha_1, \alpha_2) = c$$

Find all (α_1, α_2) where:

$$v_{00} + \alpha_1(v_{10} - v_{00}) + \alpha_2(v_{01} - v_{00}) + \alpha_1\alpha_2(v_{00} + v_{11} - v_{10} - v_{01}) = c$$



Bi-Linear Interpolation: Critical Points



Compute gradient (critical points are where gradient is zero vector):

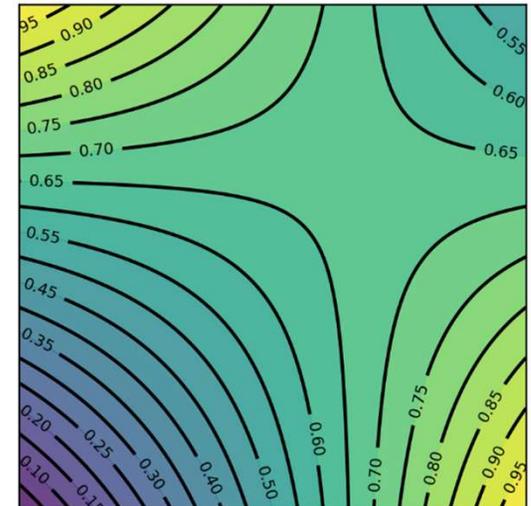
$$\frac{\partial f(\alpha_1, \alpha_2)}{\partial \alpha_1} = (v_{10} - v_{00}) + \alpha_2(v_{00} + v_{11} - v_{10} - v_{01})$$

$$\frac{\partial f(\alpha_1, \alpha_2)}{\partial \alpha_2} = (v_{01} - v_{00}) + \alpha_1(v_{00} + v_{11} - v_{10} - v_{01})$$

Where are lines of constant value / critical points?

$$\frac{\partial f(\alpha_1, \alpha_2)}{\partial \alpha_1} = 0 : \quad \alpha_2 = \frac{v_{00} - v_{10}}{v_{00} + v_{11} - v_{10} - v_{01}}$$

$$\frac{\partial f(\alpha_1, \alpha_2)}{\partial \alpha_2} = 0 : \quad \alpha_1 = \frac{v_{00} - v_{01}}{v_{00} + v_{11} - v_{10} - v_{01}}$$



Bi-Linear Interpolation: Critical Points



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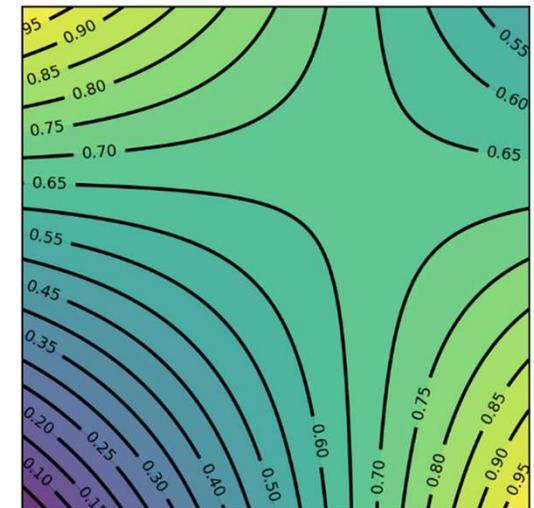
$$\frac{\partial f(\alpha_1, \alpha_2)}{\partial \alpha_1} = (v_{10} - v_{00}) + \alpha_2(v_{00} + v_{11} - v_{10} - v_{01})$$

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Where are lines of constant value / critical points?

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$$\frac{\partial f(\alpha_1, \alpha_2)}{\partial \alpha_2} = 0 : \quad \alpha_1 = \frac{v_{00} - v_{01}}{v_{00} + v_{11} - v_{10} - v_{01}}$$



if denominator is zero, bi-linear interpolation has degenerated to linear interpolation (or const)! (also means: no isolated critical points!)

Bi-Linear Interpolation: Critical Points

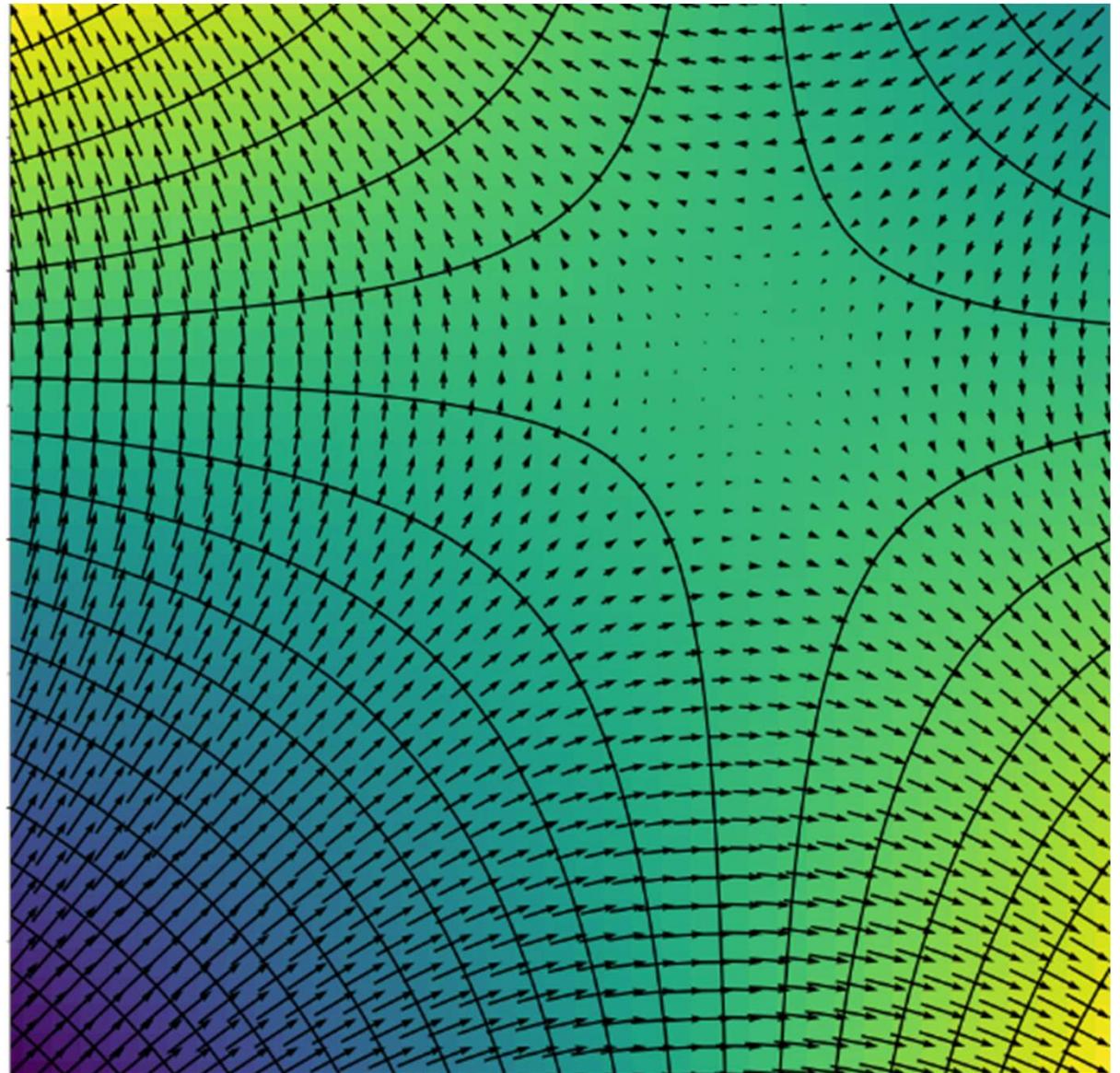


Compute gradient

Note that isolines are farther apart where gradient is smaller

Note the horizontal and vertical lines where gradient becomes vertical/horizontal

Note the critical point



Bi-Linear Interpolation: Critical Points

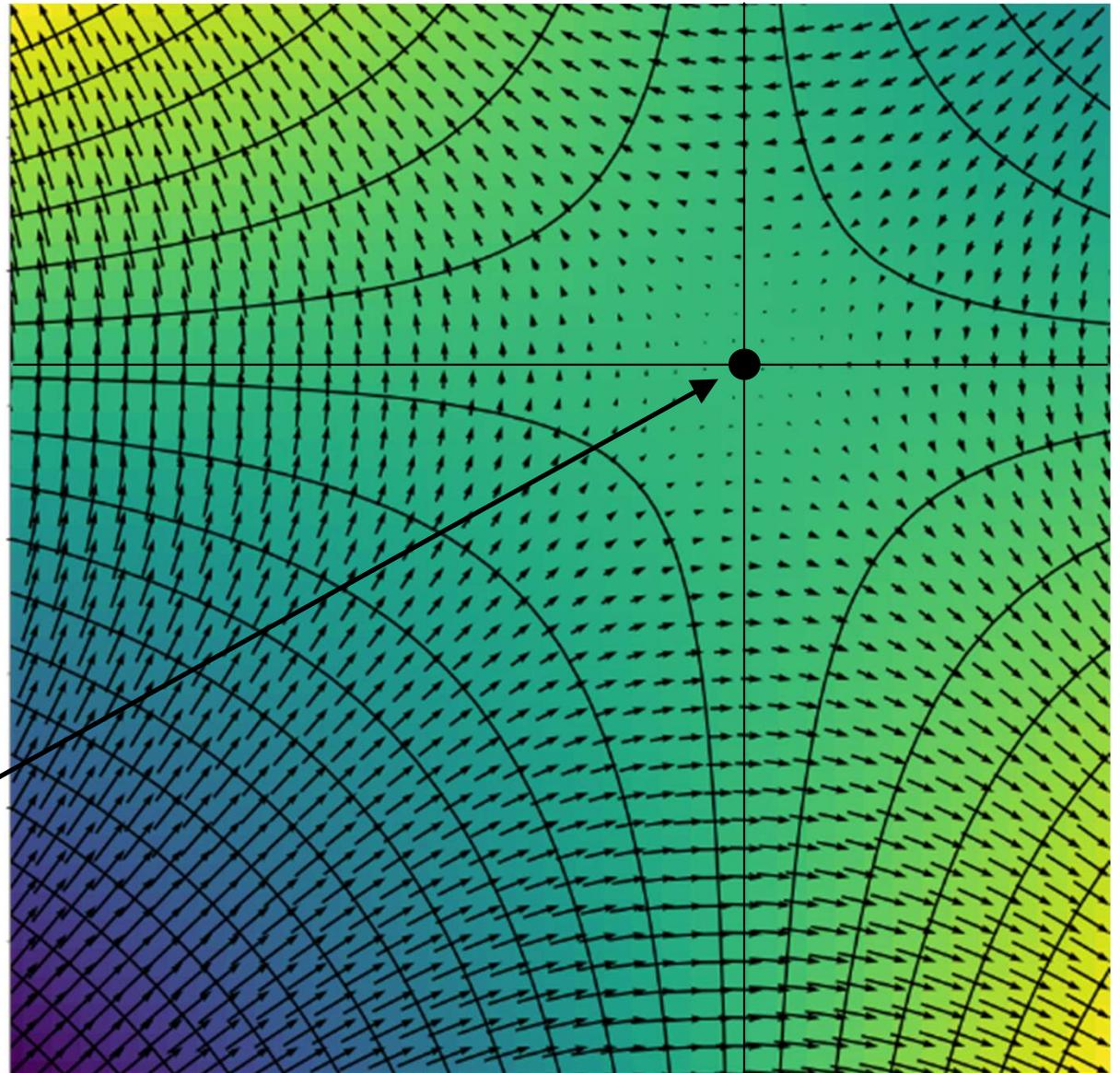


Compute gradient

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Note the horizontal and vertical lines where gradient becomes vertical/horizontal

Note the critical point



Bi-Linear Interpolation: Critical Points



Examine Hessian matrix at critical point (non-degenerate critical p.?, ...)

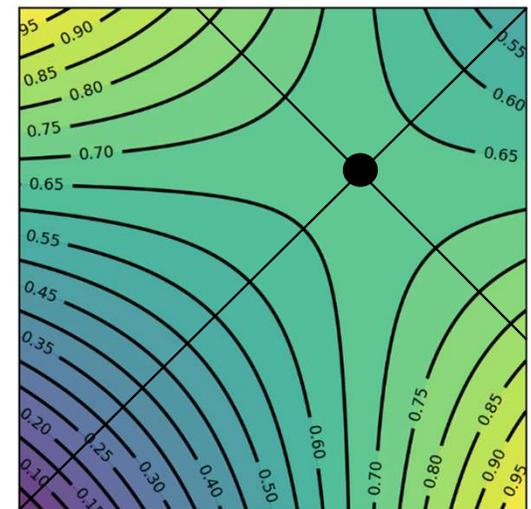
$$\begin{bmatrix} \frac{\partial^2 f}{\partial \alpha_1^2} & \frac{\partial^2 f}{\partial \alpha_1 \partial \alpha_2} \\ \frac{\partial^2 f}{\partial \alpha_2 \partial \alpha_1} & \frac{\partial^2 f}{\partial \alpha_2^2} \end{bmatrix} = \begin{bmatrix} 0 & a \\ a & 0 \end{bmatrix} \quad a = v_{00} + v_{11} - v_{10} - v_{01}$$

Eigenvalues and eigenvectors (Hessian is symmetric: always real)

$$\lambda_1 = -a \text{ and } \lambda_2 = a$$

$$v_1 = \begin{bmatrix} -1 \\ 1 \end{bmatrix}, v_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

(here also: principal curvature magnitudes and directions of this function's graph == surface embedded in 3D)



Bi-Linear Interpolation: Critical Points



Examine Hessian matrix at critical point (non-degenerate critical p.?, ...)

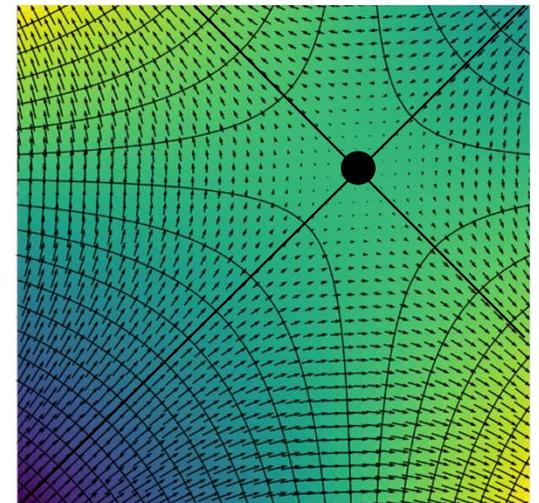
$$\begin{bmatrix} \frac{\partial^2 f}{\partial \alpha_1^2} & \frac{\partial^2 f}{\partial \alpha_1 \partial \alpha_2} \\ \frac{\partial^2 f}{\partial \alpha_2 \partial \alpha_1} & \frac{\partial^2 f}{\partial \alpha_2^2} \end{bmatrix} = \begin{bmatrix} 0 & a \\ a & 0 \end{bmatrix} \quad a = v_{00} + v_{11} - v_{10} - v_{01}$$

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Bi-Linear Interpolation: Critical Points



Examine Hessian matrix at critical point (non-degenerate critical p.?, ...)

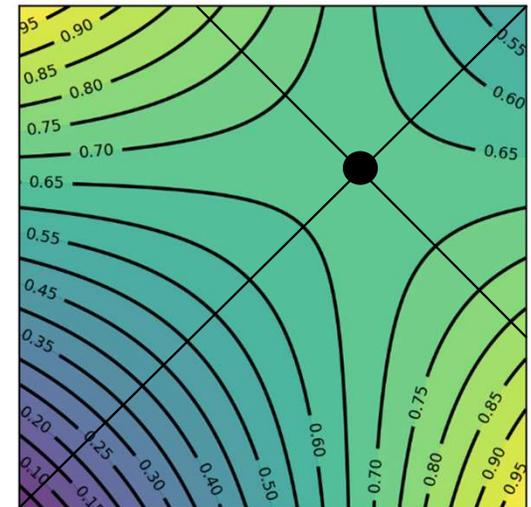
$$\begin{bmatrix} \frac{\partial^2 f}{\partial \alpha_1^2} & \frac{\partial^2 f}{\partial \alpha_1 \partial \alpha_2} \\ \frac{\partial^2 f}{\partial \alpha_2 \partial \alpha_1} & \frac{\partial^2 f}{\partial \alpha_2^2} \end{bmatrix} = \begin{bmatrix} 0 & a \\ a & 0 \end{bmatrix} \quad a = v_{00} + v_{11} - v_{10} - v_{01}$$

Eigenvalues and eigenvectors (Hessian is symmetric: always real)

$$\lambda_1 = -a \text{ and } \lambda_2 = a$$

$$v_1 = \begin{bmatrix} -1 \\ 1 \end{bmatrix}, v_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

degenerate means determinant = 0 (at least one eigenvalue = 0);
bi-linear is simple: $a = 0$ means degenerated to
linear anyway: no critical point at all! (except constant function)
(but with more than one cell: can have max or min at vertices)



Interlude: Implicit Function Theorem



When can I write an implicit function in \mathbb{R}^{n+m} such that it is the graph of a function $f: \mathbb{R}^n \rightarrow \mathbb{R}^m$ *at least locally*?

That is: is this implicitly described function an n -manifold embedded in \mathbb{R}^{n+m} ? (with local coordinates in \mathbb{R}^n)

$$G(f) := \{(x, f(x)) \mid x \in \mathbb{R}^n\} \subset \mathbb{R}^n \times \mathbb{R}^m \simeq \mathbb{R}^{n+m}$$

Theorem: if $m \times m$ Jacobian matrix is invertible
(easier for scalar field: check if gradient of f is non-zero)

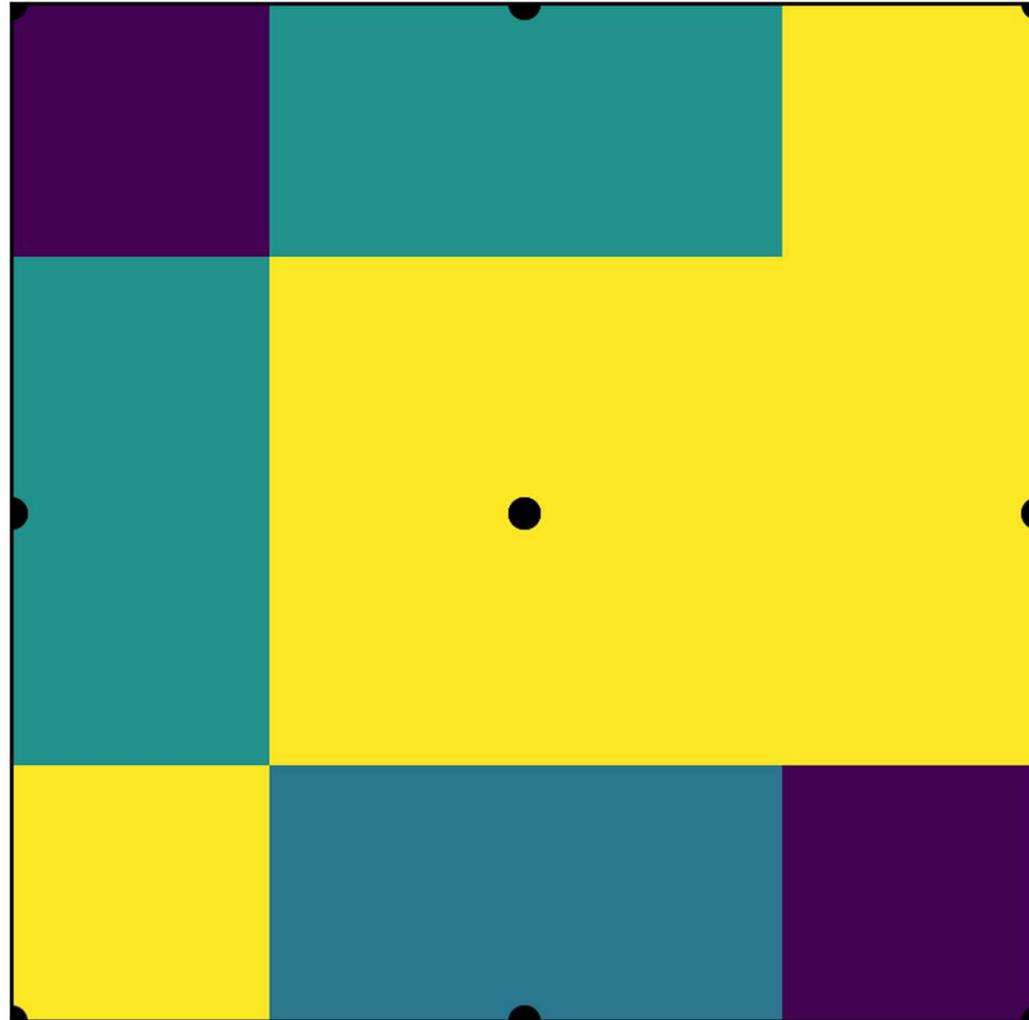
See https://en.wikipedia.org/wiki/Implicit_function_theorem

General result: *constant rank theorem*

Bi-Linear Interpolation: Comparisons



nearest-neighbor

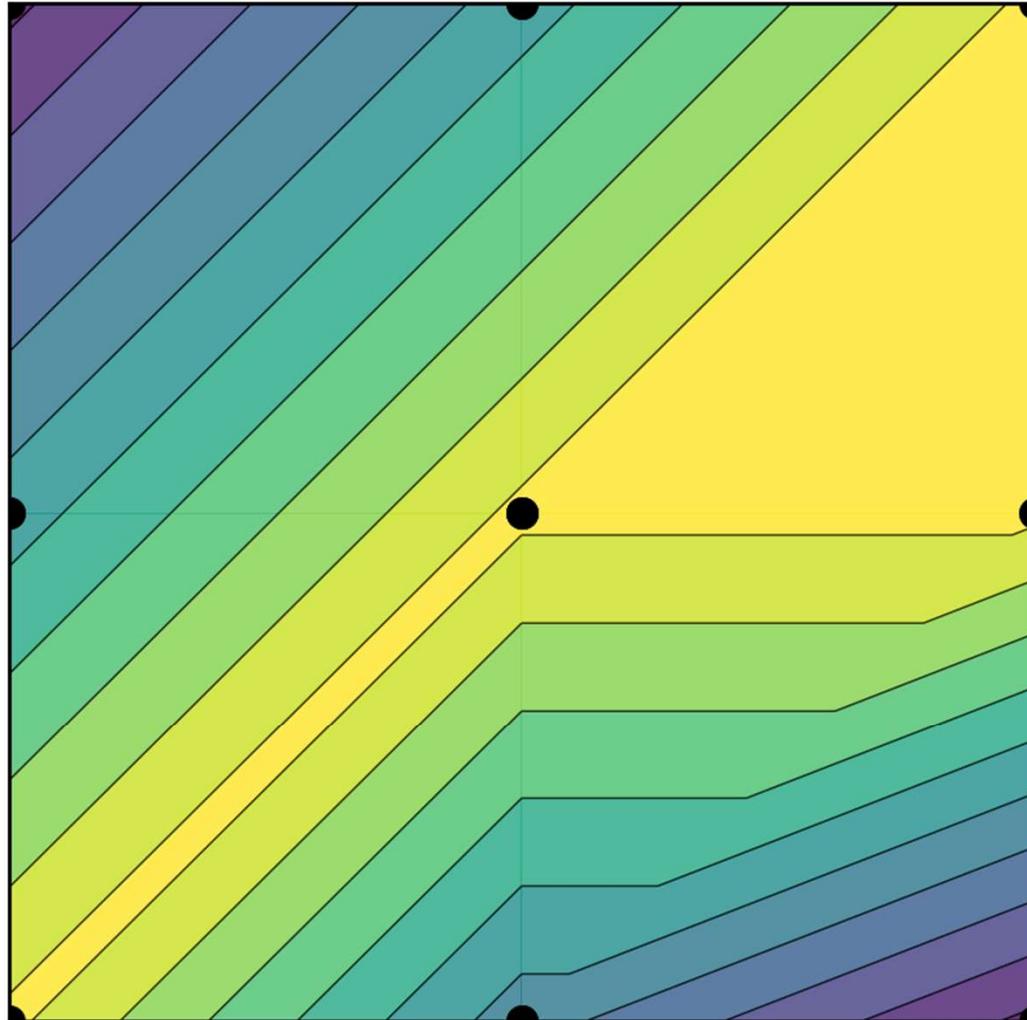


Bi-Linear Interpolation: Comparisons



piecewise linear

(2 triangles per quad;
diagonal:
bottom-left,
top-right)

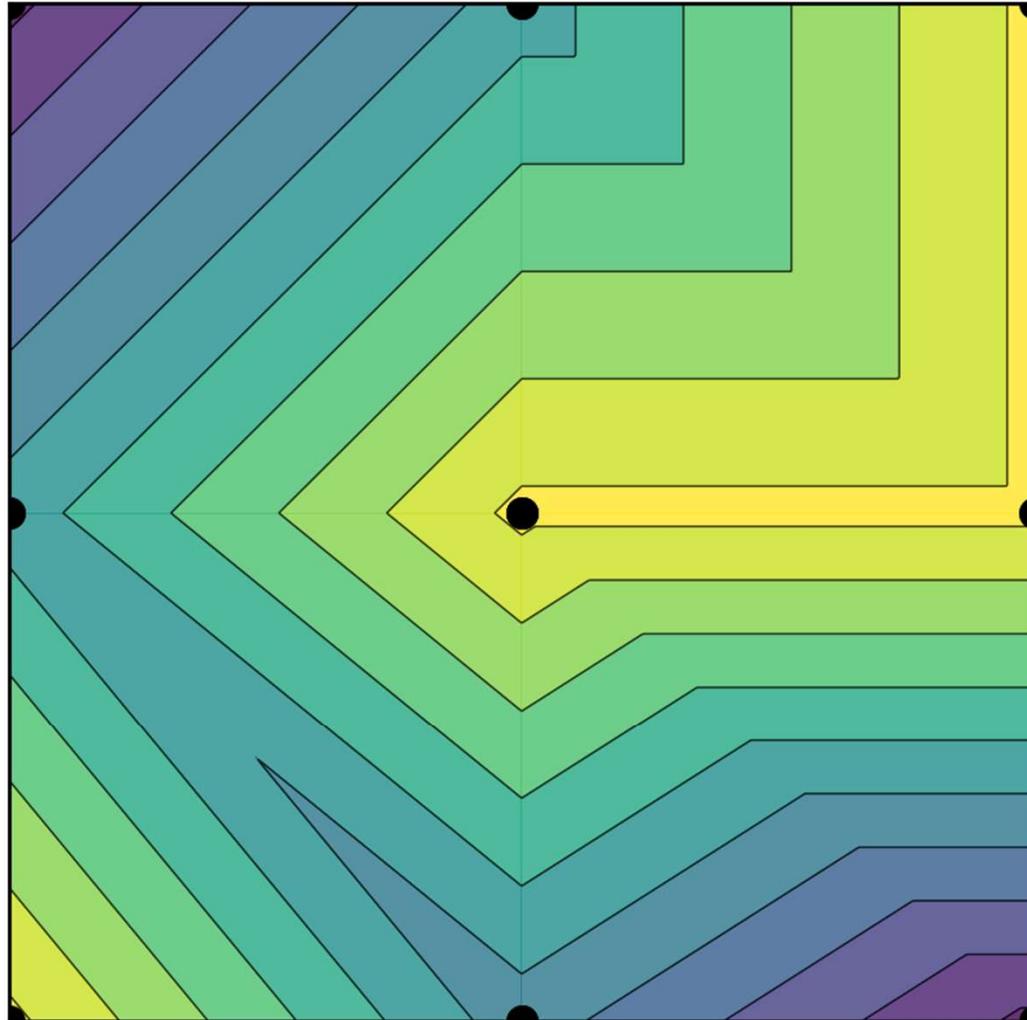


Bi-Linear Interpolation: Comparisons



piecewise linear

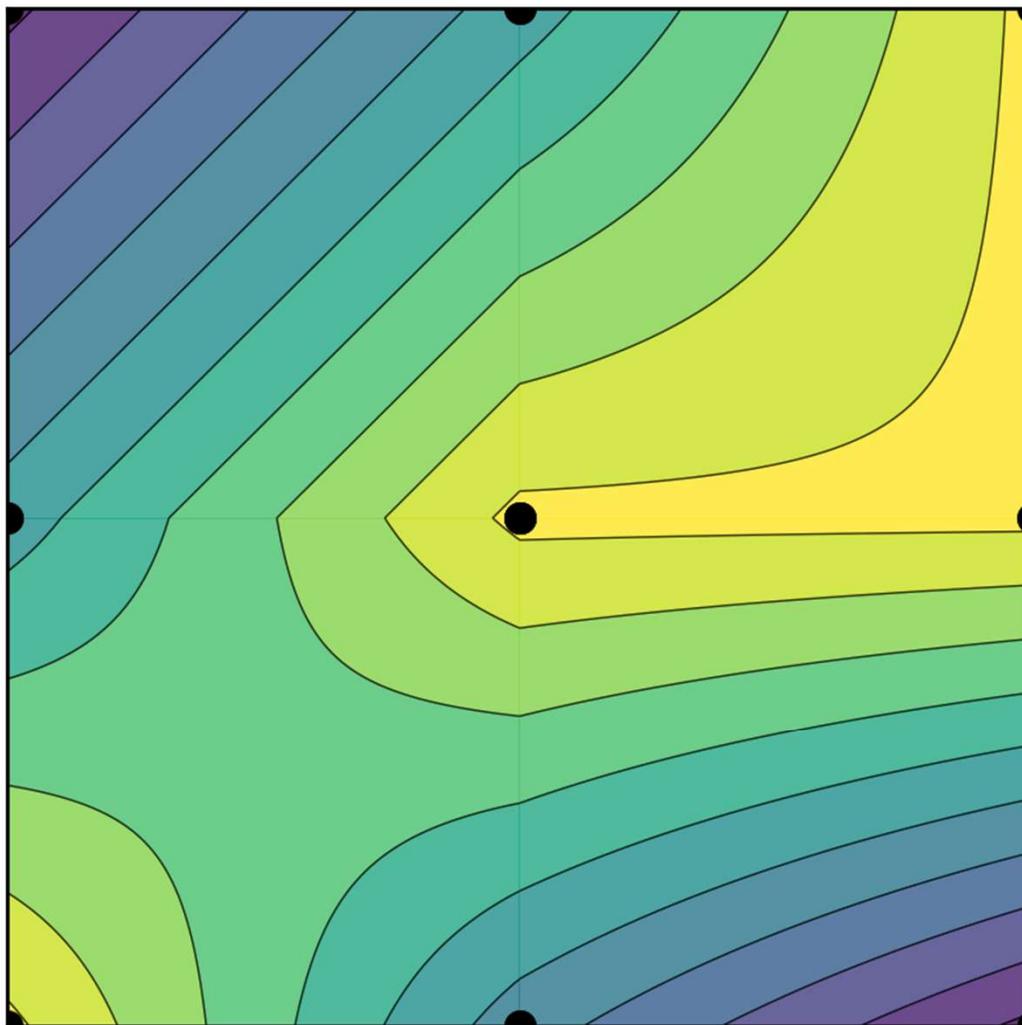
(2 triangles per quad;
diagonal:
top-left,
bottom-right)



Bi-Linear Interpolation: Comparisons



bi-linear

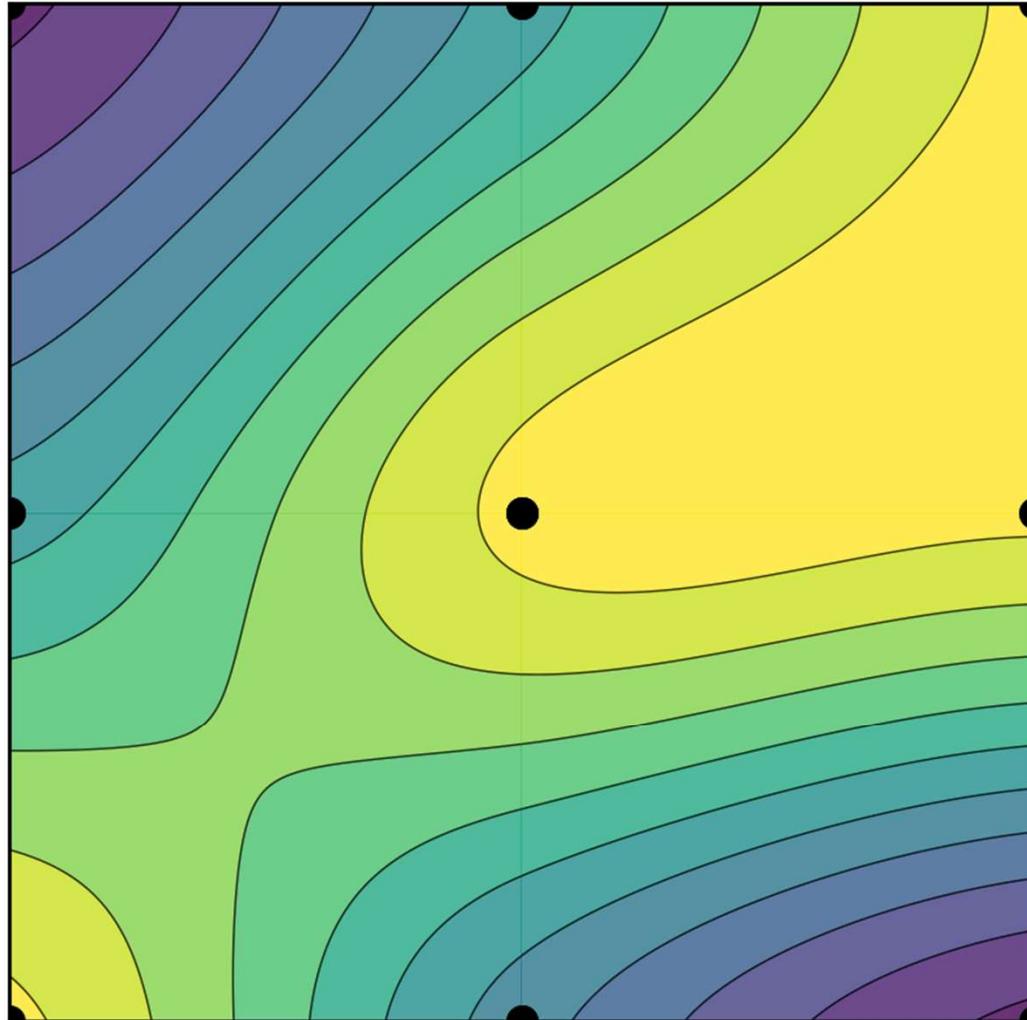


Bi-Linear Interpolation: Comparisons



bi-cubic

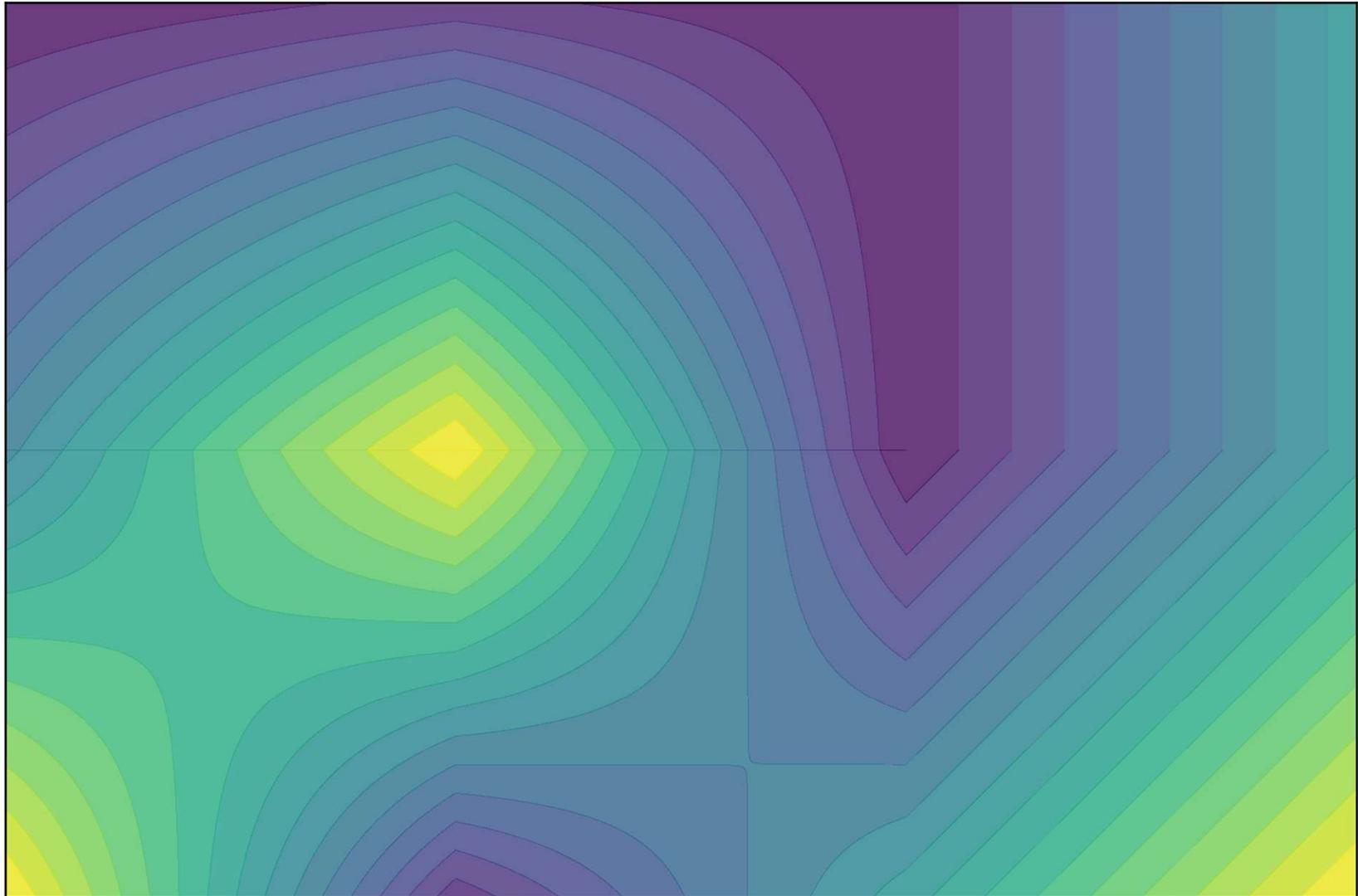
(Catmull-Rom spline)



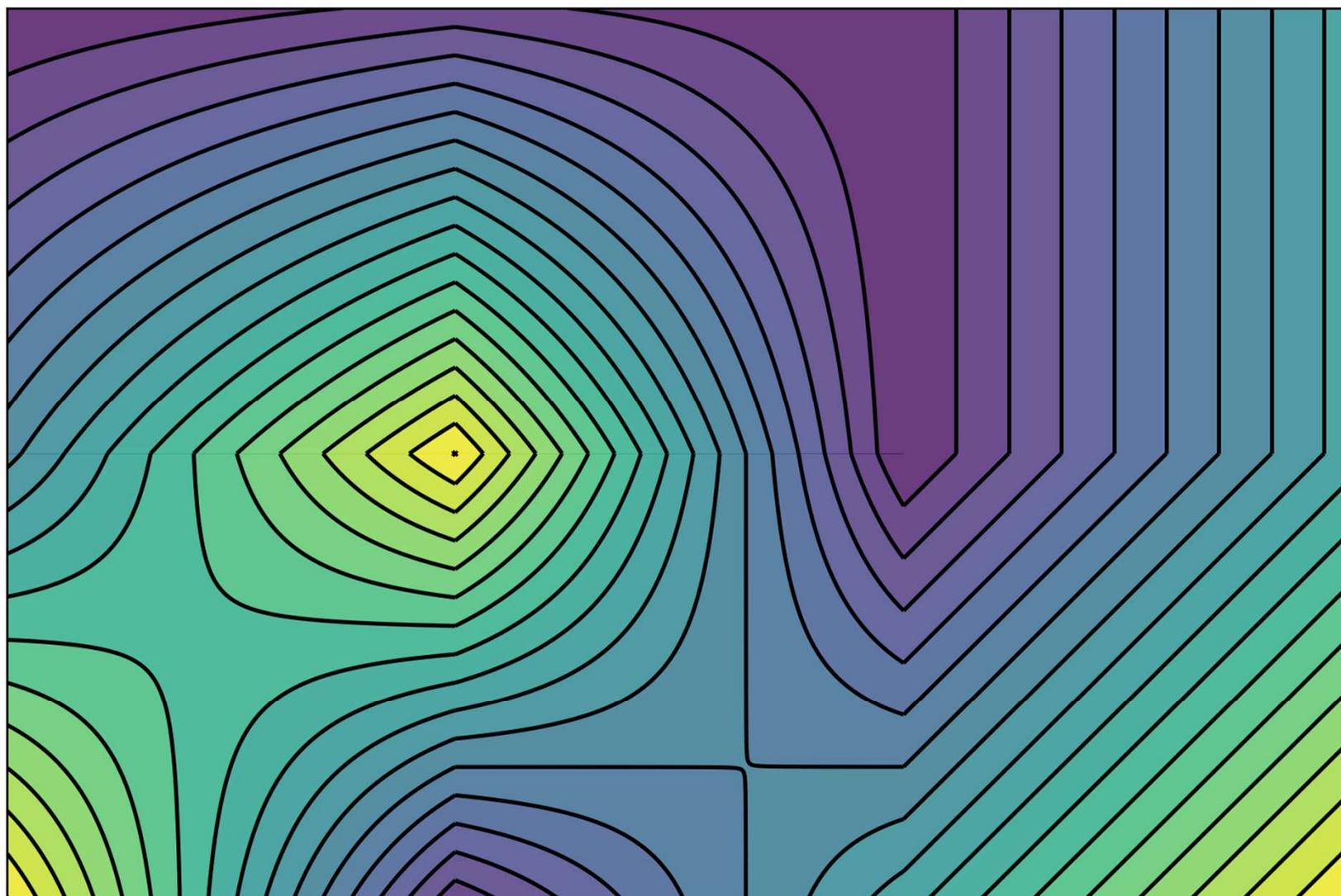


More examples

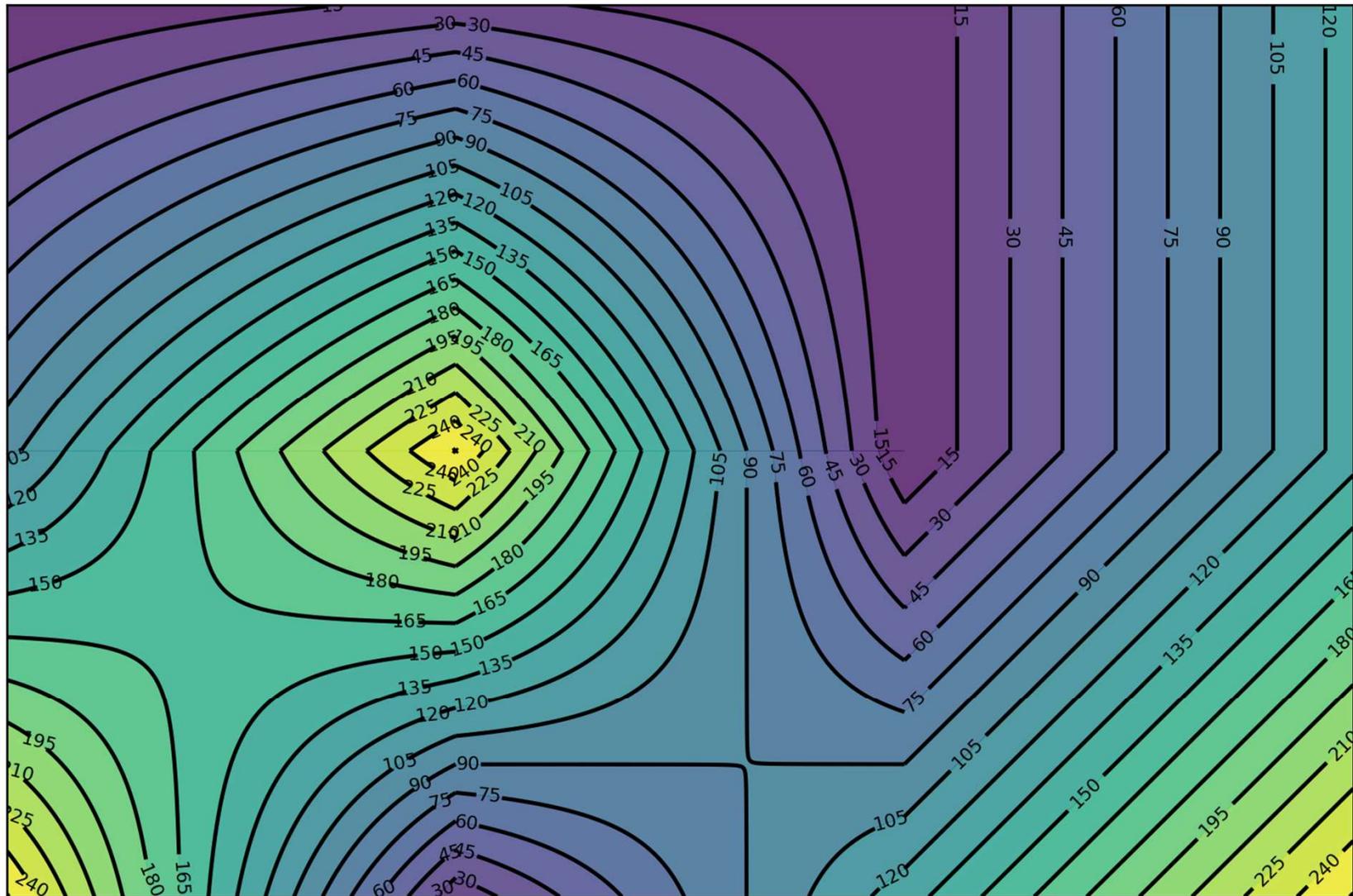
Piecewise Bi-Linear (Example: 3x2 Cells)



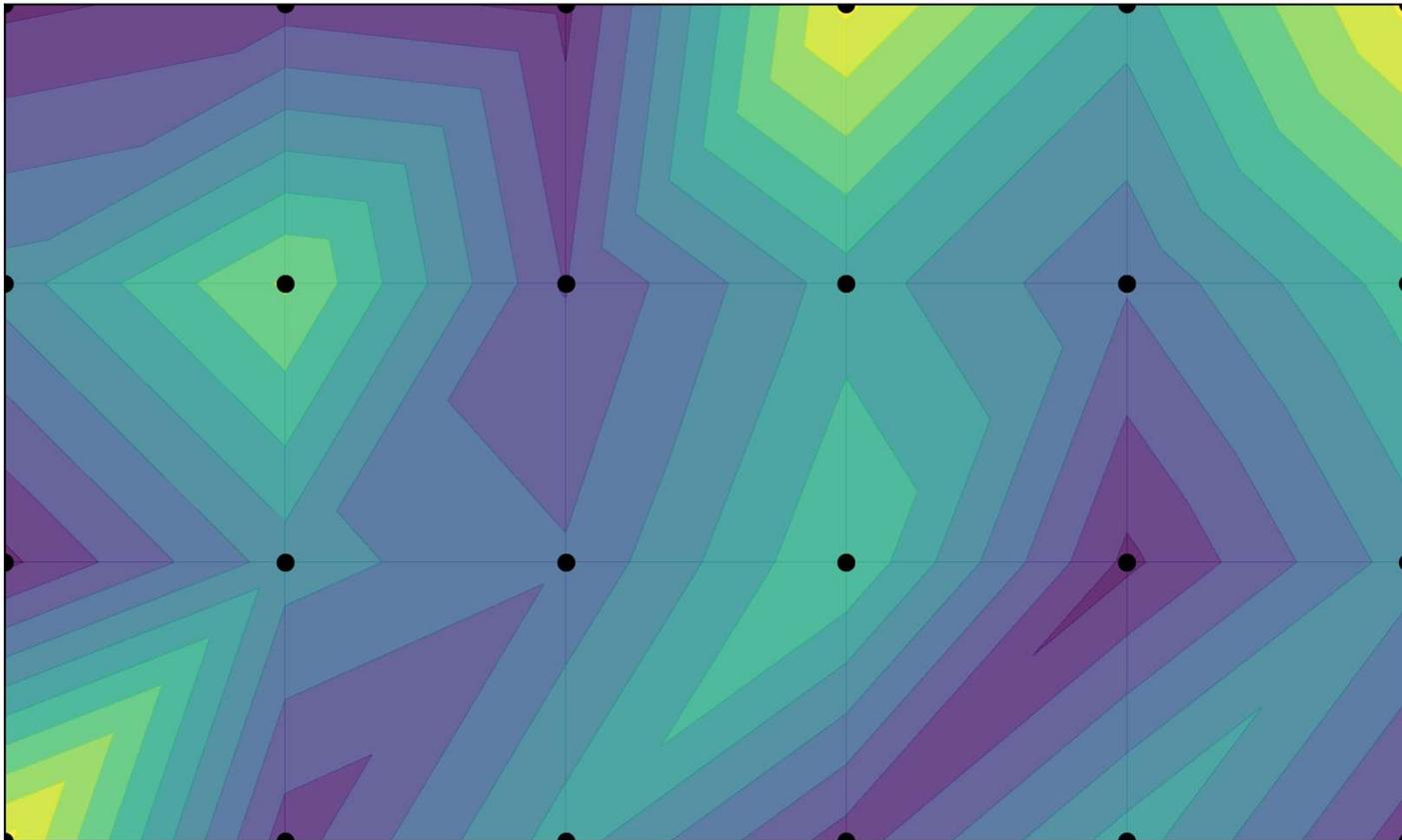
Piecewise Bi-Linear (Example: 3x2 Cells)



Piecewise Bi-Linear (Example: 3x2 Cells)

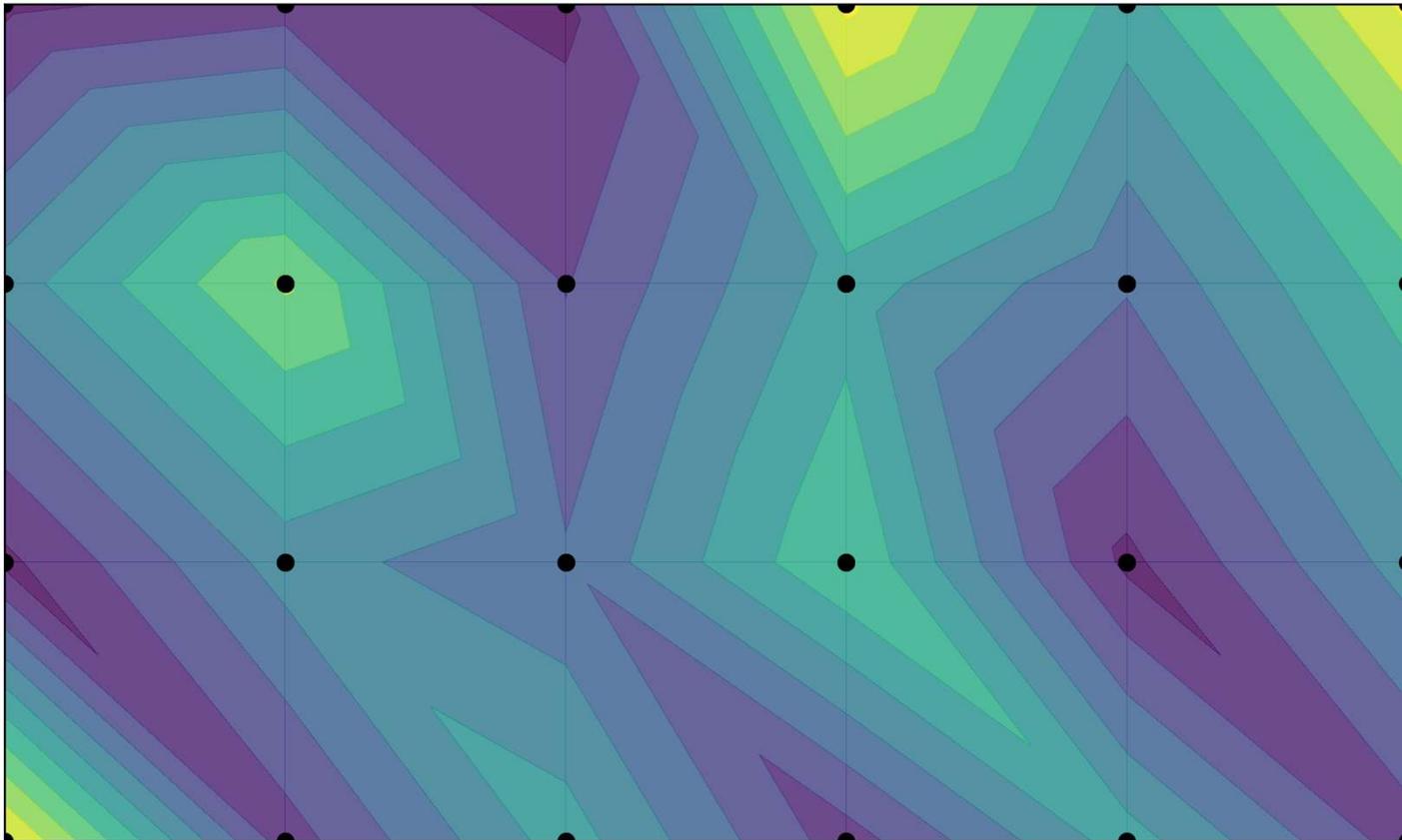


Bi-Linear Interpolation: Comparisons



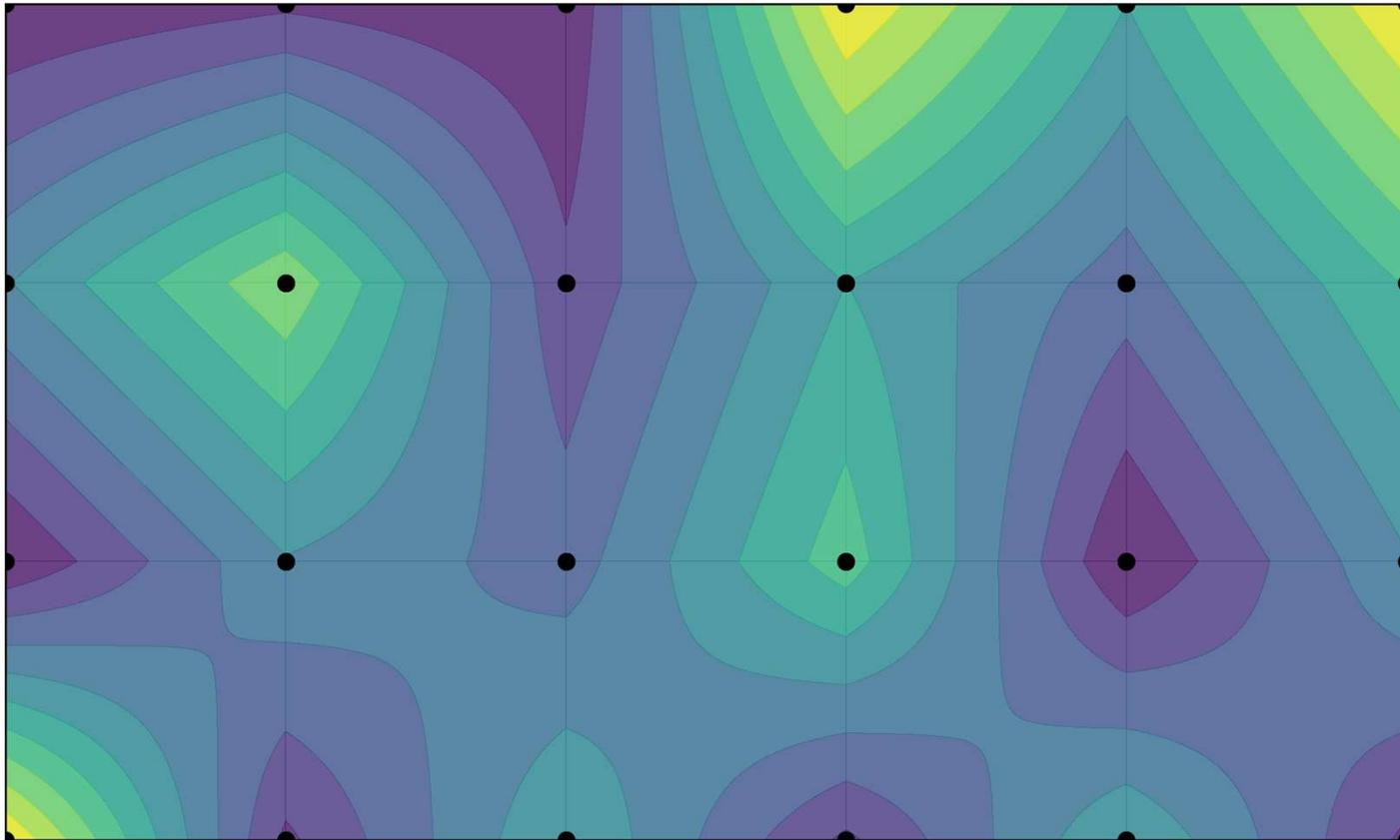
linear (diagonal 1)

Bi-Linear Interpolation: Comparisons



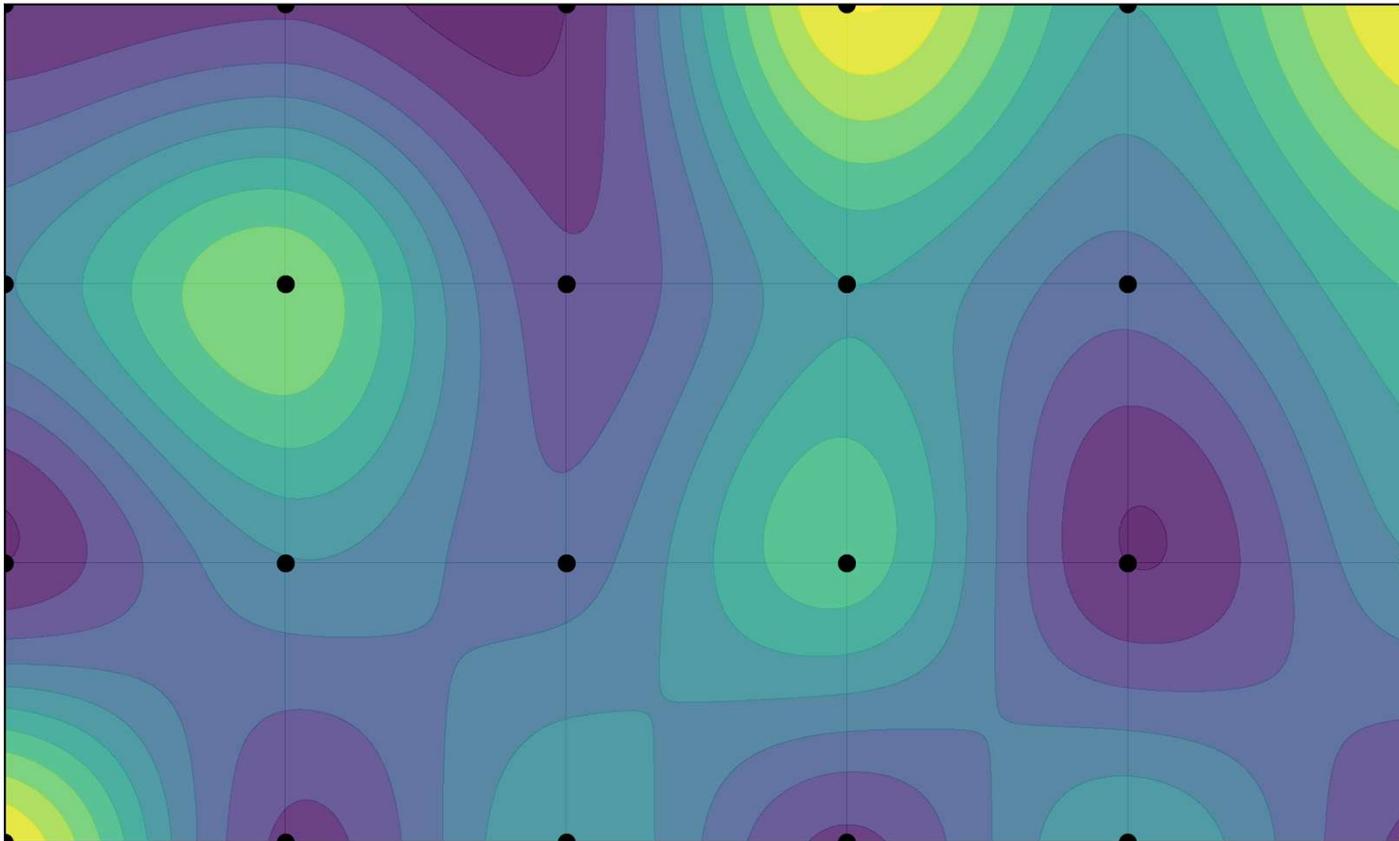
linear (diagonal 2)

Bi-Linear Interpolation: Comparisons



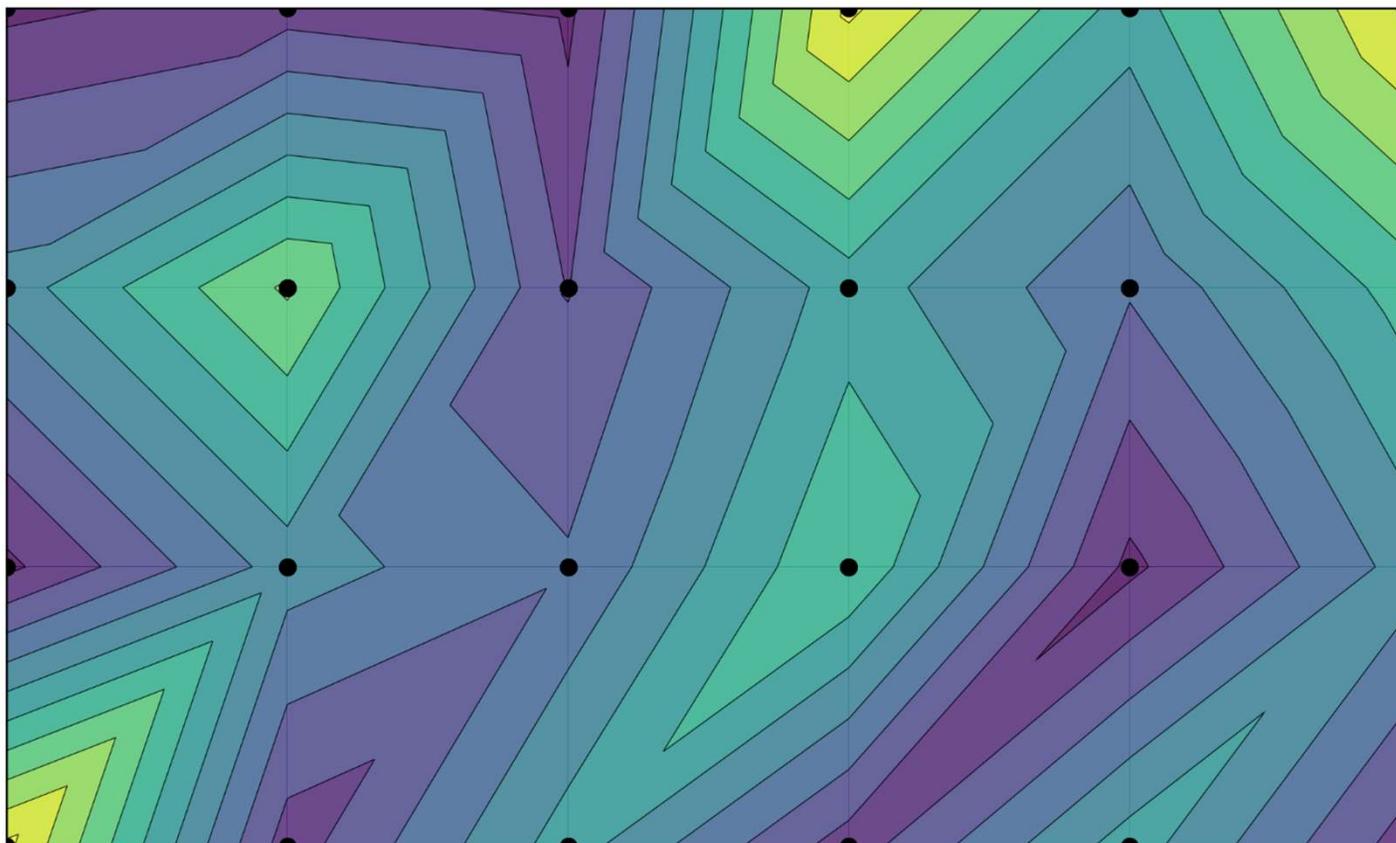
bi-linear (in 3D: tri-linear)

Bi-Linear Interpolation: Comparisons



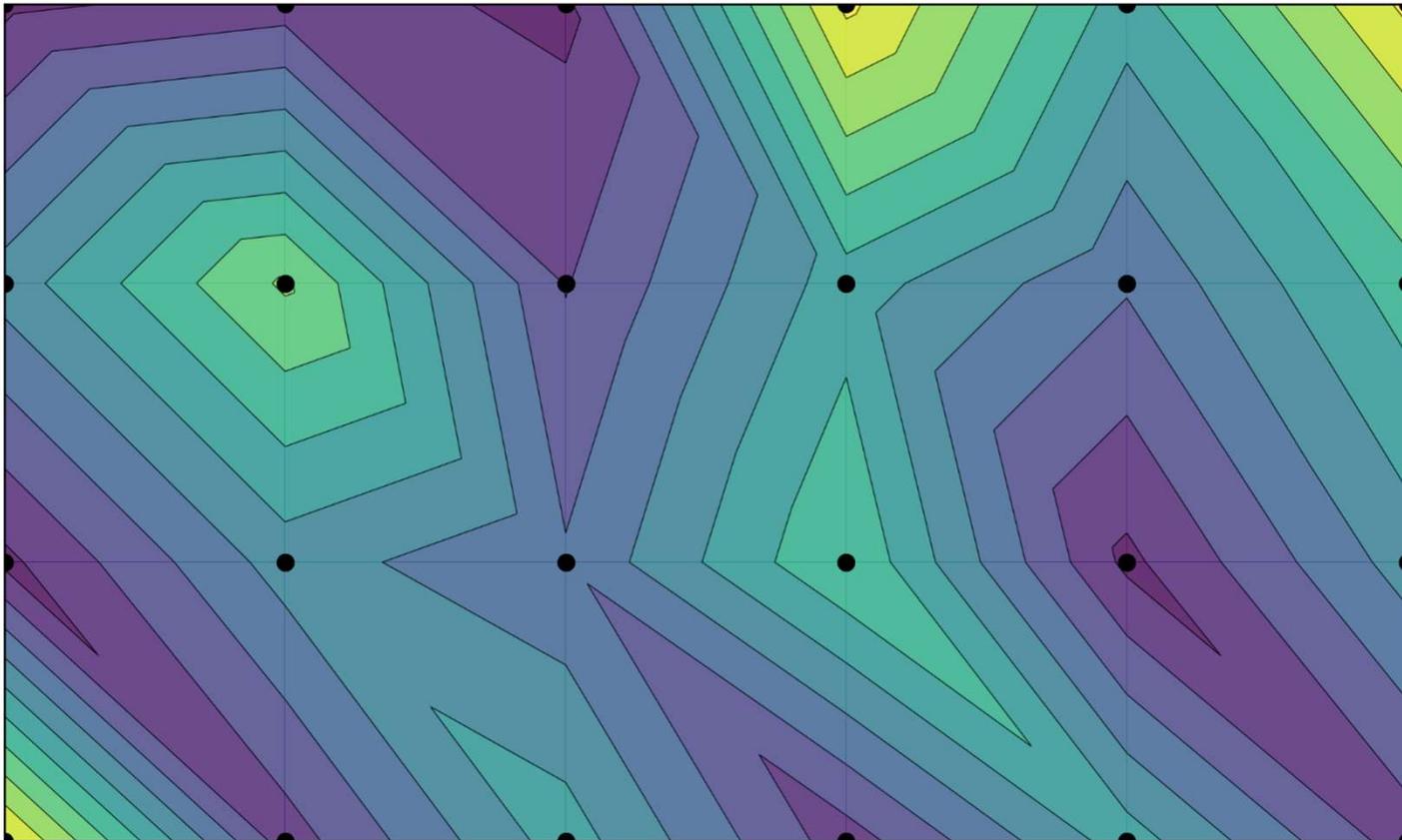
bi-cubic (in 3D: tri-cubic)

Bi-Linear Interpolation: Comparisons



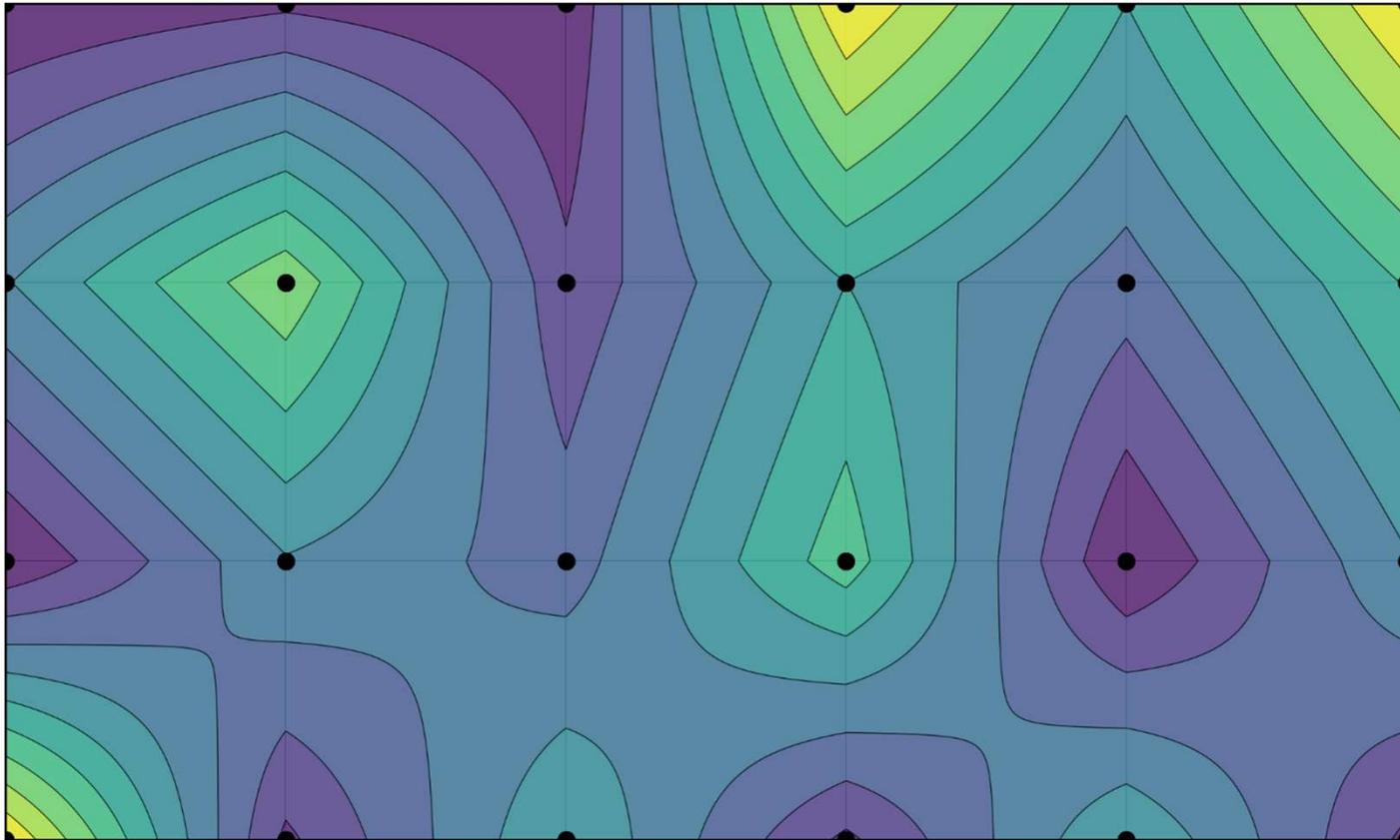
linear (diagonal 1)

Bi-Linear Interpolation: Comparisons



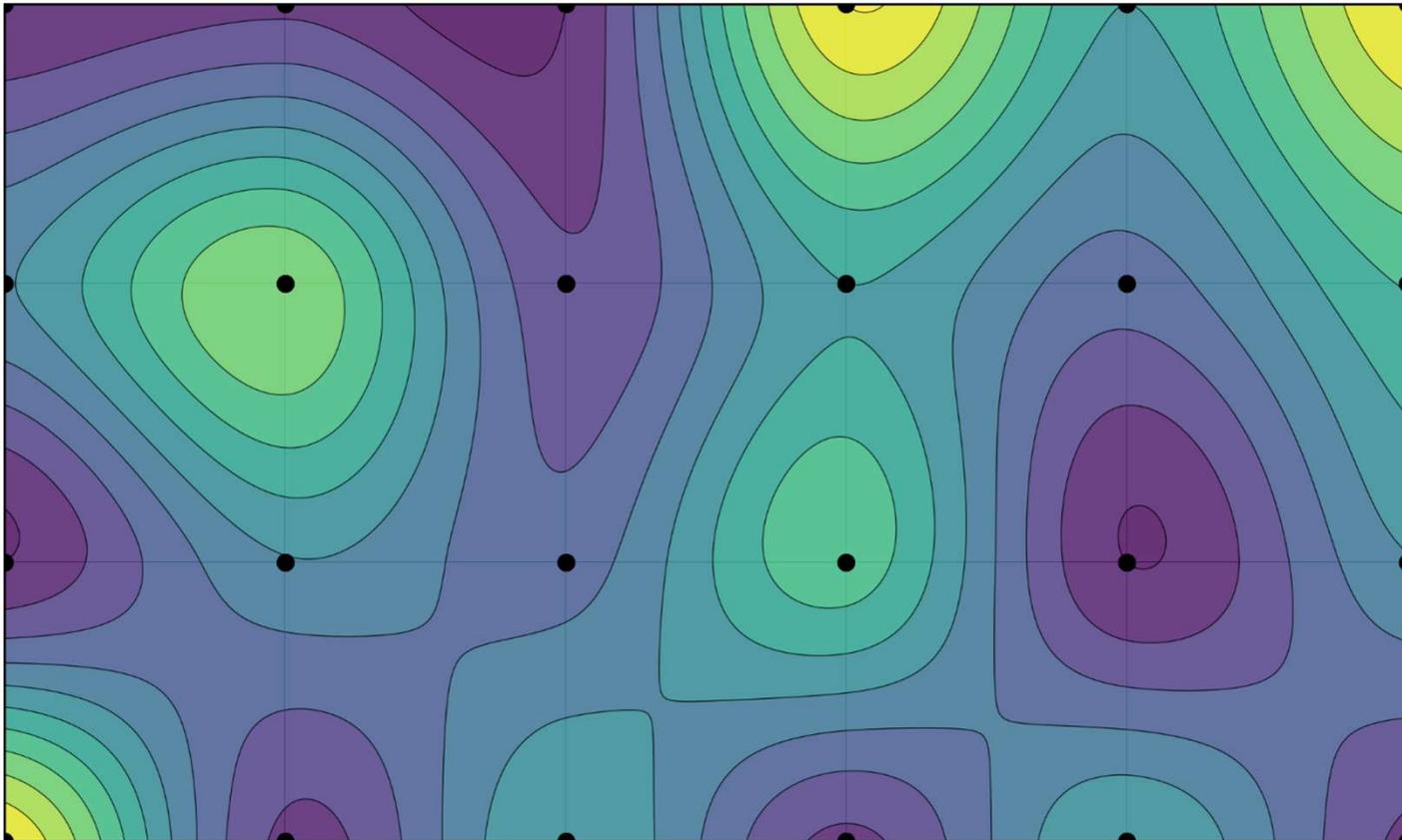
linear (diagonal 2)

Bi-Linear Interpolation: Comparisons



bi-linear (in 3D: tri-linear)

Bi-Linear Interpolation: Comparisons



bi-cubic (in 3D: tri-cubic)

Thank you.

Thanks for material

- Helwig Hauser
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