

CS 247 – Scientific Visualization

Lecture 23: Vector / Flow Visualization, Pt. 2

Markus Hadwiger, KAUST

Reading Assignment #12 (until Apr 18)



Read (required):

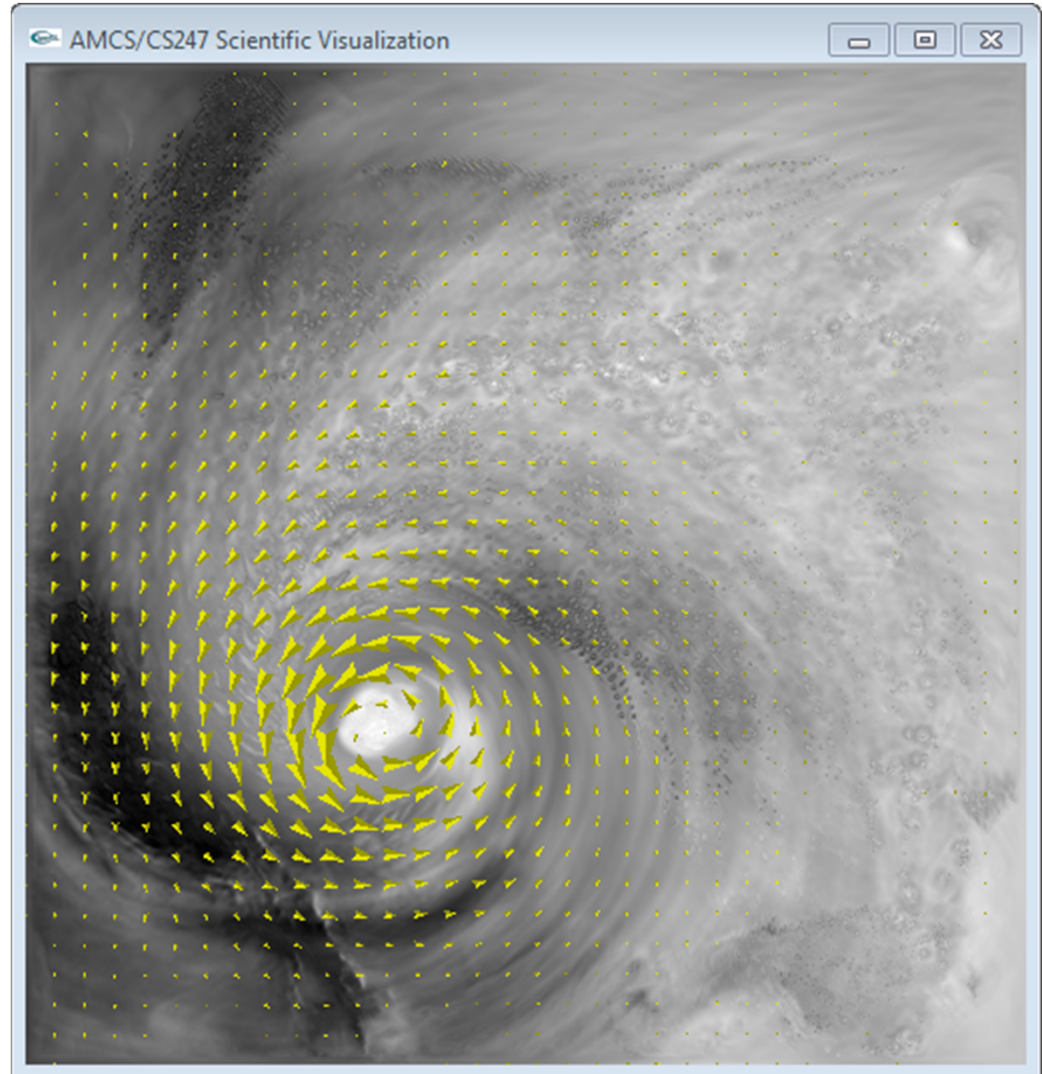
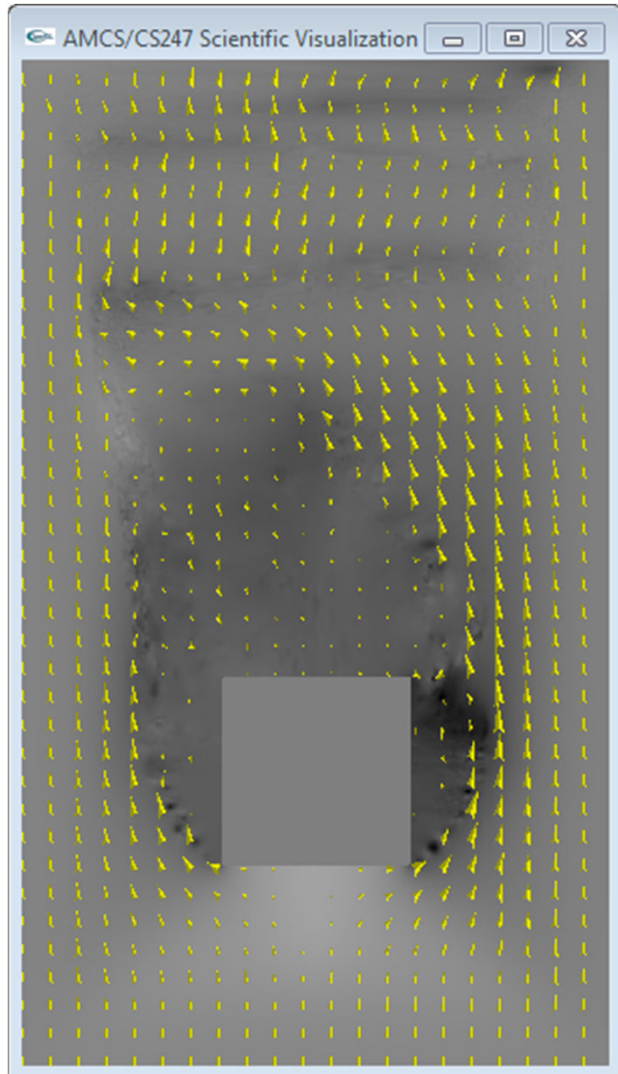
- Data Visualization book
 - Chapter 6 (Vector Visualization)
 - Beginning (before 6.1)
 - Chapters 6.2, 6.3, 6.5
- More general vector field basics (the book is not very precise on the basics)

https://en.wikipedia.org/wiki/Vector_field

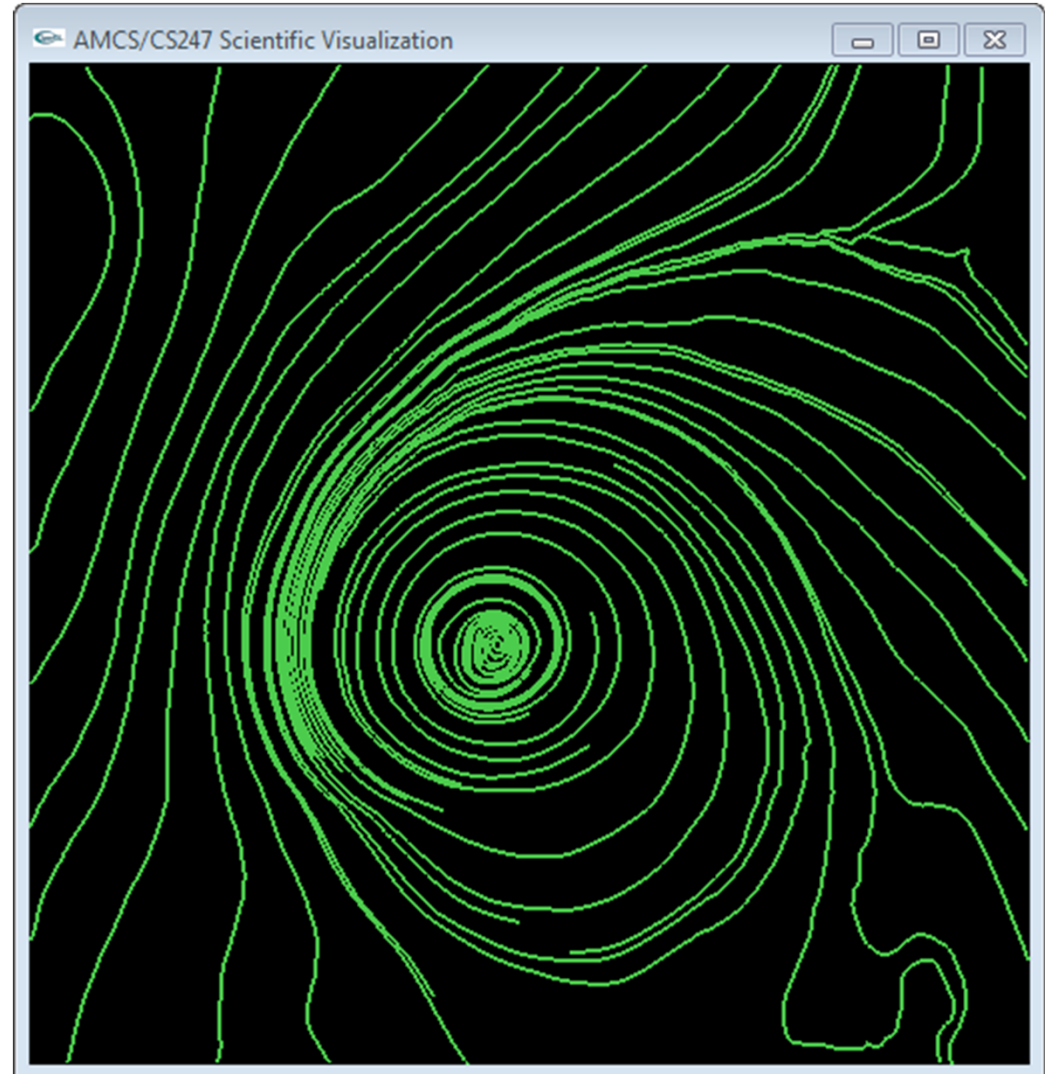
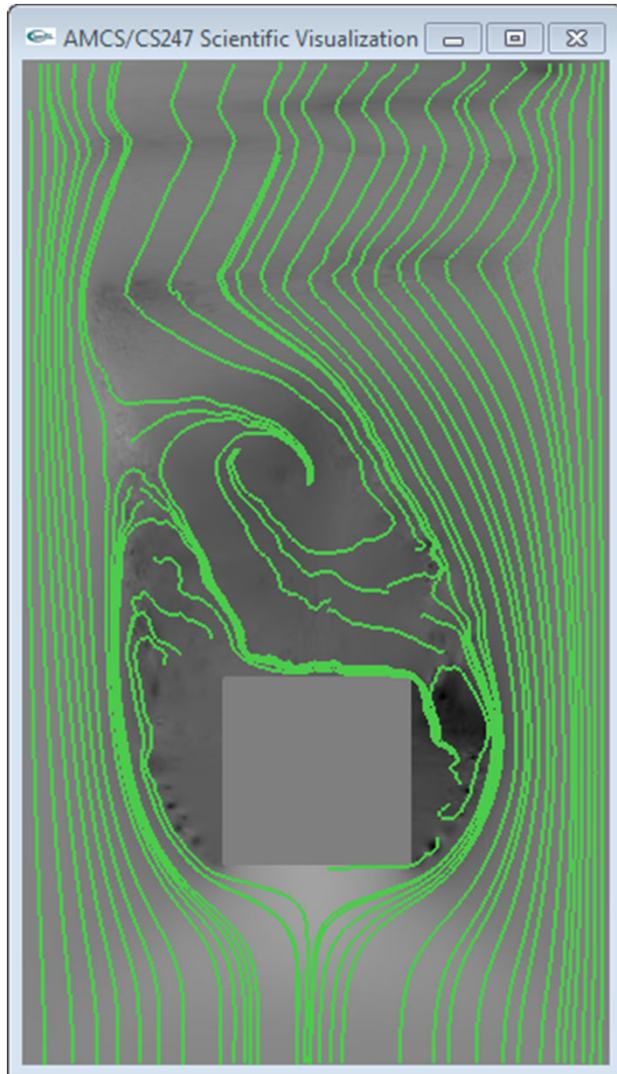
Read (optional):

- Paper:
Bruno Jobard and Wilfrid Lefer
Creating Evenly-Spaced Streamlines of Arbitrary Density,
<http://citeseerx.ist.psu.edu/viewdoc/summary?doi=10.1.1.29.9498>

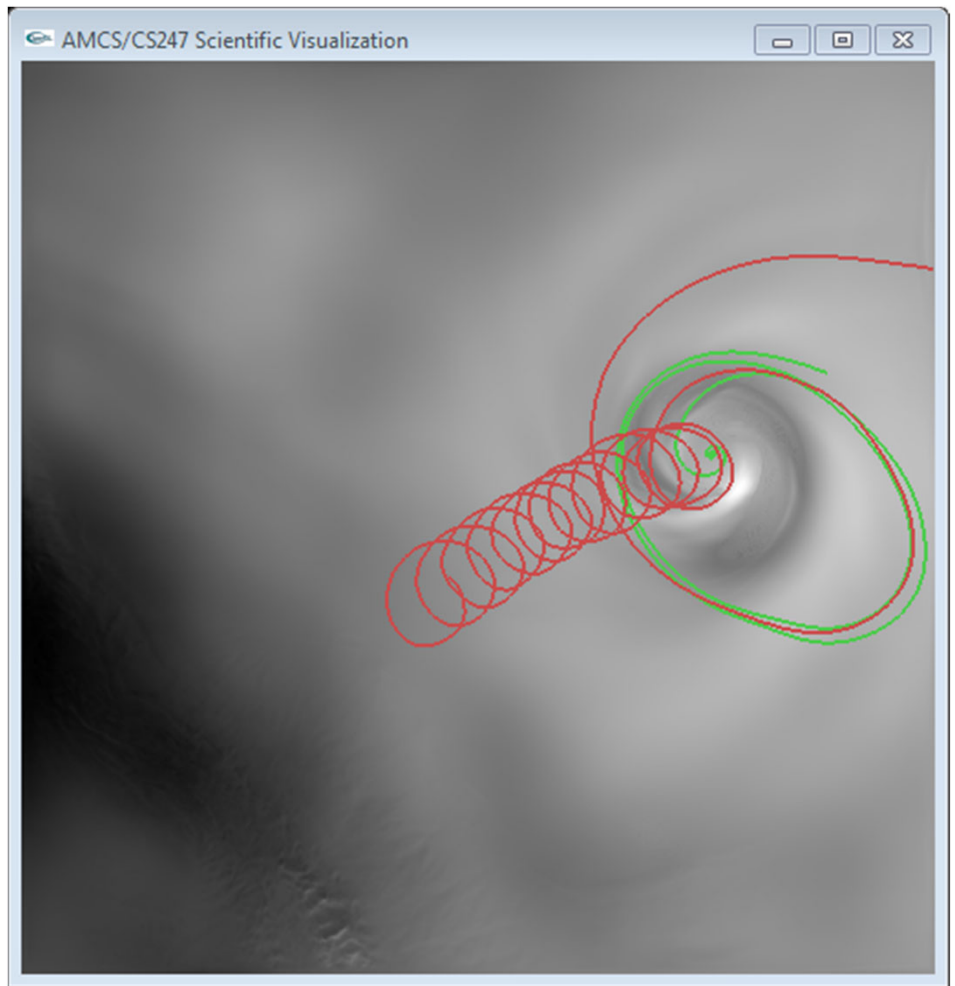
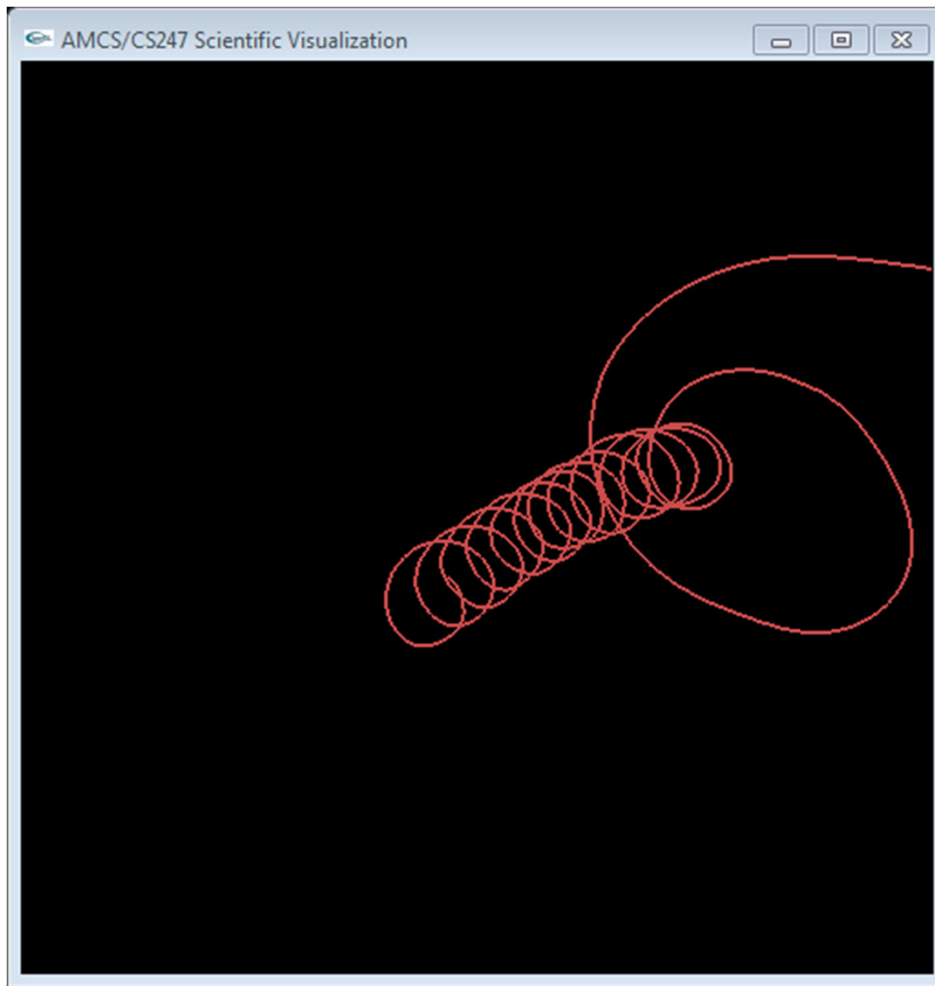
Programming Assignment #5: Flow Vis 1



Programming Assignment #5: Flow Vis 1



Programming Assignment #5: Flow Vis 1



Online Demos and Info



Numerical ODE integration methods (Euler vs. Runge Kutta, etc.)

[https://demonstrations.wolfram.com/
NumericalMethodsForDifferentialEquations/](https://demonstrations.wolfram.com/NumericalMethodsForDifferentialEquations/)

Flow visualization concepts

<https://www3.nd.edu/~cwang11/flowvis.html>

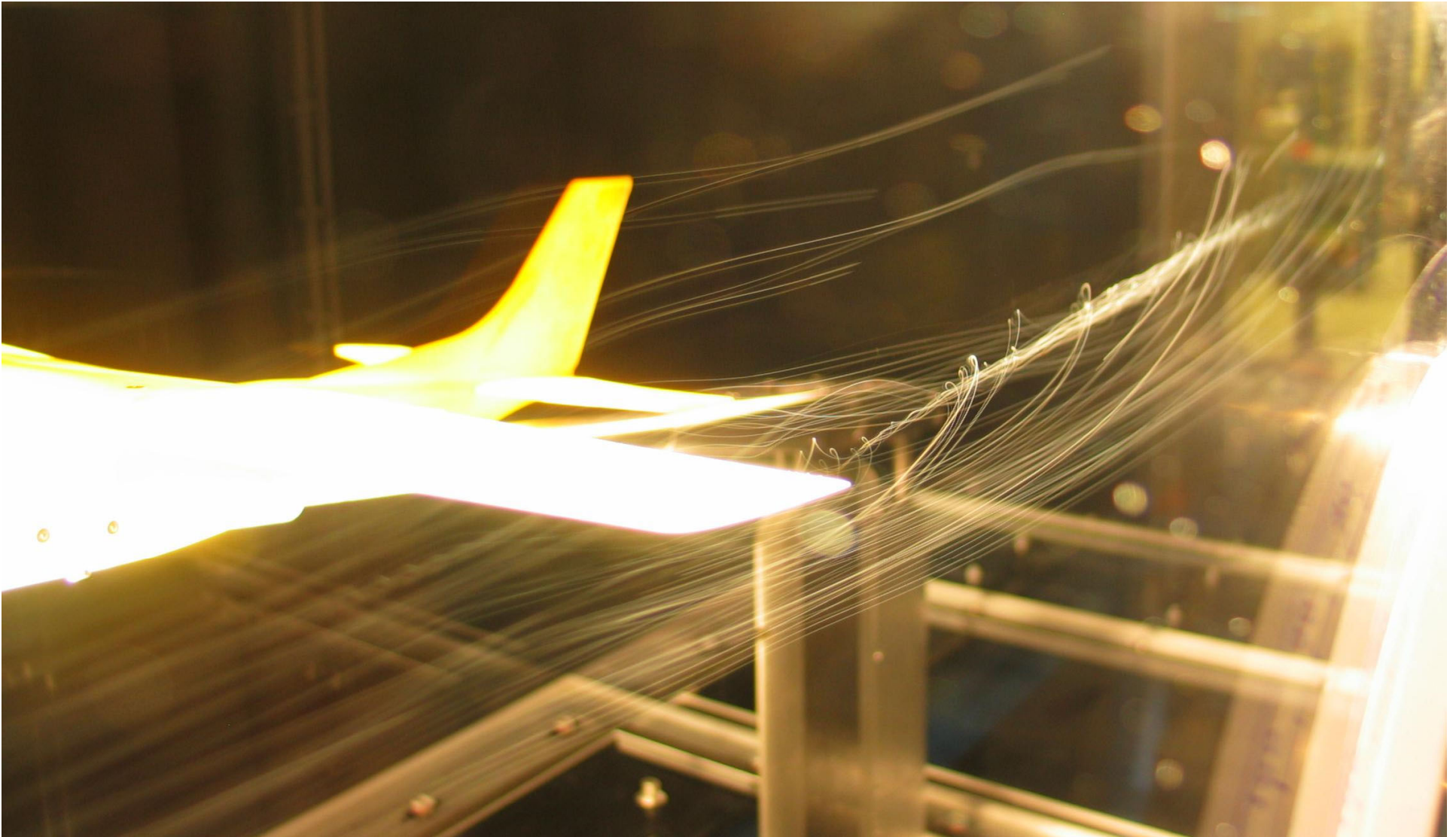
Vector Fields: Motivation



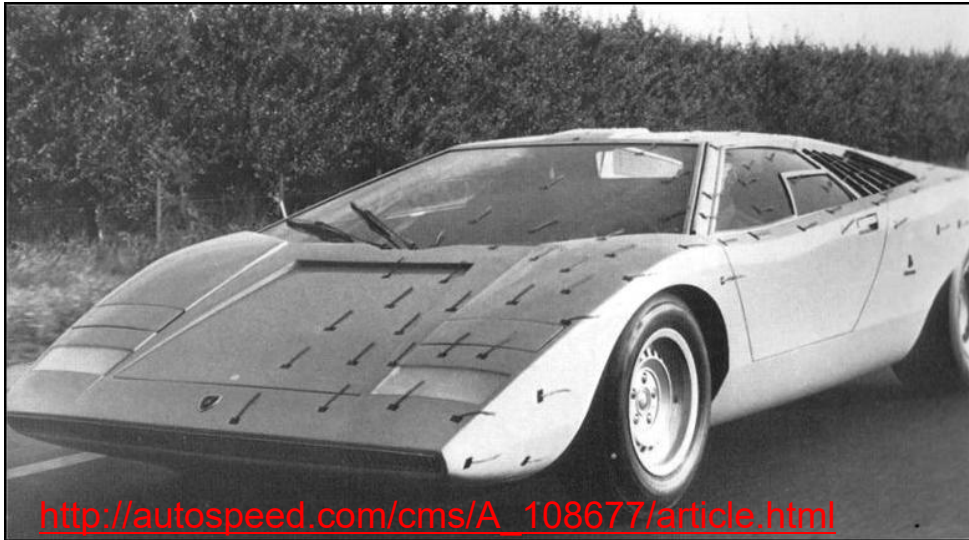
Smoke angel

A C-17 Globemaster III from the 14th Airlift Squadron, Charleston Air Force Base, S.C. flies off after releasing flares over the Atlantic Ocean near Charleston, S.C., during a training mission on Tuesday, May 16, 2006. The "smoke angel" is caused by the vortex from the engines.

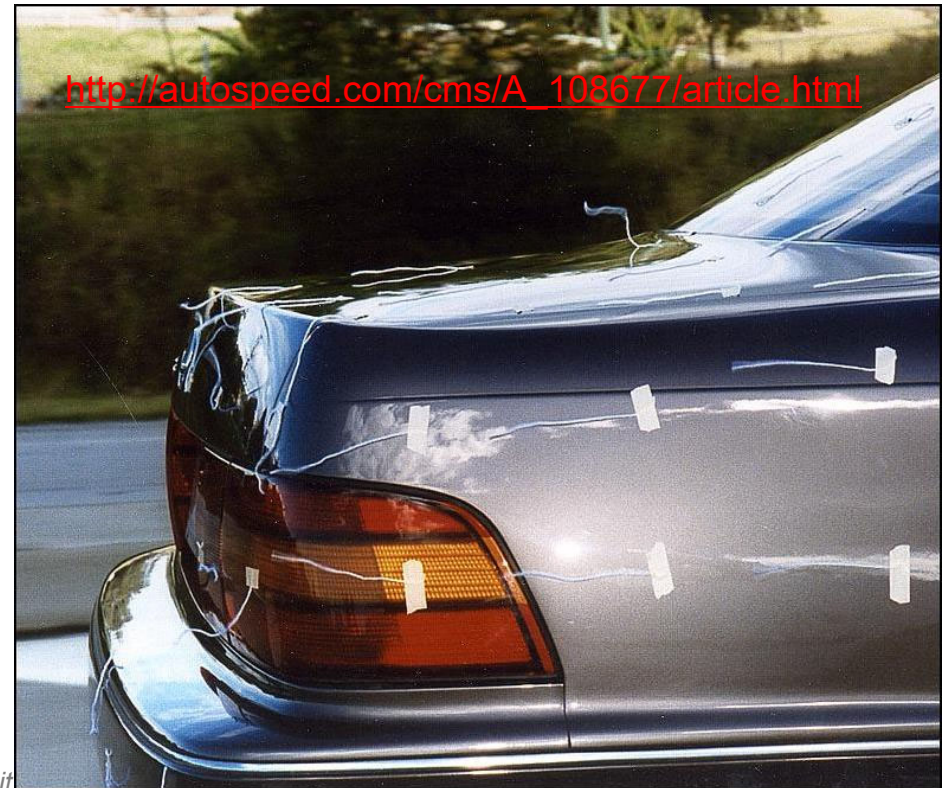
(U.S. Air Force photo/Tech. Sgt. Russell E. Cooley IV)



A wind tunnel model of a Cessna 182 showing a wingtip vortex.
Tested in the RPI (Rensselaer Polytechnic Institute) Subsonic Wind Tunnel.
By Ben FrantzDale (2007).



wool tufts



Flow Visualization: Problems and Concepts



smoke injection



http://autospeed.com/cms/A_108677/article.html

smoke nozzles



[NASA, J. Exp. Biol.]



http://autospeed.com/cms/A_108677/article.html

smoke nozzles

Smoke injection

A. L. R. Thomas, G. K. Taylor, R. B. Srygley, R. L. Nudds, and R. J. Bomphrey. Dragonfly flight: free-flight and tethered flow visualizations reveal a diverse array of unsteady lift-generating mechanisms, controlled primarily via angle of attack. *J Exp Biol*, 207(24):4299–4323, 2004.



http://de.wikipedia.org/wiki/Bild:Airplane_vortex_edit.jpg

Flow Visualization: Problems and Concepts



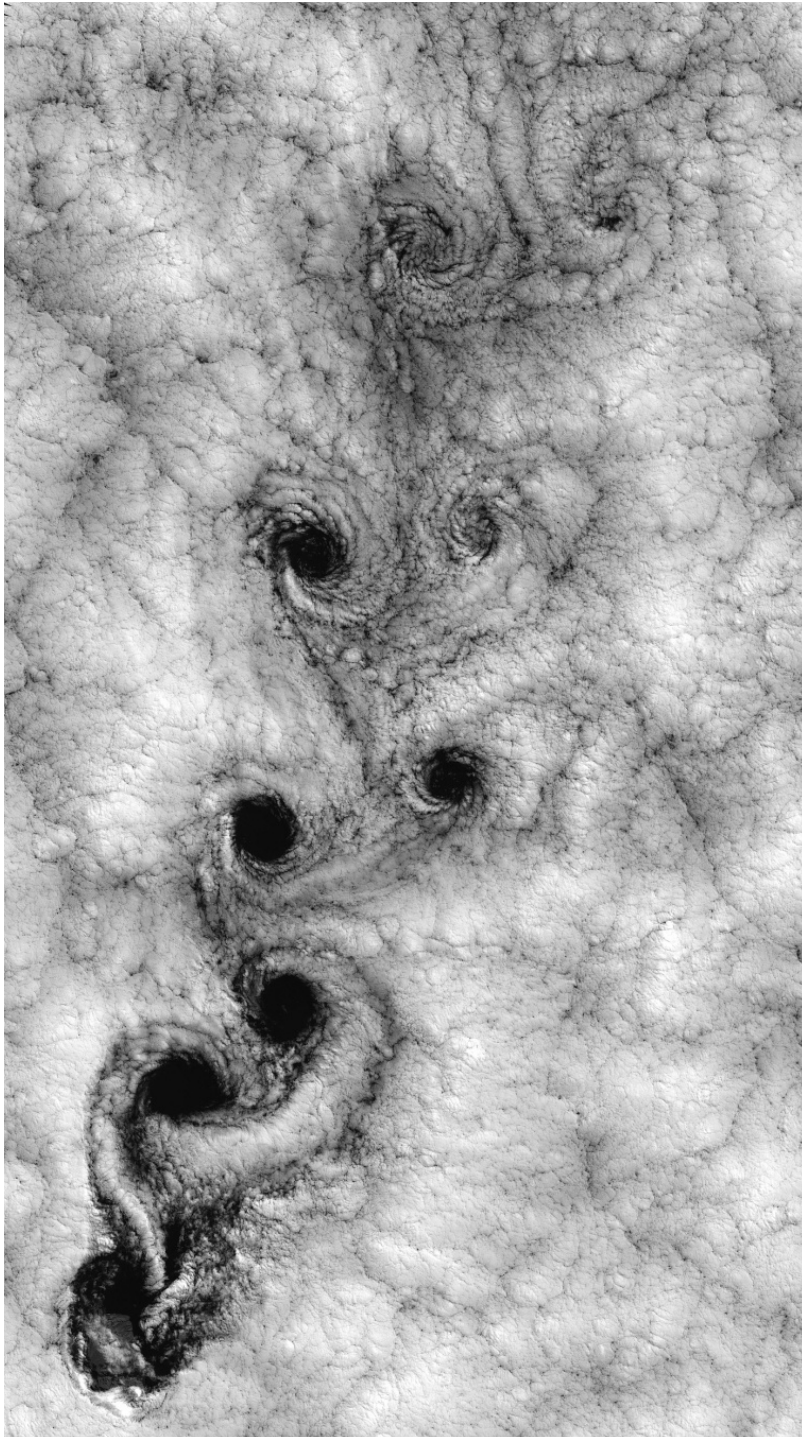


Smoke injection

<http://www-me.ccny.cuny.edu/research/aerolab/facilities/images/wt2.jpg>

Clouds (satellite image)

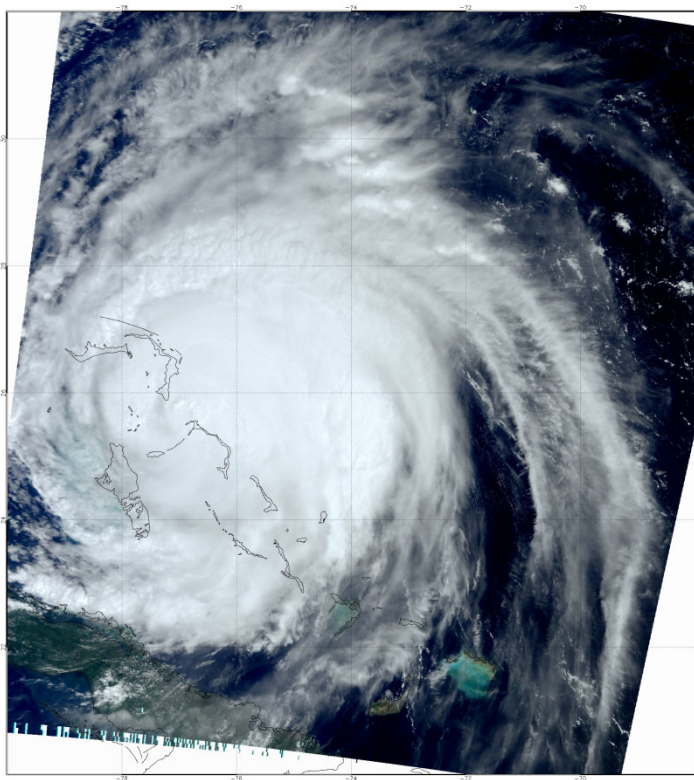
Juan Fernandez Islands



<http://de.wikipedia.org/wiki/Bild:Vortex-street-1.jpg>
d University, Winter 2011/12

Clouds (satellite image)

<http://daac.gsfc.nasa.gov/gallery/frances/>



- **Vortex/ Vortex core lines**
 - There is no exact definition of vortices
 - capturing some swirling behavior

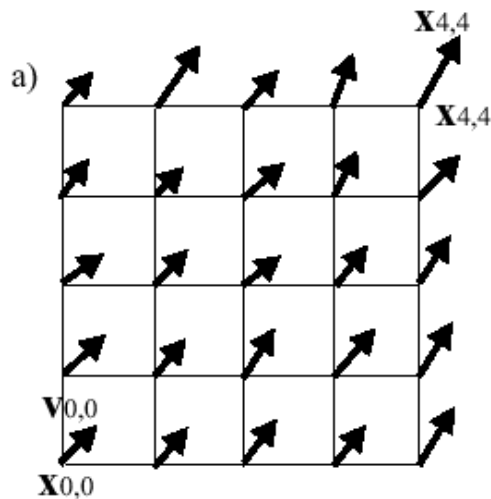


Vector Fields

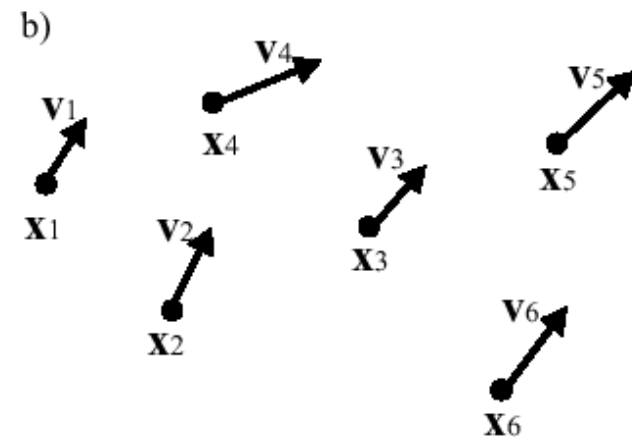


Each vector is usually thought of as a velocity vector

- Example for actual velocity: fluid flow
- But also force fields, etc. (e.g., electrostatic field)



vectors given at grid points



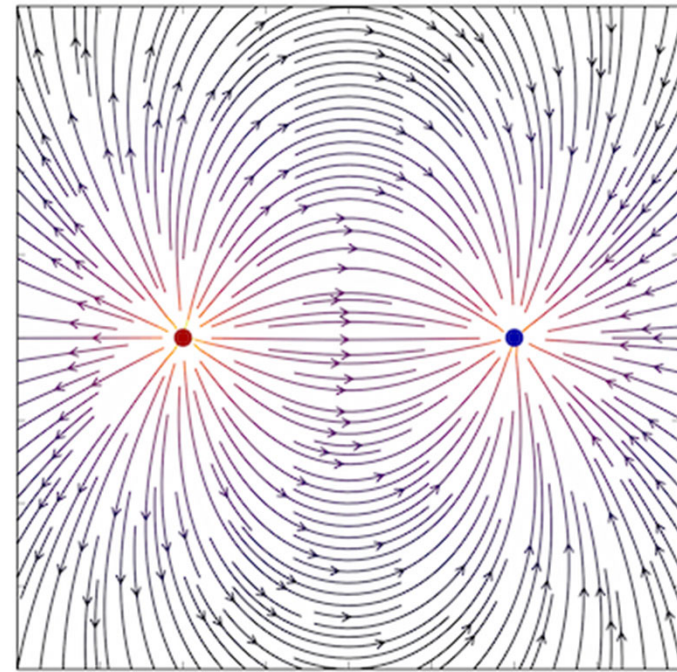
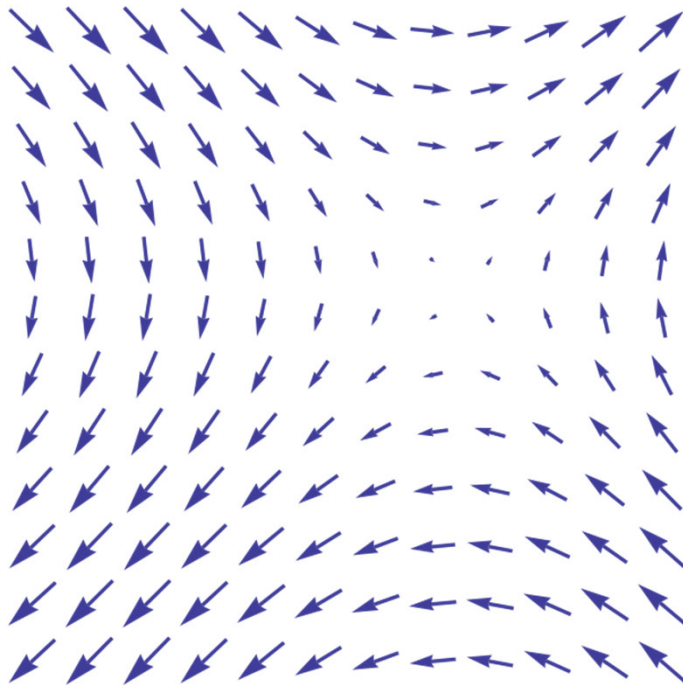
vectors given at particle positions

Vector Fields



Each vector is usually thought of as a velocity vector

- Example for actual velocity: fluid flow
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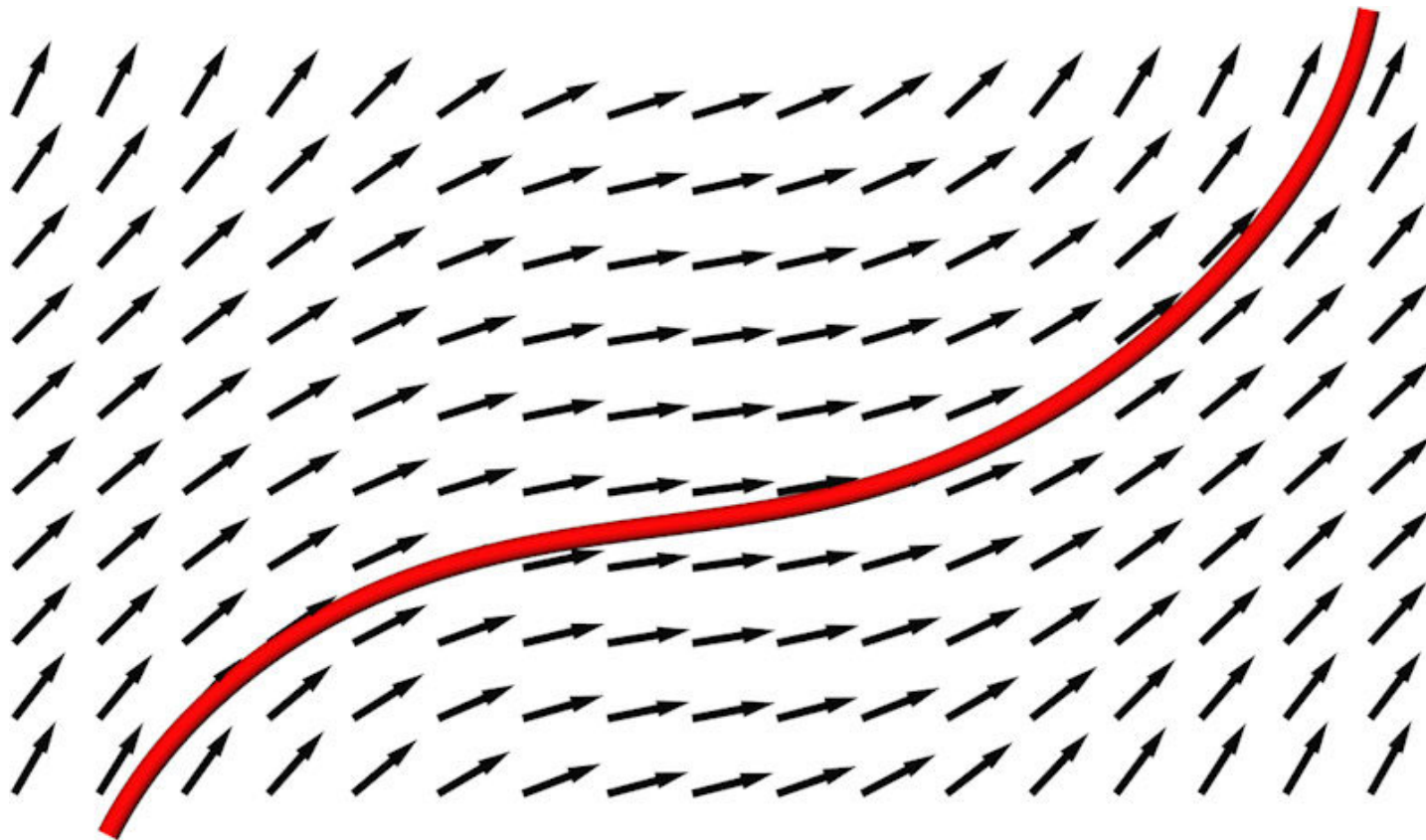


images from wikipedia

Integral Curves / Stream Objects



Integrating velocity over time yields spatial motion



Vector Fields



Each vector is usually thought of as a velocity vector

- Example for actual velocity: fluid flow
- But also force fields, etc. (e.g., electrostatic field)

Each vector in a vector field
lives in the **tangent space**
of the manifold at that point:

Each vector is a **tangent vector**

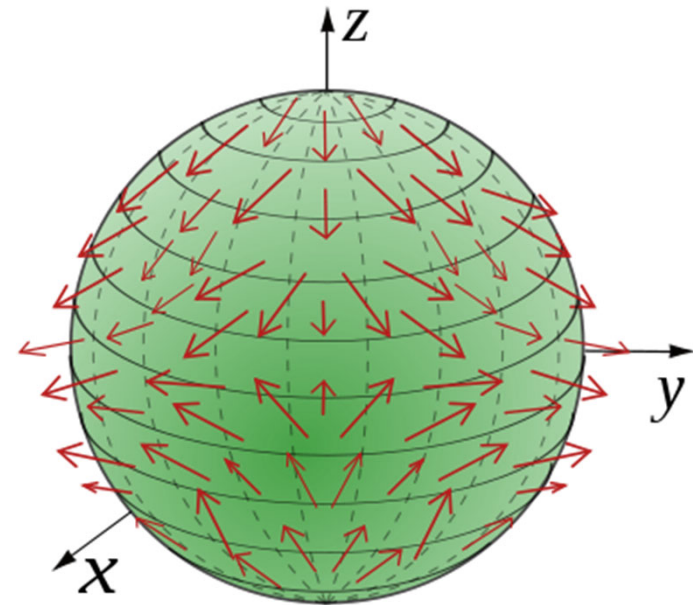
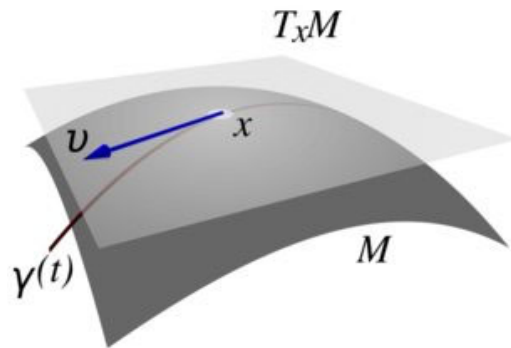


image from wikipedia

Vector Fields



Vector fields on general manifolds M (not just Euclidean space)

Tangent space at a point $x \in M$:

$$T_x M$$

Tangent bundle: Manifold of all tangent spaces over base manifold

$$\pi: TM \rightarrow M$$

Vector field: *Section* of tangent bundle

$$s: M \rightarrow TM,$$

$$x \mapsto s(x).$$

$$\pi(s(x)) = x$$

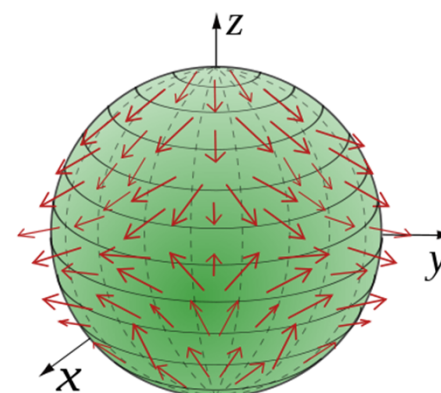
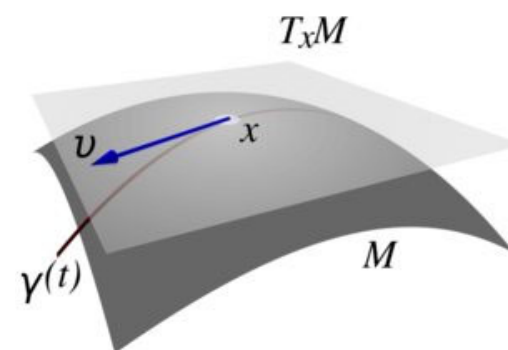


image from wikipedia

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Tangent space at a point $x \in M$:

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Tangent bundle: Manifold of all tangent spaces over base manifold

$$\pi: TM \rightarrow M$$

Vector field: *Section* of tangent bundle

$$\begin{aligned} \mathbf{v}: M &\rightarrow TM, \\ x &\mapsto \mathbf{v}(x). \end{aligned}$$

$$\mathbf{v}(x) \in T_x M$$

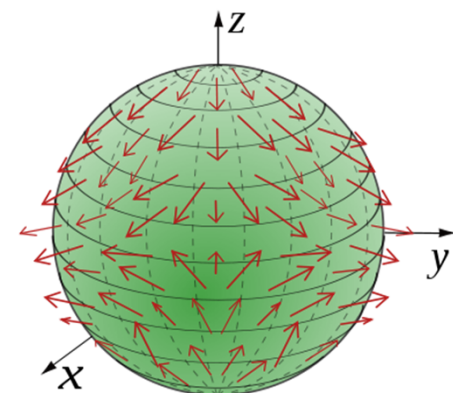
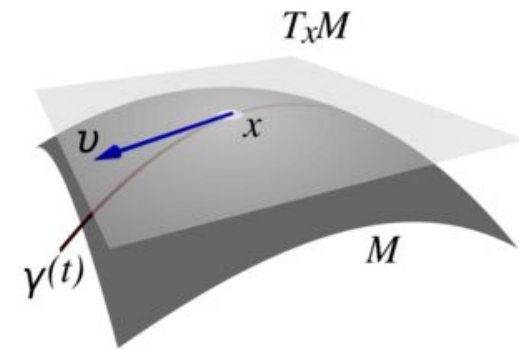


image from wikipedia

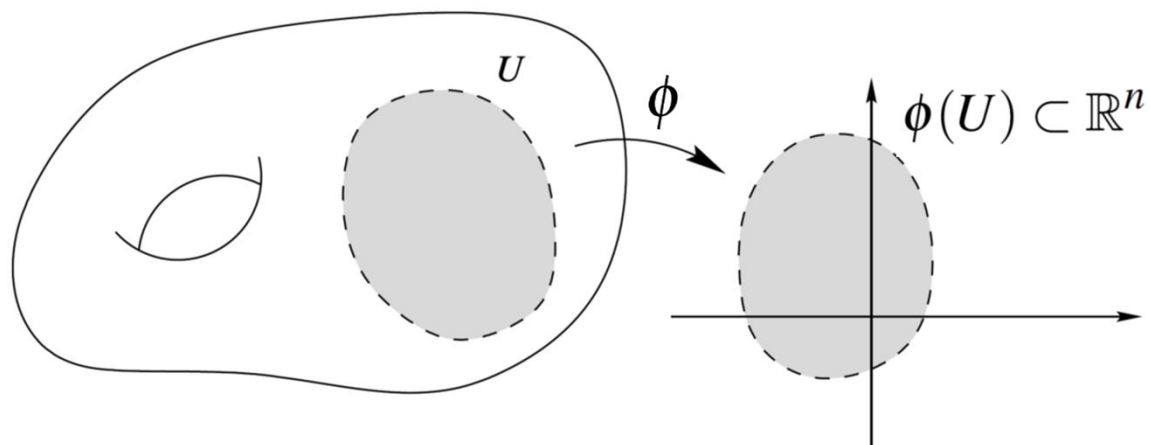
Interlude: Coordinate Charts

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Coordinate chart

$$\begin{aligned}\phi: U \subset M &\rightarrow \mathbb{R}^n, \\ x &\mapsto (x^1, x^2, \dots, x^n).\end{aligned}$$



Interlude: Coordinate Charts

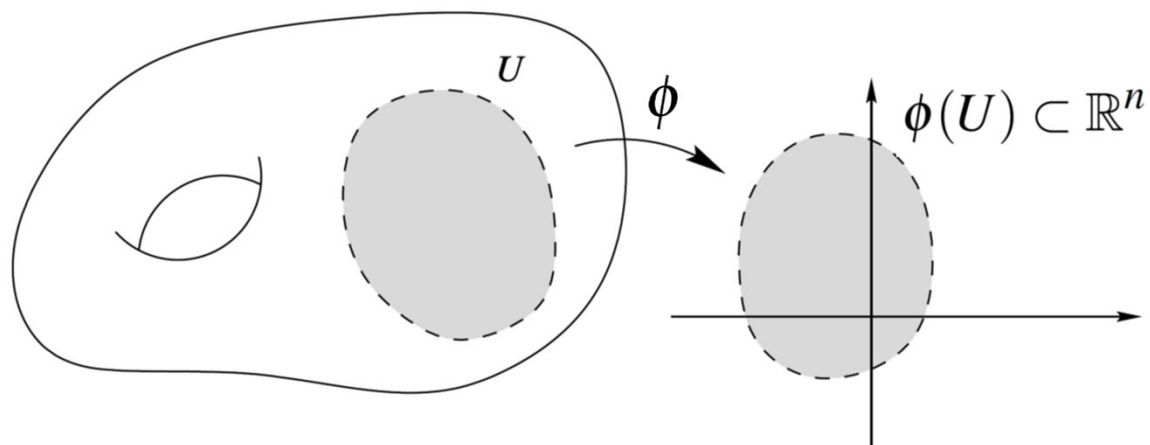


Coordinate chart

$$\begin{aligned}\phi : U \subset M &\rightarrow \mathbb{R}^n, \\ x &\mapsto (x^1, x^2, \dots, x^n).\end{aligned}$$

Coordinate functions

$$\begin{aligned}x^i : U \subset M &\rightarrow \mathbb{R}, \\ x &\mapsto x^i(x).\end{aligned}$$



Interlude: Coordinate Charts

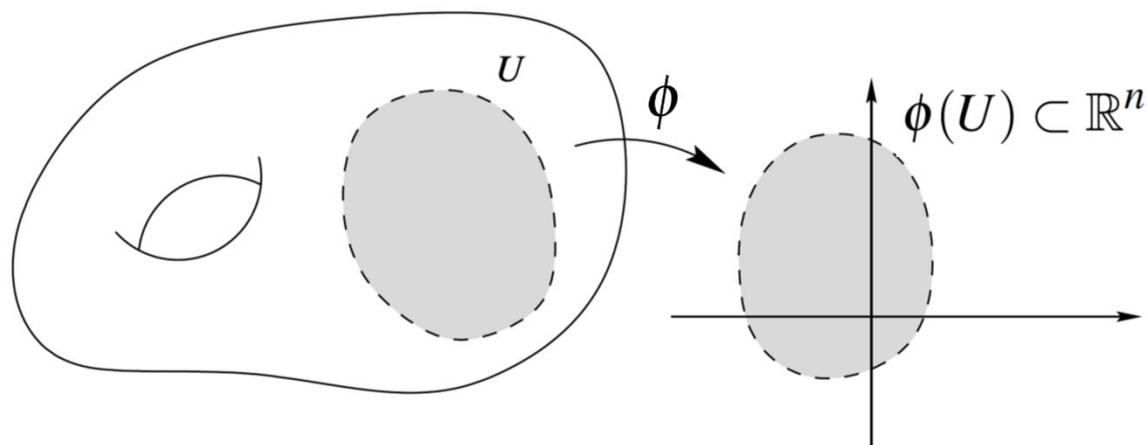


Coordinate charts

$$\begin{aligned}\phi_\alpha: U_\alpha \subset M &\rightarrow \mathbb{R}^n, \\ x &\mapsto (x^1, x^2, \dots, x^n).\end{aligned}$$

Atlas

$$\{(U_\alpha, \phi_\alpha)\}_{\alpha \in I}$$



Interlude: Coordinate Charts



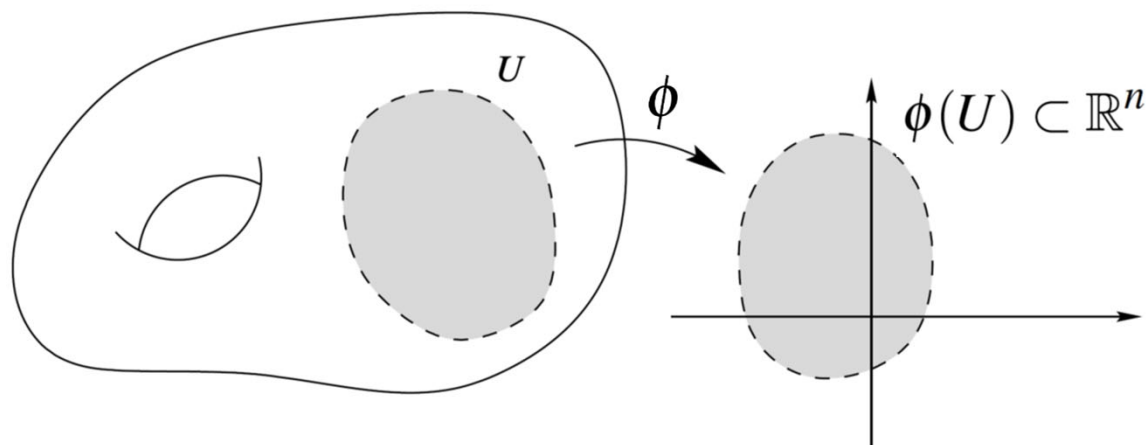
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$$\begin{aligned}\phi_\alpha: U_\alpha \subset M &\rightarrow \mathbb{R}^n, \\ x &\mapsto (x^1(x), x^2(x), \dots, x^n(x)).\end{aligned}$$

Atlas

$$\{(U_\alpha, \phi_\alpha)\}_{\alpha \in I}$$





Vector Fields vs. Vectors in Components

Because Euclidean space is most common, often slightly sloppy notation

$$\mathbf{v}: U \subset \mathbb{R}^2 \rightarrow \mathbb{R}^2,$$
$$(x, y) \mapsto \begin{bmatrix} u \\ v \end{bmatrix}.$$

Vector Fields vs. Vectors in Components



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$$\mathbf{v}: U \subset \mathbb{R}^3 \rightarrow \mathbb{R}^3,$$
$$(x, y, z) \mapsto \begin{bmatrix} u \\ v \\ w \end{bmatrix}.$$

$$\mathbf{v}: U \subset \mathbb{R}^2 \rightarrow \mathbb{R}^2,$$
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Vector Fields vs. Vectors in Components



$$\mathbf{v}: U \subset \mathbb{R}^n \rightarrow \mathbb{R}^n,$$

$$(x^1, x^2, \dots, x^n) \mapsto \begin{bmatrix} v^1 \\ v^2 \\ \vdots \\ v^n \end{bmatrix}.$$

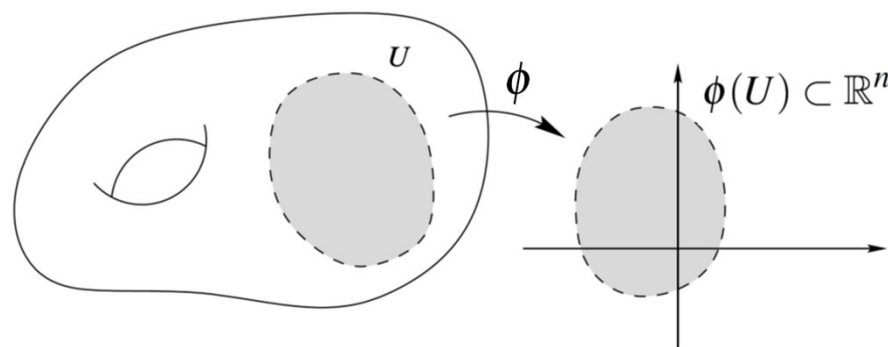
$$\mathbf{v}: U \subset \mathbb{R}^n \rightarrow \mathbb{R}^n,$$

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Vector Fields vs. Vectors in Components



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$$\mathbf{v}|_U: \phi(U) \subset \mathbb{R}^n \rightarrow \mathbb{R}^n,$$
$$(x^1, x^2, \dots, x^n) \mapsto \begin{bmatrix} v^1 \\ v^2 \\ \vdots \\ v^n \end{bmatrix}.$$



Vector Fields vs. Vectors in Components

Need basis vector fields

$$\begin{aligned} \mathbf{e}_i: U \subset M &\rightarrow TM, \\ x &\mapsto \mathbf{e}_i(x) \end{aligned} \quad \{\mathbf{e}_i(x)\}_{i=1}^n \quad \text{basis for } T_x M$$

Vector Fields vs. Vectors in Components



Need basis vector fields

$$\begin{aligned} \mathbf{e}_i: U \subset M &\rightarrow TM, \\ x &\mapsto \mathbf{e}_i(x) \end{aligned} \quad \{\mathbf{e}_i(x)\}_{i=1}^n \text{ basis for } T_x M$$

$$\begin{aligned} \mathbf{v}: U \subset M &\rightarrow TM, \\ x &\mapsto v^1 \mathbf{e}_1 + v^2 \mathbf{e}_2 + \dots + v^n \mathbf{e}_n. \end{aligned}$$

$$\begin{aligned} \mathbf{v}: U \subset M &\rightarrow TM, \\ x &\mapsto v^1(x) \mathbf{e}_1(x) + v^2(x) \mathbf{e}_2(x) + \dots + v^n(x) \mathbf{e}_n(x). \end{aligned}$$

Vector Fields vs. Vectors in Components



Need basis vector fields

$$\mathbf{e}_i: U \subset M \rightarrow TM, \quad x \mapsto \mathbf{e}_i(x) \quad \{\mathbf{e}_i(x)\}_{i=1}^n \text{ basis for } T_x M$$

Coordinate basis:

$$\mathbf{e}_i := \frac{\partial}{\partial x^i}$$

$$\mathbf{v}: U \subset M \rightarrow TM, \\ x \mapsto v^1 \mathbf{e}_1 + v^2 \mathbf{e}_2 + \dots + v^n \mathbf{e}_n.$$

$$\mathbf{v}: U \subset M \rightarrow TM, \\ x \mapsto v^1(x) \mathbf{e}_1(x) + v^2(x) \mathbf{e}_2(x) + \dots + v^n(x) \mathbf{e}_n(x).$$

Examples of Coordinate Curves and Bases



Coordinate functions, coordinate curves, bases

- Coordinate functions are real-valued (“scalar”) functions on the domain
- On each coordinate curve, *one* coordinate changes, *all others stay constant*
- Basis: n linearly independent vectors at each point of domain

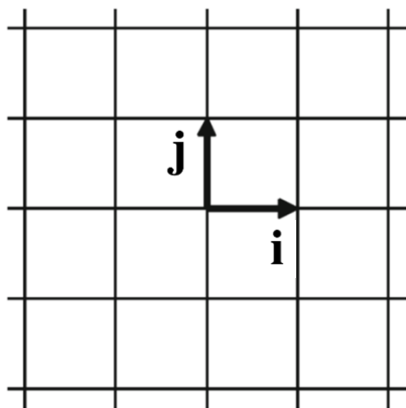
Cartesian coordinates

$$x^1 = x$$

$$x^2 = y$$

$$\mathbf{e}_1 = \frac{\partial}{\partial x} = \mathbf{i}$$

$$\mathbf{e}_2 = \frac{\partial}{\partial y} = \mathbf{j}$$



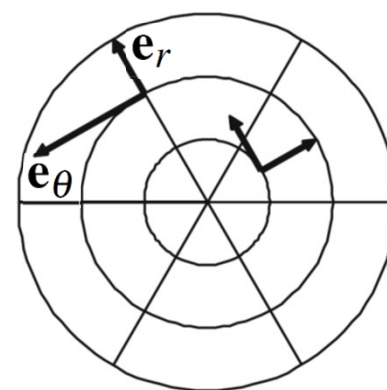
polar coordinates

$$x^1 = r$$

$$x^2 = \theta$$

$$\mathbf{e}_1 = \frac{\partial}{\partial r} = \mathbf{e}_r$$

$$\mathbf{e}_2 = \frac{\partial}{\partial \theta} = \mathbf{e}_\theta$$



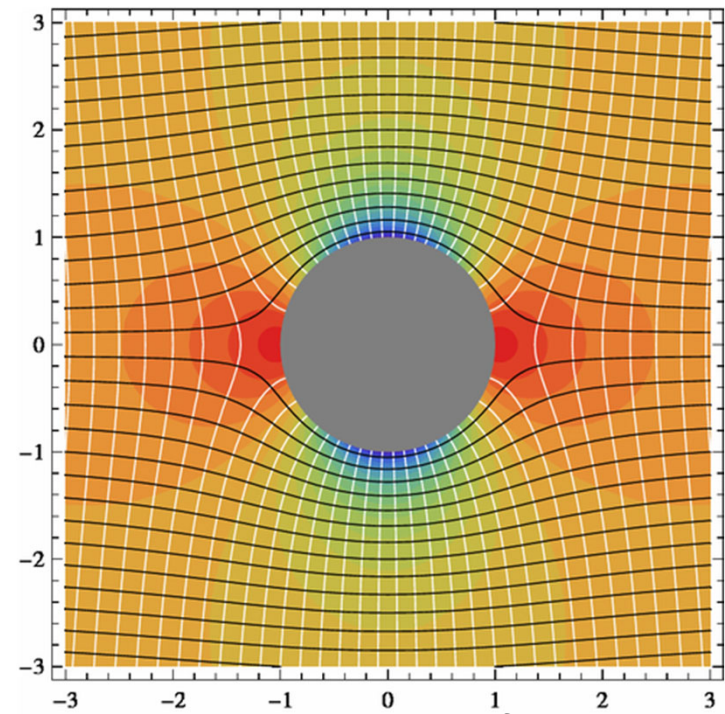
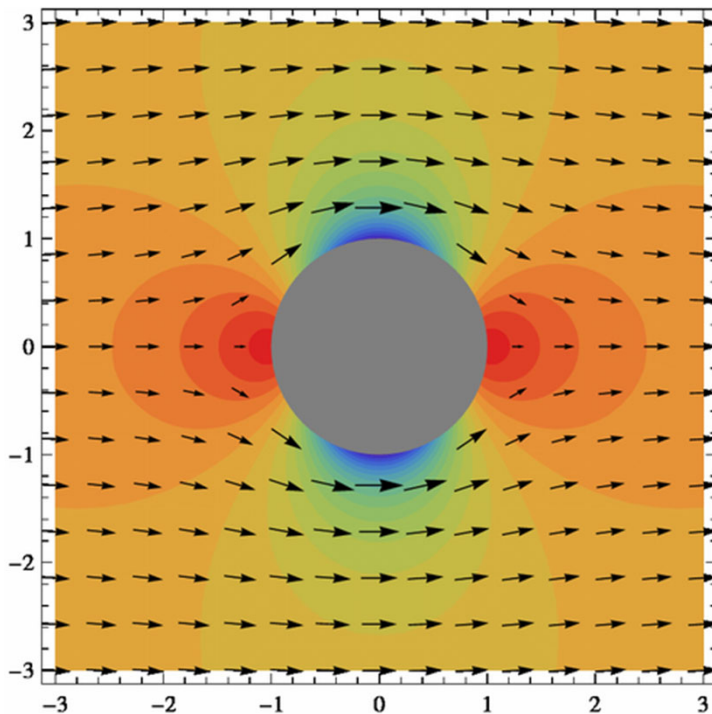
Flow Field Example (1)



Potential flow around a circular cylinder

https://en.wikipedia.org/wiki/Potential_flow_around_a_circular_cylinder

Inviscid, incompressible flow that is irrotational (curl-free) and can be modeled as the gradient of a scalar function called the (scalar) velocity potential



images from wikipedia

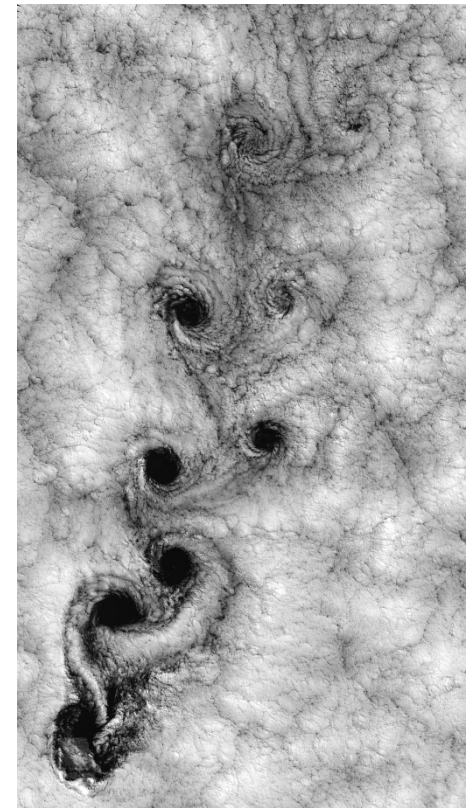
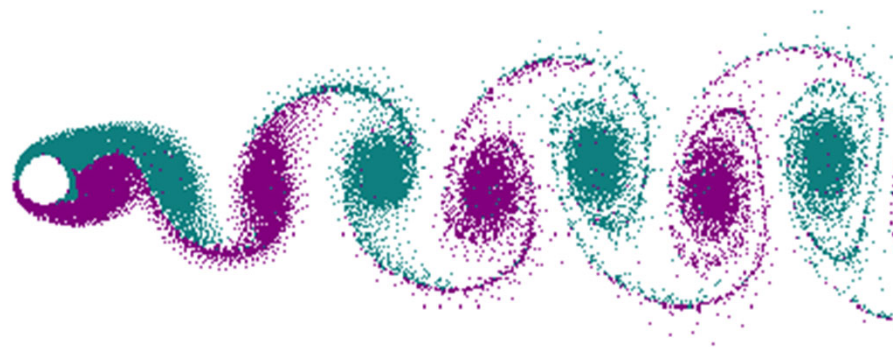
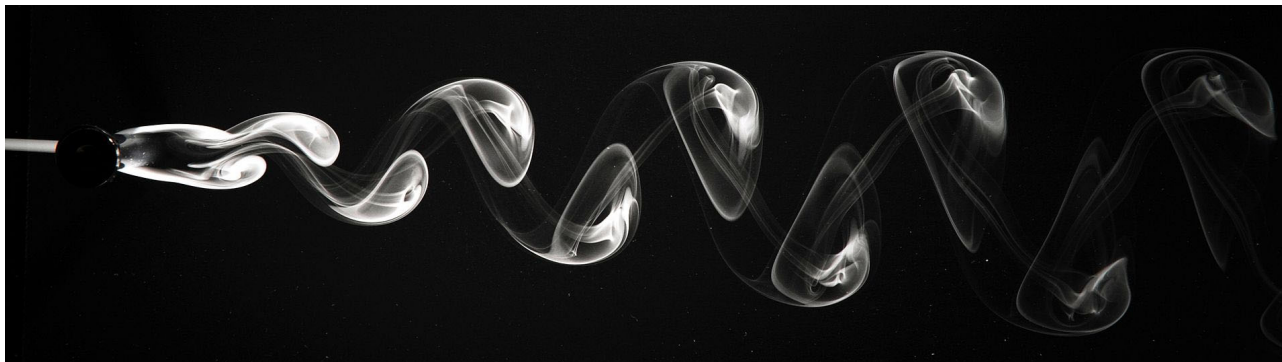
Flow Field Example (2)



Depending on Reynolds number, turbulence will develop

Example: von Kármán vortex street: vortex shedding

https://en.wikipedia.org/wiki/Karman_vortex_street



images from wikipedia

Steady vs. Unsteady Flow



- Steady flow: time-independent

- Flow itself is static over time: $\mathbf{v}(\mathbf{x})$

$$\mathbf{v}: \mathbb{R}^n \rightarrow \mathbb{R}^n, \\ x \mapsto \mathbf{v}(x).$$

- Example: laminar flows

- Unsteady flow: time-dependent

- Flow itself changes over time: $\mathbf{v}(\mathbf{x}, t)$

$$\mathbf{v}: \mathbb{R}^n \times \mathbb{R} \rightarrow \mathbb{R}^n, \\ x \mapsto \mathbf{v}(x, t).$$

- Example: turbulent flows

(here just for Euclidean domain; analogous on general manifolds)

Thank you.

Thanks for material

- Helwig Hauser
- Eduard Gröller
- Daniel Weiskopf
- Torsten Möller
- Ronny Peikert
- Philipp Muigg
- Christof Rezk-Salama