

### CS 247 – Scientific Visualization Lecture 16: Volume Rendering, Pt. 3

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### Reading Assignment #9 (until Mar 28)



#### Read (required):

- Real-Time Volume Graphics, Chapter 4.5 4.8
- Paper:

Jens Krüger and Rüdiger Westermann,

Acceleration Techniques for GPU-based Volume Rendering,
IEEE Visualization 2003,

http://dl.acm.org/citation.cfm?id=1081482

#### Quiz #2: Mar 28



#### Organization

- First 30 min of lecture
- No material (book, notes, ...) allowed

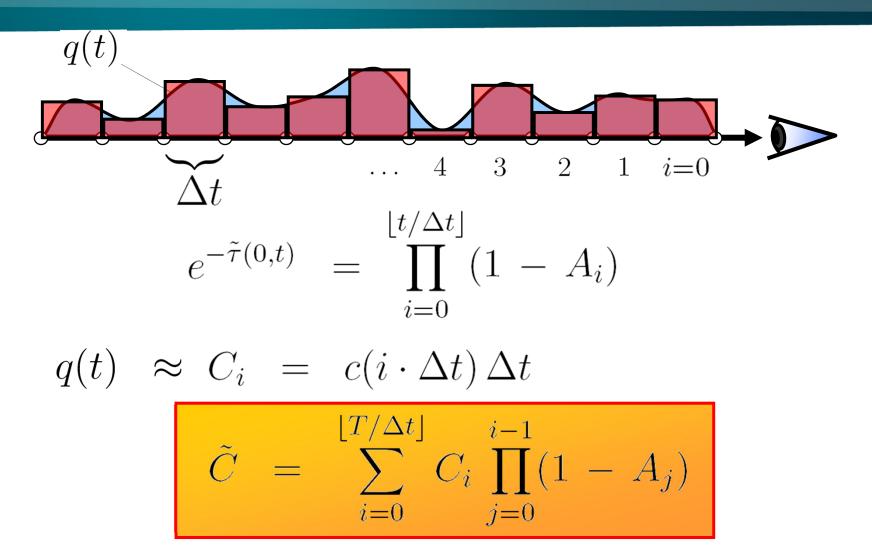
#### Content of questions

- Lectures (both actual lectures and slides)
- Reading assignments (except optional ones)
- Programming assignments (algorithms, methods)
- Solve short practical examples

# **Volume Visualization**

### Volume Rendering Integral: Numerical Solution

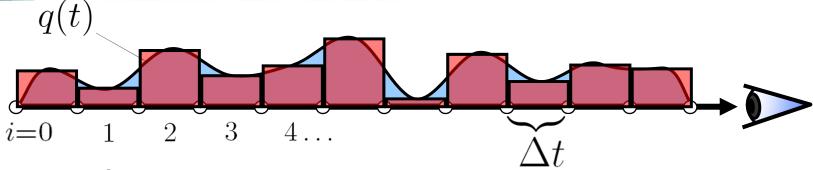




can be computed recursively/iteratively!

### Volume Rendering Integral: Numerical Solution





Back-to-front compositing

$$C'_i = C_i + (1 - A_i)C'_{i-1}$$

Iterate from *i*=0 (back) to *i*=max (front): *i* increases

Front-to-back compositing

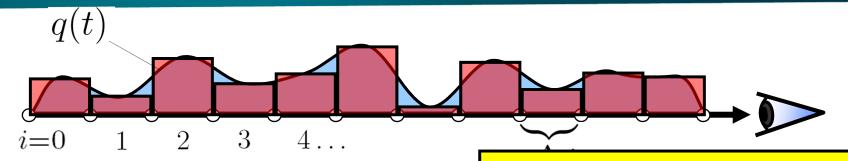
$$C'_{i} = C'_{i+1} + (1 - A'_{i+1})C_{i}$$

$$A'_{i} = A'_{i+1} + (1 - A'_{i+1})A_{i}$$

Iterate from *i*=max (front) to *i*=0 (back) : *i* decreases

### Volume Rendering Integral: Numerical Solution





Back-to-front compositing

$$C_i' = C_i + (1$$

Iterate from *i*=0 (back

Front-to-back compositing

$$A_i' \approx 1$$

$$C'_{i} = C'_{i+1} + (1 - A'_{i+1})C_{i}$$
 $A'_{i} = A'_{i+1} + (1 - A'_{i+1})A_{i}$ 

Iterate from *i*=max (front) to *i*=0 (back) : *i* decreases

#### Volume Rendering Integral Summary



Volume rendering integral for *Emission Absorption* model



$$I(s) = I(s_0) e^{-\tau(s_0,s)} + \int_{s_0}^{s} q(\tilde{s}) e^{-\tau(\tilde{s},s)} d\tilde{s}$$

Numerical solutions:

#### Back-to-front compositing

$$C'_i = C_i + (1 - A_i)C'_{i-1}$$

#### here, all colors are associated colors!

#### Front-to-back compositing

$$C'_{i} = C_{i} + (1 - A_{i})C'_{i-1}$$
  $C'_{i} = C'_{i+1} + (1 - A'_{i+1})C_{i}$   
 $A'_{i} = A'_{i+1} + (1 - A'_{i+1})A_{i}$ 

# **VolVis: Implementation**

### **Implementation**



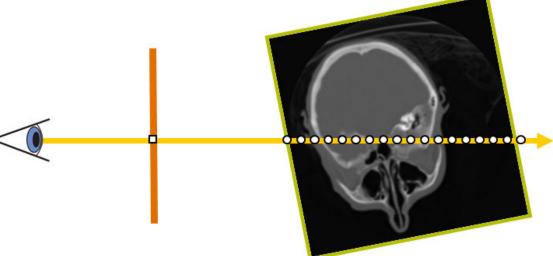
Ray setup

Loop over ray

Resample scalar value

Classification

Shading



### **Implementation**



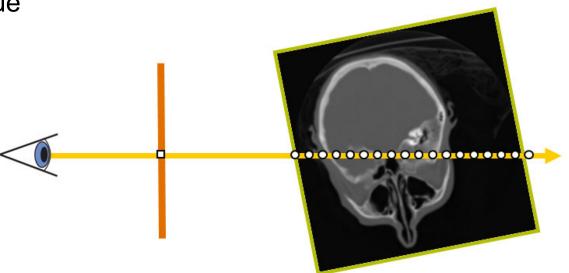
#### Ray setup

Loop over ray

Resample scalar value

Classification

Shading



#### Ray Setup

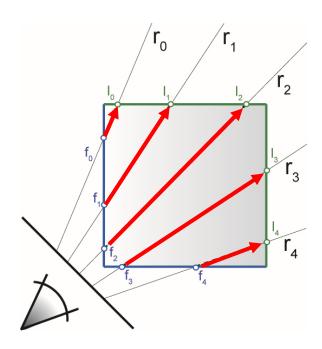


#### Two main approaches:

- Procedural ray/box intersection [Röttger et al., 2003], [Green, 2004]
- Rasterize bounding box [Krüger and Westermann, 2003]

#### Some possibilities

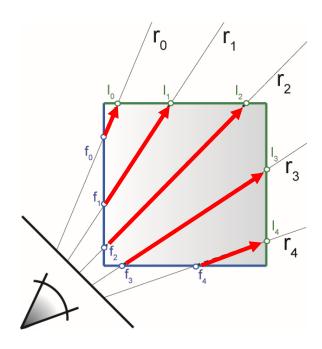
- Ray start position and exit check
- Ray start position and exit position
- Ray start position and direction vector



### Procedural Ray Setup/Termination



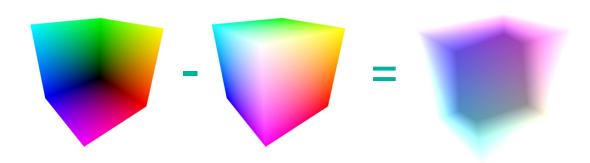
- Everything handled in the fragment shader / CUDA kernel
- Procedural ray / bounding box intersection
- Ray is given by camera position and volume entry position
- Exit criterion needed
- Pro: simple and self-contained
- Con: full computational load per-pixel/fragment

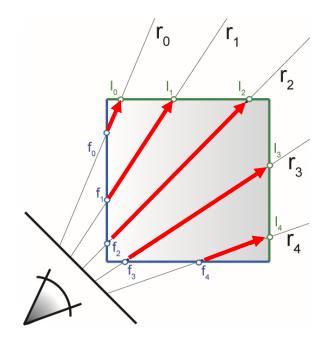


### Rasterization-Based Ray Setup



- Fragment == ray
- Need ray start pos, direction vector
- Rasterize bounding box



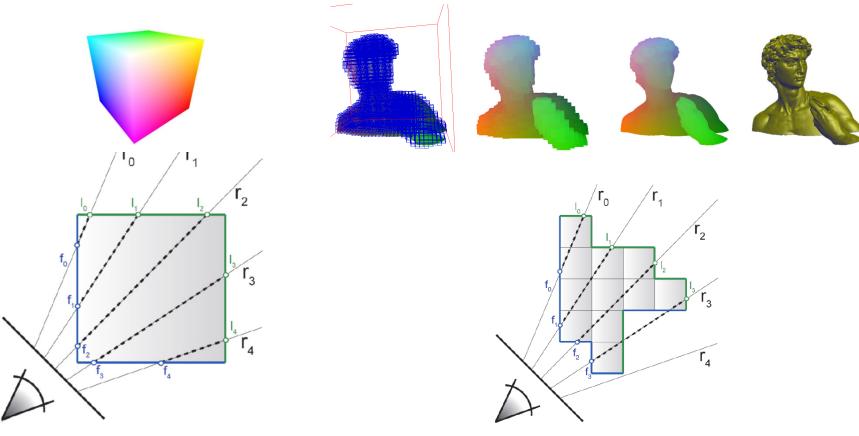


Identical for orthogonal and perspective projection!

### Object-Order Empty Space Skipping



#### Modify initial rasterization step



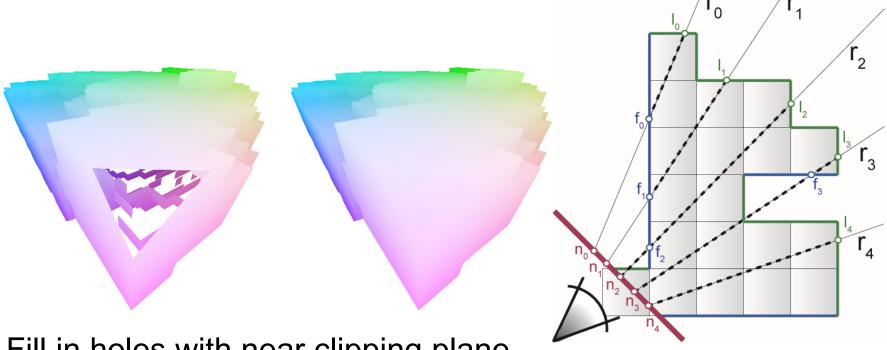
rasterize bounding box

rasterize "tight" bounding geometry

### Moving Into The Volume



Near clipping plane clips into front faces



Fill in holes with near clipping plane

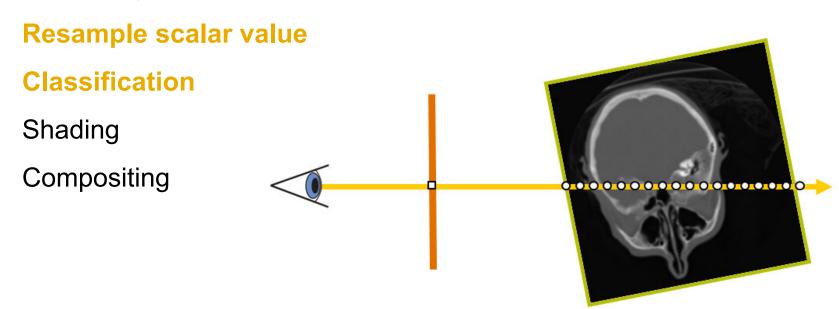
Can use depth buffer [Scharsach et al., 2006]

### **Implementation**



#### Ray setup

Loop over ray

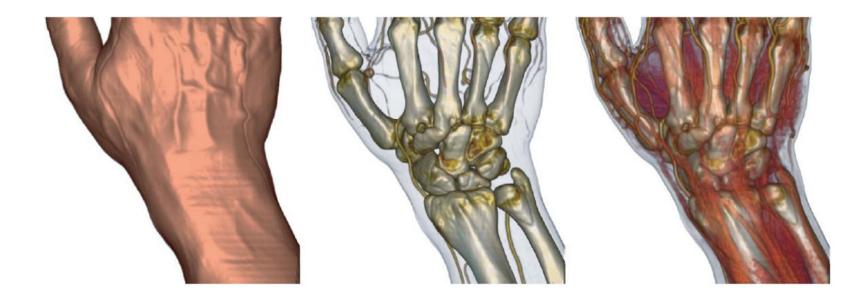


### Classification – Transfer Functions



During Classification the user defines the "look" of the data.

- Which parts are transparent?
- Which parts have what color?



#### Classification – Transfer Functions



During Classification the user defines the "look" of the data.

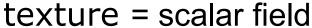
- Which parts are transparent?
- Which parts have what color?

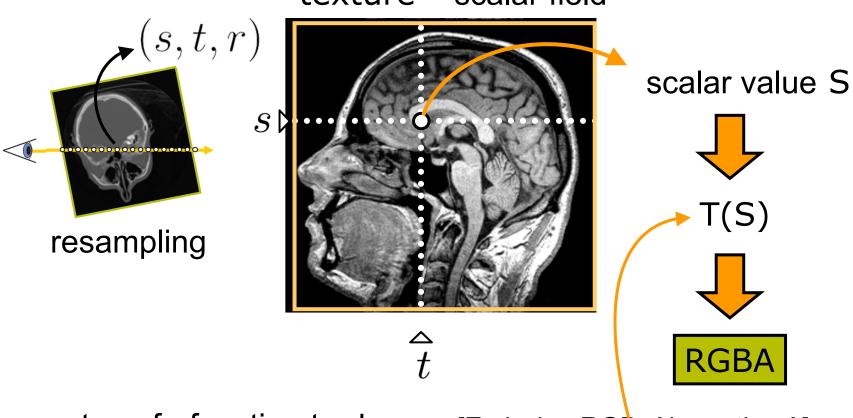
The user defines a *transfer function*.



#### 1D Transfer Functions



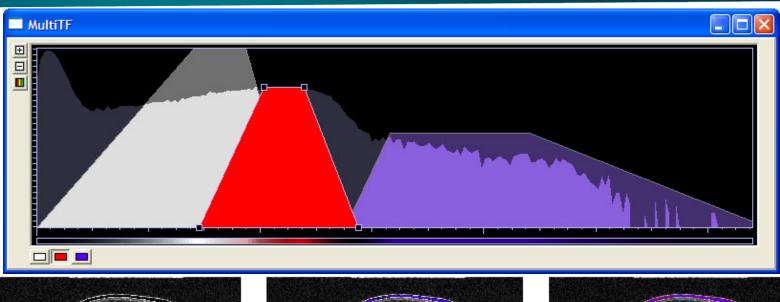


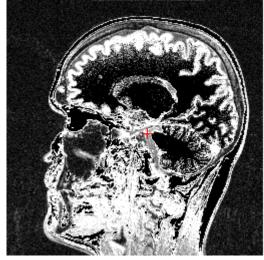


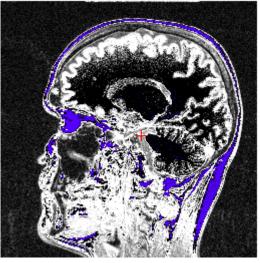
transferfunction texture = [Emission RGB, Absorption A]

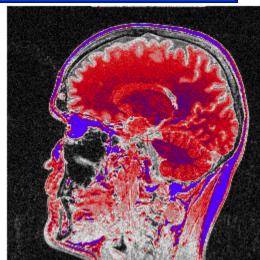
### 1D Transfer Functions













### Applying Transfer Function: Cg Example

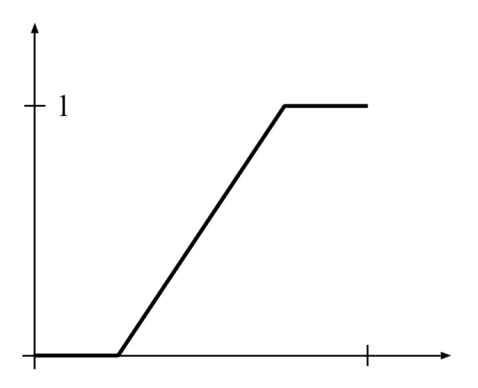
```
Cg fragment program for post-classification
// using 3D textures
float4 main (float3 texUV : TEXCOORD0,
            uniform sampler3D volume texture,
            uniform sampler1D transfer function) :
  COLOR
   float index = tex3D(volume texture, texUV);
   float4 result = tex1D(transfer function, index);
   return result;
```

### Windowing Transfer Function



Map input scalar range to output intensity range

- Select scalar range of interest
- Adjust contrast

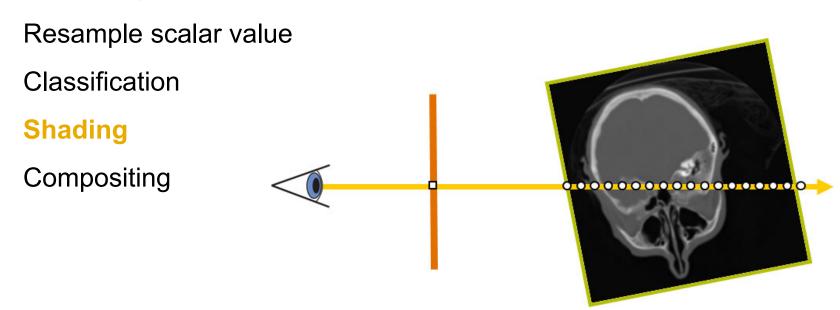


### **Implementation**



#### Ray setup

#### Loop over ray

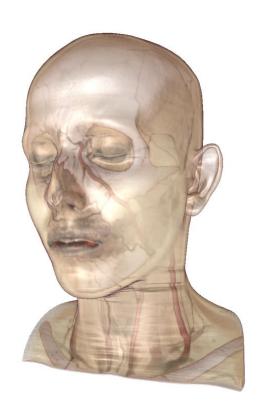


### Volume Shading



#### Local illumination vs. global illumination

- Gradient-based or gradient-less
- Shadows, (multiple) scattering, ...





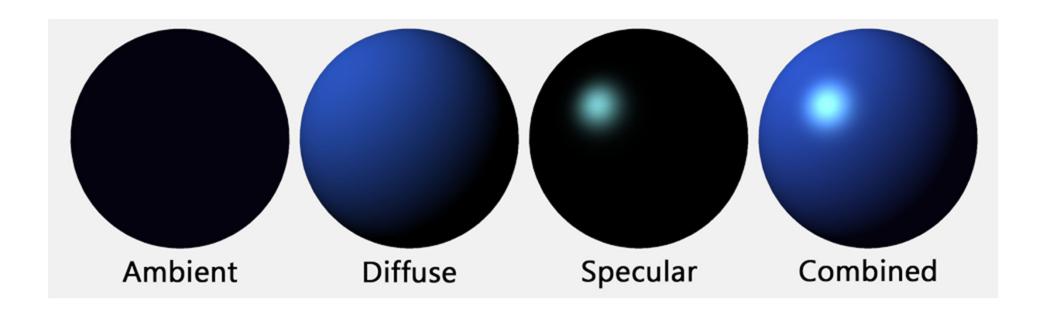




### Local Illumination Model: Phong Lighting Model



$$\mathbf{I}_{\mathrm{Phong}} = \mathbf{I}_{\mathrm{ambient}} + \mathbf{I}_{\mathrm{diffuse}} + \mathbf{I}_{\mathrm{specular}}$$



### On-the-fly Gradient Estimation



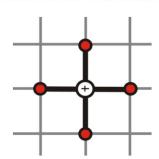
$$\nabla f(x, y, z) \approx \frac{1}{2h} \begin{pmatrix} f(x+h, y, z) - f(x-h, y, z) \\ f(x, y+h, z) - f(x, y-h, z) \\ f(x, y, z+h) - f(x, y, z-h) \end{pmatrix}$$

```
float3 sample1, sample2;
// six texture samples for the gradient
sample1.x = tex3D(texture,uvw-half3(DELTA,0.0,0.0)).x;
sample2.x = tex3D(texture,uvw+half3(DELTA,0.0,0.0)).x;
sample1.y = tex3D(texture,uvw-half3(0.0,DELTA,0.0)).x;
sample2.y = tex3D(texture,uvw+half3(0.0,DELTA,0.0)).x;
sample1.z = tex3D(texture,uvw-half3(0.0,0.0,DELTA)).x;
sample2.z = tex3D(texture,uvw+half3(0.0,0.0,DELTA)).x;
// central difference and normalization
float3 N = normalize(sample2-sample1);
```

### On-The-Fly Gradients

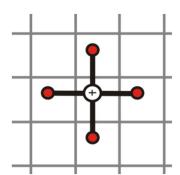


Reduce texture memory consumption!



Central differences before and after linear interpolation of values at grid points yield the same results

Caveat: texture filter precision



Filter kernel methods are expensive, but:

Tri-cubic B-spline kernels can be used in real-time (e.g., GPU Gems 2 Chapter "Fast Third-Order Filtering")

#### **Implementation**



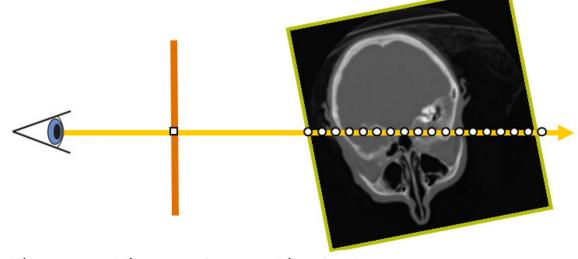
#### Ray setup

#### Loop over ray

Resample scalar value

Classification

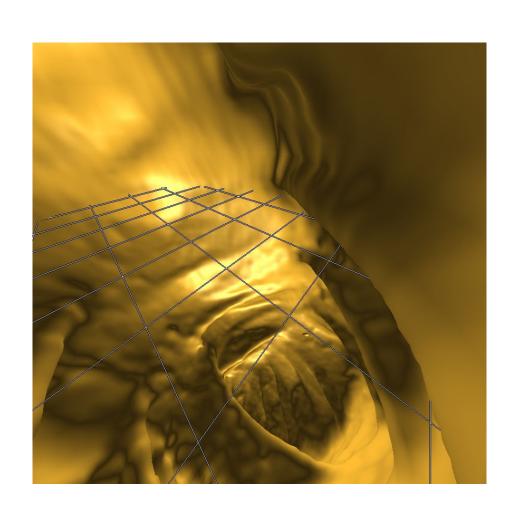
**Shading** 



$$C'_{i} = C'_{i+1} + (1 - A'_{i+1})C_{i}$$
  

$$A'_{i} = A'_{i+1} + (1 - A'_{i+1})A_{i}$$













#### Fragment Shader

- Rasterize front faces of volume bounding box
- Texcoords are volume position in [0,1]
- Subtract camera position
- Repeatedly check for exit of bounding box

```
// Cg fragment shader code for single-pass ray casting
float4 main(VS_OUTPUT IN, float4 TexCoord0 : TEXCOORDO,
            uniform sampler3D SamplerDataVolume,
            uniform sampler1D SamplerTransferFunction,
            uniform float3 camera,
            uniform float stepsize,
            uniform float3 volExtentMin.
            uniform float3 volExtentMax
            ) : COLOR
   float4 value;
    float scalar:
    // Initialize accumulated color and opacity
    float4 dst = float4(0,0,0,0);
    // Determine volume entry position
    float3 position = TexCoord0.xyz;
    // Compute ray direction
    float3 direction = TexCoord0.xyz - camera;
    direction = normalize(direction);
    // Loop for ray traversal
    for (int i = 0; i < 200; i++) // Some large number
        // Data access to scalar value in 3D volume texture
        value = tex3D(SamplerDataVolume, position);
        scalar = value.a;
        // Apply transfer function
        float4 src = tex1D(SamplerTransferFunction, scalar);
        // Front-to-back compositing
        dst = (1.0-dst.a) * src + dst;
        // Advance ray position along ray direction
        position = position + direction * stepsize;
        // Ray termination: Test if outside volume ...
        float3 temp1 = sign(position - volExtentMin);
        float3 temp2 = sign(volExtentMax - position);
        float inside = dot(temp1, temp2);
        // ... and exit loop
        if (inside < 3.0)
            break;
    return dst;
```

#### **CUDA** Kernel

- Image-based ray setup
  - Ray start image
  - Direction image
- Ray-cast loop
  - Sample volume
  - Accumulate color and opacity
- Terminate
- Store output

```
global
void RayCastCUDAKernel( float *d_output_buffer, float *d_startpos_buffer, float *d_direction_buffer)
   // output pixel coordinates
   dword screencoord x = umul24( blockIdx.x, blockDim.x ) + threadIdx.x;
   dword screencoord y = umul24( blockIdx.y, blockDim.y ) + threadIdx.y;
   // target pixel (RGBA-tuple) index
   dword screencoord indx = ( umu124( screencoord y, cu screensize.x ) + screencoord x ) * 4;
   // get direction vector and ray start
   float4 dir vec = d direction buffer[ screencoord indx ];
   float4 startpos = d startpos buffer[ screencoord indx ];
   // ray-casting loop
   float4 color
                    = make float4( 0.0f );
   float poscount = 0.0f;
   for ( int i = 0; i < 8192; i++ ) {
       // next sample position in volume space
       float3 samplepos = dir vec * poscount + startpos;
       poscount += cu_sampling_distance;
       // fetch density
       float tex_density = tex3D( cu_volume_texture, samplepos.x, samplepos.y, samplepos.z );
       // apply transfer function
       float4 col classified = tex1D( cu transfer function texture, tex density );
       // compute (1-previous.a) *tf.a
       float prev_alpha = -color.w * col_classified.w + col_classified.w;
       // composite color and alpha
       color.xyz = prev_alpha * col_classified.xyz + color.xyz;
       color.w += prev alpha;
       // break if ray terminates (behind exit position or alpha threshold reached)
       if ( ( poscount > dir_vec.w ) || ( color.w > 0.98f ) ) {
           break:
   // store output color and opacity
   d_output_buffer[ screencoord_indx ] = __saturatef( color );
```

### Thank you.

#### Thanks for material

- Helwig Hauser
- Eduard Gröller
- Daniel Weiskopf
- Torsten Möller
- Ronny Peikert
- Philipp Muigg
- Christof Rezk-Salama